S.A. ENGINEERING COLLEGE

(An Autonomous Institution, Affiliated to Anna University, Chennai) Veeraraghavapuram, Thiruverkadu post, Chennai-600077



Curriculum and Syllabi

Bachelor of Engineering Mechanical Engineering

Regulation - 2020 Choice Based Credit System (CBCS)

The UG Syllabus of the Department of Mechanical Engineering, S.A. Engineering College (Autonomous), Chennai for 2020-2021 admission onwards, has been ratified by the Board of Studies of Mechanical Engineering which met on 29.02.2020 at S.A. Engineering College, Chennai.

Contents

1. Curriculum

2. Syllabus

S.A. ENGINEERING COLLEGE (An Autonomous Institution) B.E. MECHANICAL ENGINEERING CURRICULUM (Batch-2020) SEMESTER I

| S.N O | SUB CODE | COURSE TITLE | CATEGORY | L | Τ | Р | С |
|-------|----------|-------------------------------|----------|----|---|----|----|
| THEO | RY | | | | | | |
| 1. | HS1101 | Technical English | HS | 3 | 0 | 0 | 3 |
| 2. | MA1101 | Calculus And Its Applications | BS | 3 | 1 | 0 | 4 |
| 3. | PH1101 | Applied Physics | BS | 3 | 0 | 0 | 3 |
| 4. | CY1101 | Engineering Chemistry | BS | 3 | 0 | 0 | 3 |
| 5. | CS1101 | Problem Solving and | ES | 3 | 0 | 0 | 3 |
| | | Python Programming | | | | | |
| 6. | ME1101 | Engineering Graphics | ES | 2 | 0 | 2 | 3 |
| PRACT | TICALS | | · | | | | |
| 1. | | Physics and Chemistry | ES | 0 | 0 | 4 | 2 |
| | BS1101 | Laboratory | | | | | |
| 2. | CS1102 | Problem Solving and Python | BS | 0 | 0 | 4 | 2 |
| | | Programming Laboratory | | | | | |
| 1. | CI1101 | Indian Constitution | MC | 2 | 0 | 0 | 0 |
| | | | | | | | |
| | • | | TOTAL | 19 | 1 | 10 | 23 |

SEMESTER II

| S.NO | SUB CODE | COURSE TITLE | CATEGORY | L | T | Р | C |
|-------|----------|----------------------------------|----------|---|---|---|---|
| THEO | RY | | | | | | |
| 1. | HS1201 | English for Communication | HS | 3 | 0 | 0 | 3 |
| 2. | MA1201 | Complex Variables and Transforms | BS | 3 | 1 | 0 | 4 |
| 3. | PH1201 | Materials Science | BS | 3 | 0 | 0 | 3 |
| 4. | EE1201 | Basics Electrical & Electronics | ES | 3 | 0 | 0 | 3 |
| | | Engineering | | | | | |
| 5. | CE1201 | Engineering Mechanics | ES | 3 | 1 | 0 | 3 |
| PRAC' | FICALS | | | | | | |
| 1. | GE1201 | Engineering Practices Laboratory | ES | 0 | 0 | 4 | 2 |
| 2. | EE1204 | Basic Electrical and Electronics | ES | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |

| 1. | CY1201 | Environmental Science and | MC | 2 | 0 | 0 | 0 |
|----|--------|---------------------------|-------|----|---|---|----|
| | | Engineering | | | | | |
| | | | TOTAL | 17 | 2 | 8 | 20 |

SEMESTER III

| S.NO | SUB | COURSE TITLE | CATEGORY | L | Τ | Р | С |
|------|--------|--------------------------------|----------|----|---|---|----|
| | CODE | | | | | | |
| THEO | RY | - | · | | | | |
| 1. | MA1302 | Transforms and Partial | BS | 4 | 0 | 0 | 4 |
| | | Differential Equations | | | | | |
| 2. | ME1301 | Engineering Thermodynamics | PC | 3 | 0 | 0 | 3 |
| 3. | ME1302 | Fluid Mechanics and Machinery | ES | 3 | 0 | 0 | 3 |
| 4. | EE1308 | Electrical Drives and Controls | ES | 3 | 0 | 0 | 3 |
| 5. | ME1303 | Production Technology | PC | 3 | 0 | 0 | 3 |
| 6. | ME1304 | Engineering Metallurgy | PC | 3 | 0 | 0 | 3 |
| PRAC | TICALS | · | | | | | |
| 1. | EE1309 | Electrical Engineering | ES | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |
| 2. | ME1305 | Production Technology | PC | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |
| | • | • | TOTAL | 19 | 0 | 8 | 23 |

SEMESTER IV

| S.NO | SUB CODE | COURSE TITLE | CATEGORY | L | Т | P | С |
|-------------|----------|---------------------------------|----------|----|---|----|----|
| THEO | RY | | | | • | | |
| 1. | MA1404 | Statistics and Numerical | BS | 4 | 0 | 0 | 4 |
| | | Methods | | | | | |
| 2. | ME1401 | Manufacturing Processes | PC | 3 | 0 | 0 | 3 |
| 3. | ME1402 | Strength of Materials | ES | 3 | 0 | 0 | 3 |
| 4. | ME1403 | Thermal Engineering | PC | 3 | 0 | 0 | 3 |
| 5. | ME1404 | Mechanics of Machines-I | PC | 3 | 0 | 0 | 3 |
| 6. | HV1401 | Universal Human Values | HS | 2 | 1 | 0 | 3 |
| | | | | | | | |
| PRAC | TICALS | | | | | | |
| 1. | ME1405 | Strength of Materials and Fluid | ES | 0 | 0 | 4 | 2 |
| | | Mechanics Laboratory | | | | | |
| 2. | ME1406 | CAD & CNC Laboratory | PC | 0 | 0 | 4 | 2 |
| | | | TOTAL | 18 | 1 | 08 | 23 |

SEMESTER V

| S.NO | SUB | COURSE TITLE | CATEGORY | L | Т | Р | С |
|-------|--------|------------------------------------|----------|----|---|---|----|
| | CODE | | | | | | |
| THEO | RY | | · | • | • | • | |
| 1. | ME1501 | Mechanics of Machines – II | PC | 3 | 0 | 0 | 3 |
| 2. | ME1502 | Metrology & Computer Aided | PC | 3 | 0 | 0 | 3 |
| | | Inspection | | | | | |
| 3. | ME1503 | Design of Machine Elements | PC | 3 | 0 | 0 | 3 |
| 4. | ME1504 | Heat and Mass Transfer | PC | 3 | 0 | 0 | 3 |
| 5. | EC1514 | Microprocessor and Microcontroller | ES | 3 | 0 | 0 | 3 |
| | | for Mechanical Engineers | | | | | |
| 6. | | Open Elective-I | OE | 3 | 0 | 0 | 3 |
| PRAC' | TICALS | | · | | | | |
| 1. | ME1505 | Metrology & Inspection | PC | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |
| 2. | ME1506 | Kinematics and Dynamics | PC | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |
| | | | TOTAL | 18 | 0 | 8 | 22 |

SEMESTER VI

| RY ME1601 ME1602 | Design of Mechanical Transmission Systems Finite Element Analysis | PC PC | 3 | 0 | 0 | 3 |
|------------------------|---|---|--|---|--|---|
| ME1602 | Transmission Systems | | | 0 | 0 | 3 |
| | - | PC | | | | |
| | Finite Element Analysis | PC | - | | | |
| | | | 3 | 0 | 0 | 3 |
| ME1603 | Hydraulics & Pneumatics | PC | 3 | 0 | 0 | 3 |
| ME1604 | Computer Aided Design and | PC | 3 | 0 | 0 | 3 |
| | Manufacturing | | | | | |
| | Professional Elective-I | PE | 3 | 0 | 0 | 3 |
| FICALS | | | | | | |
| ME1613 | Thermal Engineering Laboratory | PC | 0 | 0 | 4 | 2 |
| ME1614 | Innovative Project | EEC | 0 | 0 | 4 | 2 |
| HS1601 | Professional | EEC | 0 | 0 | 2 | 1 |
| | Communication | | | | | |
| | Internship | EEC | 0 | 0 | 0 | 1 |
| | | TOTAL | 15 | 0 | 10 | 21 |
| | ME1604 TICALS ME1613 ME1614 | ME1604 Computer Aided Design and Manufacturing Professional Elective-I TICALS ME1613 Thermal Engineering Laboratory ME1614 Innovative Project HS1601 Professional Communication | ME1604Computer Aided Design and ManufacturingPCProfessional Elective-IPETCALSME1613Thermal Engineering LaboratoryPCME1614Innovative ProjectEECHS1601Professional CommunicationEECInternshipEEC | ME1604Computer Aided Design and ManufacturingPC3Professional Elective-IPE3TCALSPC0ME1613Thermal Engineering LaboratoryPC0ME1614Innovative ProjectEEC0HS1601Professional CommunicationEEC0InternshipEEC0 | ME1604Computer Aided Design and ManufacturingPC30Professional Elective-IPE30TCALSME1613Thermal Engineering LaboratoryPC00ME1614Innovative ProjectEEC00HS1601Professional CommunicationEEC00InternshipEEC00 | ME1604Computer Aided Design and ManufacturingPC300Professional Elective-IPE300TCALSME1613Thermal Engineering LaboratoryPC004ME1614Innovative ProjectEEC004HS1601Professional CommunicationEEC002InternshipEEC0000 |

SEMESTER VII

| S.NO | SUB CODE | COURSE TITLE | CATEGORY | L | Τ | P | С |
|------|----------|-----------------------------|----------|----|---|----|----|
| THE | DRY | | | | | | |
| 1. | ME1701 | Statistical Quality Control | PC | 3 | 0 | 0 | 3 |
| 2. | ME1702 | Power Plant Engineering | PC | 3 | 0 | 0 | 3 |
| 3. | ME1703 | Mechatronics | PC | 3 | 0 | 0 | 3 |
| 4. | | Professional Elective-II | PE | 3 | 0 | 0 | 3 |
| 5. | | Professional Elective-III | PE | 3 | 0 | 0 | 3 |
| PRAC | CTICALS | | | | | | |
| 1. | ME1720 | Computer Aided Analysis | PC | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |
| 2. | ME1721 | Mechatronics and Automation | PC | 0 | 0 | 4 | 2 |
| | | Laboratory | | | | | |
| 3. | ME1722 | Comprehension | EEC | 0 | 0 | 2 | 0 |
| | | | TOTAL | 15 | 0 | 10 | 19 |

SEMESTER VIII

| S.NO | SUB CODE | COURSE TITLE | CATEGORY | L | Т | Р | С | | | | |
|------|----------|---------------------------|----------|---|---|----|----|--|--|--|--|
| THEC | THEORY | | | | | | | | | | |
| 1. | ME1801 | Engineering Economics and | PC | 3 | 0 | 0 | 3 | | | | |
| | | Cost Analysis | | | | | | | | | |
| 2. | | Professional Elective-IV | PE | 3 | 0 | 0 | 3 | | | | |
| 3. | | Professional Elective-V | PE | 3 | 0 | 0 | 3 | | | | |
| PRAC | TICALS | | | | | | | | | | |
| 1. | ME1813 | Project Work | EEC | 0 | 0 | 12 | 6 | | | | |
| | | | TOTAL | 9 | 0 | 12 | 15 | | | | |

TOAL NUMBER OF CREDITS TO BE EARNED FOR AWARD OF THE DEGREE=166

OPEN ELECTIVES

| S.No | SUB CODE | COURSE TITLE | L | Т | Р | С |
|------|----------|-----------------------------------|---|---|---|---|
| 1. | OME501 | Internal Combustion Engines | 3 | 0 | 0 | 3 |
| 2. | OME502 | Robotics | 3 | 0 | 0 | 3 |
| 3. | OME701 | Introduction to Nano Technology | 3 | 0 | 0 | 3 |
| 4. | OME702 | Product Design and Development | 3 | 0 | 0 | 3 |
| 5. | OME703 | Energy Conversion Techniques | 3 | 0 | 0 | 3 |
| 6. | OME704 | Energy Efficient Buildings Design | 3 | 0 | 0 | 3 |

PROFESSIONAL ELECTIVES

| S.No | SUB CODE | COURSE TITLE | L | Т | Р | С |
|---------|----------|---|---|---|---|---|
| Electiv | ve-I | | | | | |
| 1. | ME1605 | Design of Jigs and Fixtures and Press Tools | 3 | 0 | 0 | 3 |
| 2. | ME1606 | Design for Manufacture and Assembly | 3 | 0 | 0 | 3 |
| 3. | ME1607 | Material Characterization | 3 | 0 | 0 | 3 |
| 4. | ME1608 | Renewable Energy sources | 3 | 0 | 0 | 3 |
| 5. | ME1609 | Gas Dynamics & Jet Propulsion | 3 | 0 | 0 | 3 |
| 6. | ME1610 | Operations Research | 3 | 0 | 0 | 3 |
| 7. | ME1611 | Total Quality Management | 3 | 0 | 0 | 3 |
| 8. | ME1612 | Entrepreneurship and Development of | 3 | 0 | 0 | 3 |
| | | Industries | | | | |
| Electiv | ve-II | | | | | |
| 1. | ME1704 | Vibration and Noise Engineering | 3 | 0 | 0 | 3 |
| 2. | ME1705 | Concurrent and Reverse Engineering | 3 | 0 | 0 | 3 |
| 3. | ME1706 | Micro Machining and Nano composites | 3 | 0 | 0 | 3 |
| 4. | ME1707 | Computational Fluid Dynamics | 3 | 0 | 0 | 3 |
| 5. | ME1708 | Refrigeration and Air Conditioning | 3 | 0 | 0 | 3 |
| 6. | ME1709 | Cryogenics Engineering | 3 | 0 | 0 | 3 |
| 7. | ME1710 | Product Life Cycle Management | 3 | 0 | 0 | 3 |
| Electiv | ve-III | | | | | |
| 1. | ME1711 | Tribology in Design | 3 | 0 | 0 | 3 |
| 2. | ME1712 | Advanced Finite Element Analysis | 3 | 0 | 0 | 3 |
| 3. | ME1713 | Optimization Techniques for Engineering | 3 | 0 | 0 | 3 |
| | | Systems | | | | |
| 4. | ME1714 | Additive Manufacturing | 3 | 0 | 0 | 3 |
| 5. | ME1715 | Heat Transfer in Nano fluids | 3 | 0 | 0 | 3 |
| 6. | ME1716 | Flexible Manufacturing Systems | 3 | 0 | 0 | 3 |
| 7. | ME1717 | Logistics and Supply Chain Management | 3 | 0 | 0 | 3 |
| 8. | ME1718 | Industrial Robotics | 3 | 0 | 0 | 3 |
| 9. | ME1719 | Industrial Management & Safety Engineering | 3 | 0 | 0 | 3 |
| Electiv | ve-IV | | | 1 | | |
| 1. | ME1802 | Advanced Welding and Joining | 3 | 0 | 0 | 3 |
| | | Technologies | | | | |
| 2. | ME1803 | Failure Analysis and Design | 3 | 0 | 0 | 3 |
| 3. | ME1804 | Nano Science & Materials | 3 | 0 | 0 | 3 |
| 4. | ME1805 | Design of Experiments | 3 | 0 | 0 | 3 |

| 5. | ME1806 | Design of Heat Transfer Equipments | 3 | 0 | 0 | 3 |
|---------|--------|--------------------------------------|---|---|---|---|
| Electiv | ve-V | | | | | |
| 1. | ME1807 | Green Manufacturing | 3 | 0 | 0 | 3 |
| 2. | ME1808 | Plant Layout and Material Handling | 3 | 0 | 0 | 3 |
| 3. | ME1809 | Inventory Management | 3 | 0 | 0 | 3 |
| 4. | ME1810 | Energy Auditing | 3 | 0 | 0 | 3 |
| 5. | ME1811 | Bio Materials | 3 | 0 | 0 | 3 |
| 6. | ME1812 | Process Planning and Cost Estimation | 3 | 0 | 0 | 3 |

HS1101

TECHNICAL ENGLISH

L-T-P-C

3-0-0-3

Prerequisites: Basic Language Proficiency.

Objective:

- Develop strategies and skills to enhance their ability to read and comprehend engineering and technology texts.
- Nurture their ability in technical writing like to prepare professional job applications and effective reports.
- Develop their speaking skills by participating in various speaking activities.
- Strengthen their listening skill to comprehend lectures and talks in their areas of specialization.
- Improve their ability to explicit their excellence in all modes of technical communication.

Course Outcomes:

The Students will be able to

- CO1: Read technical texts and write area- specific texts effortlessly.
- CO2: Listen and comprehend lectures and talks in their area of specialization successfully.
- CO3: Speak appropriately and effectively in varied formal and informal contexts.
- CO4: Write correctly, clearly and concisely with coherence and cohesion.
- **CO5**: Prepare job applications and resume in an inspiring manner.

UNIT - 1

9 Periods

Reading- Reading short texts **Listening-** Listening to different formal / informal conversations **Writing-**Instructions, Jumbled sentences **Speaking-** Self introduction **Language development-** Parts of speech, Prepositions **Vocabulary development-** Word formation- root words from foreign language and their use in English.

UNIT - 2

9 Periods

9 Periods

Reading-Skimming and Scanning to find specific information **Listening**- Listening to INK talks **Writing**-Job Application – cover letter, resume writing **Speaking**- Asking and Giving directions **Language development**- Conjunctions, Types of Nouns **Vocabulary development**- Prefixes and Suffixes.

UNIT – 3

Reading- Reading for predicting the content **Listening-** Listening to situational short talks **Writing-** Types of paragraphs- Descriptive/Analytical/ compare and contrast **Speaking-** Mini presentations, Expressing greeting and thanks **Language development-** Adjectives, Numerical Adjectives, Conditional Clauses **Vocabulary development-** Homophones, Homonyms.

UNIT – 4

Reading- Practice in speed reading **Listening-** Listening to short texts and fill the data **Writing-**Interpretation of Graphics / Information, Note making **Speaking-**Contributing for Group Discussion **Language development-** Active, Passive, Impersonal passive voice **Vocabulary development-**Definitions, Nominal Compounds.

9 Periods

UNIT – 5

9 Periods

Reading- Reading short stories **Listening-** Listening for note taking **Writing-** Report writing, E-mail Writing **Speaking-** Picture descriptions, Speaking in familiar situations **Language development-** Tenses **Vocabulary development-** British and American Vocabulary.

TOTAL PERIODS: 45

Text Books

- Richards, C. Jack. Interchange Students' Book-2 New Delhi: CUP, 2015.
- Board of editors. Fluency in English A Course book for Engineering and Technology.Orient Blackswan, Hyderabad: 2016.

Extensive Reading

• Khera, Shiv. You can Win, Macmillan, 2000.

Reference

- Bailey, Stephen. Academic Writing: A practical guide for students. New York:Rutledge,2011.
- Comfort, Jeremy, et al. Speaking Effectively : Developing Speaking Skills for Business English. Cambridge University Press, Cambridge: Reprint 2011
- Darlene Smith-Worthington, Sue Jefferson, Technical writing for Success, South-Western Cengage Learning, USA-2011
- Means, L. Thomas and Elaine Langlois, English & Communication For Colleges. Cengage Learning, USA: 2007
- Raman, Meenakshi and Sharma, Sangeetha- Technical Communication Principles and Practice.Oxford University Press: New Delhi, 2014
- Swan Michael, Practical English Usage. Oxford University Press, Eighth impression 2002.

Recommended Websites

bbc.co.uk/llearning english oxfordonlineenglish.com/ cambridgeenglish.org inktalks.com/talks/ manageyourwriting.com

MA1101 CALCULUS AND ITS APPLICATIONS LTPC

OBJECTIVES:

- To understand the concepts of limits, continuity, differentiation and use it to find maxima and minima of functions of one variable.
- To make the student acquire sound knowledge of techniques in solving ordinary differential equations of first and second order that model in various engineering problems.
- To familiarize the student with functions of several variables that is needed in many branches of engineering.
- To acquaint the student with mathematical tools needed in evaluating multiple integrals and their usage.

UNIT I- DIFFERENTIAL CALCULUS

Representation of functions - Limit of a function - Continuity - Derivatives - Differentiation rules -Maxima and Minima of functions of one variable.

UNIT II -ORDINARY DIFFERENTIAL EQUATIONS OF FIRST ORDER WITH APPLICATIONS: 9+3

Basic concepts- Separable differential equations - Exact differential equations - Integrating factors - Linear differential equations - Bernoulli's equation - Geometric Applications- Orthogonal trajectories - Physical Applications - Simple electronic circuits-Newton law of cooling-Heat flow-Rate of decay of radioactive materials-Chemical reaction and solutions.

UNIT III - DIFFERENTIAL EQUATIONS

Higher order linear differential equations with constant coefficients - Method of variation of parameters – Homogenous equation of Euler's and Legendre's type – System of simultaneous linear differential equations with constant coefficients - Method of undetermined coefficients.

UNIT IV- FUNCTIONS OF SEVERAL VARIABLES 9+3

Partial differentiation – Homogeneous functions and Euler's theorem – Total derivative – Change of variables - Jacobians - Partial differentiation of implicit functions - Taylor's series for functions of two variables - Maxima and minima of functions of two variables - Lagrange's method of undetermined multipliers.

UNIT V- MULTIPLE INTEGRALS

Double integrals - Change of order of integration - Double integrals in polar co-ordinates - Area enclosed by plane curves – Triple integrals – Volume of solids – Change of variables in double and triple integrals.

TOTAL PERIODS:60

9+3

3 1 0 4

9+3

9+3

COURSE OUTCOMES:

After completing this course, students should demonstrate competency in the following skills:

- Use both the limit definition and rules of differentiation to differentiate functions. apply differentiation to solve maxima and minima problems.
- The subject helps the students to develop the fundamentals and basic concepts in ODE
- Apply integration to compute multiple integrals, area, volume, integrals in polar coordinates, in addition to change of order and change of variables.

TEXTBOOKS:

- 1. Grewal, B.S., Higher Engineering Mathematics, 43rd Edition, Khanna Publishers, 2016.
- 2. Erwin Kreyszig, Advanced Engineering Mathematics, 10th Edition, John Wiley & Sons, Inc., 2016.

REFERENCE BOOKS:

- Bali,N.P.,Goyal,M.,Watkins,C.,Advanced Engineering Mathematics,Laxmi Publications Pvt. Limited, 2007.
- Boyce,W.E.,and DiPrima,R.C.,Elementary Differential Equationsand Boundary Value Problems, Wiley India, 2012.
- O'Neil. P. V., "Advanced Engineering Mathematics", 7th Edition, Cengage Learning India Pvt., Ltd, New Delhi, 2011.
- 4. T.Veerarajan, Engineering Mathematics, Mc Grawhill Publications, New Delhi 2017.

UNIT-1 PROPERTIES OF MATTER

Elasticity- plasticity - Different Types of Stress and Strain- concept of stress-strain diagram and its application - three types of modulus of elasticity- Poisson's Ratio - Bending of beams- Expression for bending moment -- young's modulus uniform and Non uniform bending : Theory and Experiment - I Shape girders - Torsional oscillation Theory and Experiment- Application of Elastic Materials.

UNIT-2 APPLIED OPTICS

Laser : characteristics of laser - Principle of spontaneous emission and stimulated emission - Laser action -Einstein A & B coefficients - Population inversion - Pumping – Basic requirement of laser – Types of laser : Nd-YAG and CO₂ – Applications : Welding, Drilling & Cutting – Medical field

Fiber optics: Introduction- Principle and propagation of light – Numerical aperture and acceptance angle - classification of optical fibers - Losses in optical fibers(Qualitative) - Fiber optics communication system (Block Diagram) - Advantages with fiber optic communication system.

UNIT-3 THERMAL PHYSICS

Modes of heat transfer- thermal conduction, convection and radiation – Specific heat capacity- thermal conductivity- Newton's law of cooling - Searle's and Lee's disc methods: theory and experiment conduction through compound media (series and parallel) - thermal expansion of solids, liquids and gases - Applications: heat exchangers, refrigerators and solar water heaters.

UNIT-4 WAVE AND PARTICLE PHYSICS

Inadequacy of Classical Mechanics - Development of quantum theory- Planck's Black body radiation and Distribution Laws(Qualitative) - Compton Effect (Derivation) - De Broglie wavelength properties of matter waves - Experimental Verification (G.P Thomson experiment) - Heisenberg's uncertainty principle - Schrodinger's wave equation - time dependent - time independent wave equations - physical significance of Wave function - applications: particle in a one dimensional potential box.

UNIT-5 CRYSTALOGRAPHY

Single crystalline, polycrystalline and amorphous materials Lattice - unit cell- Crystal systems-Bravais lattices- Lattice planes- Miller indices- Interplanar- d- Spacing in cubic Lattice- calculation of number of atoms per unit cell - atomic radius - packing factor for SC, BCC, FCC and HCP structures- Crystal Defects - types.

Total Periods : 45

APPLIED PHYSICS

OBJECTIVES:

PH1101

To enhance the fundamental knowledge in Physics and its applications relevant to various streams of Engineering and Technology.

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OUTCOMES:

At the end of this course,

- 1. The students will gain knowledge on the basics of properties of matter and its applications
- 2. Use the concepts of waves and optical devices and their applications in Laser and fiber optics
- 3. The students will understand the properties of thermal materials and its applications
- 4. The students will get knowledge on advanced physics concepts of quantum theory and its application in one dimensional box.
- 5. The students will understand the different types of crystals structures and different crystal growth techniques.

TEXT BOOKS :

1. Gupta S.L. and Sanjeev Gupta, Modern Engineering Physics, Dhanpat Rai Publishers, 2015.

2. R. K. Gaur and S.C. Gupta, Engineering Physics, Dhanpat Rai Publication (P) Ltd, New Delhi, 2014.

3. Bhattacharya, D.K. and Poonam, T. Engineering Physics, Oxford University Press, 2015.

REFERENCES:

- 1. C. Kittel ,Introduction to Solid State Physics 8th Edition , Wiley Eastern Ltd,2004.
- 2. Halliday, D., Resnick, R. and Walker, J. Principles of Physics. Wiley, 2015.
- 3. Tipler, P.A. and Mosca, G. Physics for Scientists and Engineers with Modern Physics, W.H.Freeman, 2007.
- 4. Einstein coefficient calculation, https://youtu.be/TvfiZHXUtXg (Video lecture)
- 5. Lattice structures, <u>https://youtu.be/Rm-i1c7zr6Q</u> (Video lecture)

CY1101 ENGINEERING CHEMISTRY

COURSE OBJECTIVES:

- To make the students conversant with boiler feed water requirements, related problems and water treatment techniques.
- To develop an understanding of the basic concepts of phase rule and its applications to single and two component systems and appreciate the purpose and significance of alloys.
- It enables the students to gain information about Principles and generation of energy in batteries, nuclear reactors, solar cells, wind mills and fuel cells
- It deals with the information about the types of fuels, calorific value calculations and manufacture of solid, liquid and gaseous fuels.
- To impart knowledge about the nanomaterials synthesis, properties and applications

UNIT I WATER TREATMENT AND TECHNOLOGY

Introduction – characteristics, Water quality parameters -hardness– types, Determination-EDTA method, Alkalinity ,boiler feed water requirements-boiler troubles – scale & sludge - Caustic Embrittlement , boiler explosion -softening of hard water - external treatment process - demineralization and zeolite, internal treatment - boiler compounds (phosphate, calgon, carbonate and colloidal conditioning methods) – desalination of brackish water –reverse osmosis.

UNIT II PHASE RULE AND ALLOYS

Phase rule: Introduction, definition of terms with examples, One Component System- water system, Sulphur, CO_2 system, Thermal Analysis and cooling curves, Reduced phase rule - Two Component Systems- classification – lead-silver system-problems. Alloys: Introduction- Definition- Properties of alloys- Significance of alloying, Functions and effect of alloying elements- Ferrous alloys- Nichrome and Stainless steel – heat treatment of steel.

UNIT III ENERGY SOURCES AND STORAGE DEVICES

Energy - Types - Non-renewable energy - Nuclear energy - renewable energy - solar energy conversion - solar cells. Introduction to Electrochemistry, Nernst Equation-Electrochemical cells - reversible and irreversible cells -Cell construction and representation - Batteries -types of batteries - characteristics - construction and working of primary battery (dry cell) - secondary battery (lithium-ion-battery) - fuel cells (H₂-O₂).

UNIT IV FUELS AND COMBUSTION

Fuel: Introduction- classification of fuels- calorific value- higher and lower calorific values- coal- analysis of coal (proximate and ultimate)- carbonization- manufacture of metallurgical coke (Otto Hoffmann method) – petroleum- manufacture of synthetic petrol (Bergius process)- knocking- octane number – diesel oil- cetane number – natural gas- compressed natural gas(CNG)- liquefied petroleum gases(LPG)- producer gas- water gas. Power alcohol and bio diesel. Combustion of fuels: introduction- theoretical calculation of calorific value- ignition temperature- explosive range – flue gas analysis (ORSAT Method).

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UNIT V NANOCHEMISTRY

Basics - distinction between nanoparticles and bulk materials; size-dependent properties., nano cluster, nano rod, nanotube(CNT)-Types of CNT and nanowire. Synthesis: precipitation, thermolysis, chemical vapour deposition, Properties, Characterisation and applications.

TOTAL PERIODS: 45

COURSE OUTCOMES:

- The knowledge gained on water treatment techniques will facilitate better understanding of engineering processes and applications for further learning.
- With the help of phase rule, they could understand the various phase diagrams and able to predict the low melting alloys.
- Students can get knowledge about various fuels and its applications based on its calorific value.
- It provides the students to understand about conventional and non-conventional energy sources and its applications
- Students gain an insight about the recent trends in nano materials.

TEXT BOOKS

Jain P.C. and Monica Jain, "Engineering Chemistry", Dhanpat Rai Publishing Company (P) Ltd., New Delhi, 2010

REFERENCES

- 1. Dara S.S, Umare S.S, "Engineering Chemistry", S. Chand & Company Ltd., New Delhi 2010
- 2. Sivasankar B., "Engineering Chemistry", Tata McGraw-Hill Publishing Company, Ltd., New Delhi, 2008.
- 3. Ozin G. A. and Arsenault A. C., "Nanochemistry: A Chemical Approach to Nanomaterials", RSC Publishing, 2005.

TOTAL PERIODS: 45

PROBLEM SOLVING AND PYTHON PROGRAMMING

L T P C 3 0 0 3

OBJECTIVES:

CS1101

- To know the basics of algorithmic problem solving
- To read and write simple Python programs.
- To develop Python programs with conditionals and loops.
- To define Python functions and call them.
- To use Python data structures -- lists, tuples, dictionaries.
- To do input/output with files in Python.

UNIT I ALGORITHMIC PROBLEM SOLVING

Algorithms, building blocks of algorithms (statements, state, control flow, functions), notation (pseudo code, flow chart, programming language), algorithmic problem solving, simple strategies for developing algorithms (iteration, recursion). Illustrative problems: find minimum in a list, insert a card in a list of sorted cards, guess an integer number in a range, Towers of Hanoi.

UNIT II DATA, EXPRESSIONS, STATEMENTS

Python interpreter and interactive mode; values and types: int, float, boolean, string, and list; variables, expressions, statements, tuple assignment, precedence of operators, comments; modules and functions, function definition and use, flow of execution, parameters and arguments; Illustrative programs: exchange the values of two variables, circulate the values of n variables, distance between two points.

UNIT III CONTROL FLOW, FUNCTIONS

Conditionals: Boolean values and operators, conditional (if), alternative (if-else), chained conditional (if-elif-else); Iteration: state, while, for, break, continue, pass; Fruitful functions: return values, parameters, local and global scope, function composition, recursion; Strings: string slices, immutability, string functions and methods, string module; Lists as arrays. Illustrative programs: square root, gcd, exponentiation, sum an array of numbers, linear search, binary search.

UNIT IV LISTS, TUPLES, DICTIONARIES

Lists: list operations, list slices, list methods, list loop, mutability, aliasing, cloning lists, list parameters; Tuples: tuple assignment, tuple as return value; Dictionaries: operations and methods; advanced list processing - list comprehension; Illustrative programs: selection sort, insertion sort, mergesort, histogram.

UNIT V FILES, MODULES, PACKAGES & TURTLE

Files and exception: text files, reading and writing files, format operator; command line arguments, errors and exceptions, handling exceptions, modules, packages; Illustrative programs: word count, copy file-**Case study: Simple Graphics using Turtle**: Draw a Random Pattern of Circle, Square and Rectangle; Draw a Pattern of Straight Lines, **Plotting Graphs in Python**: Menu Driven Program to Create Mathematical 3D Objects.

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OUTCOMES:

Upon completion of the course, students will be able to

- Develop algorithmic solutions to simple computational problems
- Read, write, execute by hand simple Python programs.
- Structure simple Python programs for solving problems.
- Decompose a Python program into functions.
- Represent compound data using Python lists, tuples, dictionaries.
- Read and write data from/to files in Python Programs.

TEXT BOOKS:

1. Allen B. Downey, ``Think Python: How to Think Like a Computer Scientist'', 2nd edition, Updated for Python 3, Shroff/O'Reilly Publishers, 2016 (<u>http://greenteapress.com/wp/thinkpython/</u>)

2. Reema Thareja, Problem Solving and Programming with python, 2nd edition, Oxford University press, 2019.

3. Guido van Rossum and Fred L. Drake Jr, "An Introduction to Python – Revised and updated for Python 3.2, Network Theory Ltd., 2011.

REFERENCES:

1. Charles Dierbach, "Introduction to Computer Science using Python: A Computational Problem- Solving Focus, Wiley India Edition, 2013.

2. John V Guttag, "Introduction to Computation and Programming Using Python", Revised and expanded Edition, MIT Press, 2013.

3. Kenneth A. Lambert, "Fundamentals of Python: First Programs", CENGAGE Learning, 2012.

4. Paul Gries, Jennifer Campbell and Jason Montojo, "Practical Programming: An Introduction to Computer Science using Python 3", Second edition, Pragmatic Programmers,LLC,2013.

5. Robert Sedgewick, Kevin Wayne, Robert Dondero, "Introduction to Programming in Python: An Interdisciplinary Approach, Pearson India Education Services Pvt. Ltd., 2016.

6. Timothy A. Budd, "Exploring Python", Mc-Graw Hill Education (India) Private Ltd., 2015.

ME1101

ENGINEERING GRAPHICS

L T P C 2 0 2 3

1

6+6

OBJECTIVES:

- To develop in students, graphic skills for communication of concepts, ideas and design of engineering products.
- To expose them to existing national standards related to technical drawings.

CONCEPTS AND CONVENTIONS (Not for Examination)

Importance of graphics in engineering applications –Use of drafting instruments – BIS conventions and specifications – Size and layout of drawing sheets – Lettering and dimensioning.

UNITI PLANE CURVES AND ORTHOGRAPHIC PROJECTIONS

Basic Geometrical constructions, Curves used in engineering practices: Conics – Construction of ellipse, parabola and hyperbola by eccentricity method – Construction of cycloid – construction of involutes of square and circle – Drawing of tangents and normal to the above curves. Visualization principles – Layout of views- Orthographic projection of multiple views(Free Hand Sketching) from pictorial views of objects-Principal planes-Projection of points-Demo using CAD software for above topics.

UNIT II PROJECTION OF POINTS STRAIGHT LINES AND PLANE SURFACES 6+6

Orthographic projections-principles-Principal planes-First angle projection-Projection of points-Projection of straight lines (only First angle projections) inclined to one of the principal planes -Determination of true lengths and true inclinations - Projection of planes (polygonal and circular surfaces) inclined to one of the principal planes - Demo using CAD software for above topics.

UNIT III PROJECTION OF SOLIDS

Projection of simple solids like prisms, pyramids, cylinder and cone when the axis is inclined to one of the principal planes by rotating object method-Demo using CAD software for above topics.

UNIT IV PROJECTION OF SECTIONED SOLIDS AND DEVELOPMENTOF SURFACES 6+6

Sectioning of above solids in simple vertical position - the cutting plane is inclined to the one of the principal planes and perpendicular to the other – obtaining true shape of section. Development of lateral surfaces of simple and sectioned solids – Prisms, pyramids, cylinders and cones-Demo using CAD software for above topics.

UNITV ISOMETRIC AND PERSPECTIVE PROJECTIONS

Principles of isometric projection – isometric scale –Isometric projections of simple solids and truncated solids - Prisms, pyramids, cylinders, cones- combination of two solid objects in simple vertical positions –Perspective projection of simple solids-Prisms, pyramids and cylinders by visual ray method-Demo using CAD software for above topics.

TOTAL: 61 PERIODS

OUTCOMES:

On successful completion of this course, the student will be able to

- familiarize with the fundamentals and standards of Engineering graphics
- perform freehand sketching of basic geometrical constructions and multiple views of objects.
- project orthographic projections of lines and plane surfaces.
- draw projections of solids and development of surfaces.
- visualize and to project isometric and perspective sections of simple solids.

6+6

6+6

TEXT BOOK:

- 1. NatrajanK.V., "A text book of Engineering Graphics", Dhanalakshmi Publishers, Chennai,2009.
- 2. Venugopal K. and Prabhu Raja V., "Engineering Graphics", New Age International (P) Limited, 2008.

REFERENCES:

- 1. Bhatt N.D. and Panchal V.M., "Engineering Drawing", Charotar Publishing House, 50th Edition,2010.
- 2. Basant Agarwal and Agarwal C.M., "Engineering Drawing", Tata McGraw Hill Publishing Company Limited, New Delhi, 2008.
- 3. Gopalakrishna K.R., "Engineering Drawing" (Vol. I&II combined), Subhas Stores, Bangalore,2007.
- 4. Luzzader, Warren.J. and Duff,John M., "Fundamentals of Engineering Drawing with an introduction to Interactive Computer Graphics for Design and Production, Eastern Economy Edition, Prentice Hall of India Pvt. Ltd, New Delhi,2005.
- 5. N S Parthasarathy and Vela Murali, "Engineering Graphics", Oxford University, Press, New Delhi, 2015.
- 6. Shah M.B., and Rana B.C., "Engineering Drawing", Pearson, 2nd Edition, 2009.

Publication of Bureau of Indian Standards:

- 1. IS 10711 2001: Technical products Documentation Size and lay out of drawing sheets.
- 2. IS 9609 (Parts 0 & 1) 2001: Technical products Documentation –Lettering.
- 3. IS 10714 (Part 20) 2001 & SP 46 2003: Lines for technical drawings.
- 4. IS 11669 1986 & SP 46 2003: Dimensioning of Technical Drawings.
- 5. IS 15021 (Parts 1 to 4) 2001: Technical drawings Projection Methods.

Special points applicable to University Examinations on Engineering Graphics:

- 1. There will be five questions, each of either-or type covering all units of the syllabus.
- 2. All questions will carry equal marks of 20 each making a total of 100.
- 3. The answer paper shall consist of drawing sheets of A3 size only. The students will be permitted to use appropriate scale to fit solution within A3size.
- 4. The examination will be conducted in appropriate sessions on the same day

PHYSICS LABORATORY

OBJECTIVES:

• To introduce different experiments to test basic understanding of physics concepts applied in optics, thermal physics, properties of matter and liquids.

LIST OF EXPERIMENTS: PHYSICS LABORATORY (Any 5 Experiments)

- 1. Determination of rigidity modulus Torsion pendulum
- 2. Determination of Young's modulus by non-uniform bending method
- 3. (a) Determination of wavelength, and particle size using Laser
- (b) Determination of acceptance angle in an optical fiber.
- 4. Determination of thermal conductivity of a bad conductor Lee's Disc method.
- 5. Determination of velocity of sound and compressibility of liquid Ultrasonic interferometer
- 6. Determination of wavelength of mercury spectrum spectrometer grating
- 7. Determination of band gap of a semiconductor
- 8. Determination of thickness of a thin wire Air wedge method

TOTAL: 30 PERIODS

OUTCOMES:

• Upon completion of the course, the students will be able to apply principles of elasticity, optics and thermal properties for engineering applications.

CHEMISTRY LABORATORY

OBJECTIVES:

To make the student to acquire practical skills in the determination of water quality parameters through volumetric and instrumental analysis

LIST OF EXPERIMENTS (Any seven experiments to be conducted)

- 1. Estimation of HCl using Na₂CO₃ as primary standard and Determination of alkalinity in water sample.
- 2. Determination of total, temporary & permanent hardness of water by EDTA method.
- 3. Determination of DO content of water sample by Winkler's method.
- 4. Determination of TDS of water sample.
- 5. Determination of strength of acids in a mixture of acids using conductivity meter.
- 6. Estimation of iron content of the given solution using potentiometer.
- 7. Estimation of iron content of the water sample using spectrophotometer (1, 10-Phenanthroline / thiocyanate method).
- 8. Determination of molecular weight of polyvinyl alcohol using Ostwald viscometer.
- 9. Conductometric titration of strong acid vs strong base.

TOTAL PERIODS: 30

OUTCOMES:

The students will be outfitted with hands-on knowledge in the quantitative chemical analysis of water quality related parameters.

CS1102 PROBLEM SOLVING AND PYTHON PROGRAMMING LABORATORY L T P C

0042

Objectives:

- To study python programs with conditionals and loops
- To use functions for python structured programs.
- Use strings for structuring Python programs.
- Represent compound data using Python lists, tuples, dictionaries.
- To read and write data from and to files in python.

LIST OF EXPERIMENTS:

- 1. Write a program to display the largest number among three numbers.
- 2. Write a program to display the Fibonacci series by using looping constructs.
- 3. Write a function to compute the GCD of two numbers.
- 4. Explore String Functions
- 5. With the help of strings, array or list, display a simple calendar in python program without using the calendar module.
- 6. With the help of list perform Linear search and Binary search.
- 7. Write a program to perform Selection sort, Insertion sort, Merge sort
- 8. Create a text file using python file I/O. Read the content of the file and change them from lower to upper case characters.
- 9. Programs that take command line arguments (word count)
- 10. Find the most frequent words in a text read from a file
- 11. Simulate bouncing ball using Pygame

TOTAL PERIODS: 60

Course Outcomes:

- Design simple programs using conditionals and loops.
- Write functions to solve mathematical problems
- Use strings for structuring Python programs.
- Represent compound data using Python lists, tuples, dictionaries.
- Identify to read and write data from and to files in python.

CI1101

L-T-P-C 2-0-0-0

Prerequisites: Basic law.

The Constitution of India is the supreme law of India. Parliament of India cannot make any law which violates the Fundamental Rights enumerated under the Part III of the Constitution. The Parliament of India has been empowered to amend the Constitution under Article 368, however, it cannot use this power to change the "basic structure" of the constitution, which has been ruled and explained by the Supreme Court of India in its historical judgments. The Constitution of India reflects the idea of "Constitutionalism" – a modern and progressive concept historically developed by the thinkers of "liberalism" – an ideology which has been recognized as one of the most popular political ideology and result of historical struggles against arbitrary use of sovereign power by state. The historic revolutions in France, England, America and particularly European Renaissance and Reformation movement have resulted into progressive legal reforms in the form of "constitutionalism" in many countries. The Constitution of India was made by borrowing models and principles from many countries including United Kingdom and America.

The Constitution of India is not only a legal document but it also reflects social, political and economic perspectives of the Indian Society. It reflects India's legacy of "diversity". It has been said that Indian constitution reflects ideals of its freedom movement; however, few critics have argued that it does not truly incorporate our own ancient legal heritage and cultural values. No law can be "static" and therefore the Constitution of India has also been amended more than one hundred times. These amendments reflect political, social and economic developments since the year 1950. The Indian judiciary and particularly the Supreme Court of India has played an historic role as the guardian of people. It has been protecting not only basic ideals of the Constitution. The judicial activism of the Supreme Court of India and its historic contributions has been recognized throughout the world and it gradually made it "as one of the strongest court in the world".

Course content

- 1. Meaning of the constitution law and constitutionalism
- 2. Historical perspective of the Constitution of India
- 3. Salient features and characteristics of the Constitution of India
- 4. Scheme of the fundamental rights
- 5. The scheme of the Fundamental Duties and its legal status
- 6. The Directive Principles of State Policy Its importance and implementation
- 7. Federal structure and distribution of legislative and financial powers between the Union and the States
- 8. Parliamentary Form of Government in India The constitution powers and status of the

President of India

- 9. Amendment of the Constitutional Powers and Procedure
- 10. The historical perspectives of the constitutional amendments in India
- 11. Emergency Provisions: National Emergency, President Rule, Financial Emergency
- 12. Local Self Government Constitutional Scheme in India
- 13. Scheme of the Fundamental Right to Equality
- 14. Scheme of the Fundamental Right to certain Freedom under Article 19
- 15. Scope of the Right to Life and Personal Liberty under Article 21

HS1201

ENGLISH FOR COMMUNICATION

OBJECTIVES:

The Course enables the second semester Engineering and Technology students to:

- Improve their language ability to improve the four basic skills of communication (LSRW).
- Enhance the skills and methods to enrich their reading and comprehending ability.
- Strengthen their skills to listen to the lectures and talks related to their fields of studies.
- Foster their ability to write effectively in all contexts.
- Cultivate their oral presentation skills through technical presentations and contribution in group discussions.

Course Outcomes:

At the end of the course the students will be able to:

- **CO1:** Read for comprehending and responding in general and professional settings.
- **CO2:** Demonstrate the communication skills (LSRW) in academic, professional and social Environment.
- **CO3**: Participate effectively in formal and informal conversations and express findings and opinions with proper language ability.
- **CO4:** Comprehend conversations and short talks delivered in English.
- **CO5:** Use the language effectively to write with clarity and accuracy in general and technical contexts.

UNIT – 1

Reading- Reading for detailed comparison **Listening-** Listening to interviews **Writing-**Developing hints, summarizing **Speaking-** Talk about future plans, arrangements intensions **Language development-** Sentence structures **Vocabulary development-** Synonyms, Antonyms, Adverbs

UNIT – 2

9 Periods

9 Periods

Reading-Extended reading **Listening-** Listening to telephonic conversations **Writing-**Formal Letter Writing - Letters for bona fide certificate - to the principal for permission for in plant training, industrial visit, paper presentations, inter college events, Letter to the Editor, Recommendations **Speaking-** Formal conversation **Language development-**Use of Punctuation, Modal verbs **Vocabulary development-** One word substitutes, Common Phrasal verbs

UNIT – 3

Reading- Identify topic sentences by reading a short story **Listening-** Listening to TED talks **Writing-** Process/product description **Speaking-** Formal Conversations **Language development-** Relative Clauses, Concord, Error correction **Vocabulary development-**Idioms & Phrases, Minimal pairs

UNIT – 4

Reading- Reading newspaper articles **Listening**- Listening to inspirational speeches **Writing**- Essays, Checklist **Speaking**- Technical Presentations **Language development**-Degrees of Comparison **Vocabulary development**- Articles, Cause and Effect Expressions

UNIT – 5

Reading- Close reading **Listening-** Listening for summarizing **Writing-** Dialogue conversations **Speaking-** Movie/ Book Review **Language development-** Wh Questions, Yes/ no Questions **Vocabulary development-** Foreign Expressions and its applications, Reference words

TOTAL PERIODS: 45

Extensive Reading:

• Kalam, Abdul Dr.A.P.J. - The Wings of Fire, Universities press: 1999

Reference:

- Booth-L. Diana, Project Work, Oxford University Press, Oxford: 2014
- Grussendorf, Marion, English for Presentations, Oxford University Press, Oxford: 2007
- Kumar, Suresh. E. Engineering English. Orient Blackswan: Hyderabad, 2015
- Dutt P. Kiranmai and RajeevanGeeta. Basic Communication Skills, Foundation Books: 2013
- Means,L. Thomas and Elaine Langlois. English & Communication For Colleges.CengageLearning ,USA: 2007.

Recommended websites:

- TED.com
- learningenglish.voanews.com
- islcollective.com
- examenglish.com
- englishclass101.com

9 Periods

9 Periods

9 Periods

COMPLEX VARIABLES AND TRANSFORMS L T P C 3 1 0 4

OBJECTIVES

MA1201

- Understand the concept of Divergence and curl and use it in evaluating Line, Surface and
 - Volume integrals.
- Understand C-R equations and use it in the construction of Analytic Functions.
- Understand the methods of Complex Integration using Cauchy's Integral Formula and • Cauchy Residue theorem, finding Taylor's and Laurent's Series expansions.
- Find the Laplace Transforms of standard Functions and to find the Inverse Laplace Transform of a function and use it in solving Differential Equations.
- To introduce the effective mathematical tools for the solutions of partial differential equations that model several physical processes and to develop Z transform techniques for discrete time systems

UNIT I VECTOR CALCULUS

Gradient and directional derivative – Divergence and curl – Vector identities – Irrotational and Solenoidal vector fields – Line integral over a plane curve – Surface integral – Area of a curved surface - Volume integral - Green's, Gauss divergence and Stoke's theorems -Verification and application in evaluating line, surface and volume integrals-simple applications involving cubes and rectangular parallelopipeds.

UNIT II ANALYTIC FUNCTIONS

Analytic functions – Necessary and sufficient conditions for analyticity in Cartesian and polar coordinates - Properties - Harmonic conjugates - Construction of analytic function -Conformal mapping – Mapping by functions ($w = 1/z, w = z^2, w = e^z, w = \sinh z, w = \cosh z$) – Bilinear transformation.

UNIT III COMPLEX INTEGRATION

Line integral – Cauchy's integral theorem – Cauchy's integral formula – Taylor's and Laurent's series - Singularities - Residues - Residue theorem - Application of residue theorem for evaluation of real integrals – Use of circular contour and semicircular contour.

UNIT IV LAPLACE TRANSFORMS

Existence conditions – Transforms of elementary functions – Transform of unit step function and unit impulse function – Basic properties – Shifting theorems -Transforms of derivatives and integrals - Initial and final value theorems - Inverse transforms - Convolution theorem -Transform of periodic functions – Application to solution of linear second order ordinary differential equations with constant coefficients.

UNIT V Z - TRANSFORMS AND DIFFERENCE EQUATIONS 9+3

Z-transforms - Elementary properties - Inverse Z-transform (using partial fraction and residues) - Initial and final value theorems - Convolution theorem - Formation of difference equations – Solution of difference equations using Z - transform.

TOTAL PERIODS:60

9+3

9+3

9+3

9+3

OUTCOMES

On successful completion of this course, the student will be able to

- Solve problems using divergence and curl and evaluate line, Surface and Volume integrals.
- Solve problems in Analytic functions and construction of analytic functions using C-R Equations.
- Evaluate problems using Cauchy's integral formula and Cauchy residue theorem and find Taylor's and Laurent's series expansion of a given function.
- Obtain the Laplace Transforms of standard functions.
- Use the effective mathematical tools for the solutions of partial differential equations by using Z transform techniques for discrete time systems.

TEXTBOOKS

- 1. Grewal, B.S., Higher Engineering Mathematics, 43rd Edition, Khanna Publishers, 2016.
- 2. Erwin Kreyszig, Advanced Engineering Mathematics, 10th Edition, John Wiley & Sons, Inc., 2016.

REFERENCE BOOKS

1. Bali,N.P.,Goyal,M.,Watkins,C.,Advanced Engineering Mathematics,Laxmi Publications Pvt. Limited, 2007.

2. Boyce, W.E., and DiPrima, R.C., Elementary Differential Equations and Boundary Value Problems, Wiley India, 2012.

3. O'Neil. P. V. "Advanced Engineering Mathematics", 7th Edition, Cengage Learning India Pvt., Ltd, New Delhi, 2011.

4.T. Veerarajan, Engineering Mathematics, Tata Mcgraw Hill publications co. ltd, New Delhi.2017.

OBJECTIVES:

To enrich the understanding of various types of materials and their applications in engineering and technology.

UNIT I CONDUCTING MATERIALS

Conductors – classical free electron theory of metals – Electrical and thermal conductivity – Wiedemann – Franz law – Lorentz number – Draw backs of classical theory – Quantum theory –Fermi distribution function – Effect of temperature on Fermi Function – Density of energy states –carrier concentration in metals.

UNIT II SEMICONDUCTING MATERIALS

Intrinsic semiconductor – carrier concentration derivation – Fermi level – Variation of Fermi level with temperature – electrical conductivity – band gap determination –Elemental and Compound Semiconductors – **N-type and P-type semiconductor (Qualitative)** – Hall effect –Determination of Hall coefficient – Applications.

UNIT III MAGNETIC AND SUPERCONDUCTING MATERIALS

Origin of magnetic moment – Bohr magneton – comparison of Dia, Para and Ferro magnetism –Domain theory – Hysteresis – soft and hard magnetic materials – antiferromagnetic materials –Ferrites and its applications. **Electro static Discharge (ESD)**-Superconductivity: properties – Type I and Type II superconductors–BCS theory of superconductivity (Qualitative) - High Tc superconductors – Electrical, medical, magnetic and computer application of superconductors.

UNIT IV DIELECTRIC MATERIALS

Electrical susceptibility – dielectric constant – electronic, ionic, orientation and space charge polarization – frequency and temperature dependence of polarisation – **Clausius mosotti relation -** dielectric loss – dielectric breakdown – uses of dielectric materials (capacitor and transformer).

UNIT V ADVANCED ENGINEERING MATERIALS

Metallic glasses - melt spinning process, applications - shape memory alloys: Ni-Ti alloy, applications – nanomaterials: preparation (bottom up and top down approaches), properties and applications- Bio materials – introduction- properties of bio materials-examples- medical applications- Ophthalmology- bio sensors- characteristics.

Total Periods: 45

9

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OUTCOMES:

At the end of this course,

- The students will gain knowledge of conducting materials and variation of its properties with temperature.
- Acquire knowledge on basics of semiconductor physics and its applications in various devices.
- Get knowledge on magnetic and superconducting materials properties and their various applications.
- The students will understand the basics of dielectric materials, properties and applications of dielectric materials.
- The students will get knowledge about new engineering materials and its applications in social applications.

TEXT BOOKS:

- 1. S.Mohan, Principles of Materials Science, MJP Publishers, 2018.
- 2. Jasprit Singh, Semiconductor Devices, Basic Principles, Wiley 2012.
- 3. Umesh K Mishra and Jasprit Singh, Semiconductor Device Physics and Design^I, Springer, 2008.

REFERENCES:

- 1. Wahab, M.A. Solid State Physics: Structure and Properties of Materials^{II}, Narosa Publishing House, 2009.
- 2. William D.Callister Jr, David G. Rethwisch, Materials Science and Engineering, An Introduction, Wiley India (P) Ltd., 8th Edition, 2009.
- 3. Pillai S.O., Solid State Physics, New Age International (P) Ltd., Publishers, 2009.
- 4. Semiconductor Introduction, <u>https://youtu.be/k6ZxP9Yr02E</u> (Video lecture)
- 5. Superconductivity, <u>https://youtu.be/D-9M3GWOBrw</u> (Video lecture)

EE 1201BASIC ELECTRICAL AND ELECTRONICS ENGINEERINGL T P C3003

OBJECTIVES:

- To explain the basic Quantities and different componentsused in Electrical circuits
- To explain the operations of electrical machines.
- To explain the working principles of measuring instruments, transducers and calibration for instruments.
- To explain the fundamentals of Electronics
- To impart knowledge of communication.

UNIT I FUNDAMENTALS OF ELECTRICALCIRCUITS

Basic Electrical Quantities, Circuit components, Fundamental laws of electric circuits– Steady State Solution of DC Circuits- Nodal analysis and Mesh analysis-Introduction of AC Circuits-Sinusoidal Steady State Analysis, Power and Power Factor-Current and Voltage equations for Three Phase Balanced Circuits.

UNIT II ELECTRICAL MACHINES

Construction, Principle of Operation and Basic Equations of DC Generator, DCMotor, Single Phase Transformer and Single phase induction Motor.

UNIT III MEASURING INSTRUMENTS AND TRANSDUCERS

Introduction to Measuring instruments –Operating principles of PMMC, Voltmeter, Ammeter, and Dynamometer type Wattmeter & Energy Meter, Introduction to transducers –Stain Gauge, LVDT and RTD-Principles of Calibration.

UNIT IV ELECTRONICS

Introduction Analog electronics–Characteristics of PN Junction Diode and Zener Diode - Half Wave &Full Wave Rectifiers.Bipolar Junction Transistor and its Characteristics. Introduction to Digital electronics:Number systems -Boolean algebra theorems–Logic Gates-Adder-Multiplexer and Demultiplexer Basics of sequentialCircuits– Flip-Flops – Shift Registers-4 bit Ripple Counter – R-2R ladder type D/A and Successive approximation type A/D Conversion.

UNIT V FUNDAMENTALS OF COMMUNICATION SYSTEMS

Introduction – Elements of Communication Systems–Principles of Amplitude and Frequency Modulations. Basic of digital Communication –ASK,PSK and FSK- Communication Systems: Radio, Antenna, TV, ISDN, Microwave, Satellite and Optical Fibre (Block Diagram Approach only) and Comparison of 2G,3G and 4G in mobile communications.

TOTAL PERIODS: 45

9

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Ability to

- Understand electric circuits and fundamental analysis of circuits.
- Understand working principles of electrical machines
- Choose appropriate instruments for electrical measurement and transducers for a specific application.
- Understand the concepts of Analog electronics and Digital electronics.
- Understand and Gain knowledge of types communication systems

TEXT BOOKS:

- 1. D.P.Kothari and I.J. Nagarath –"Basic Electrical & Electronics Engineering", c.Grawhill publications, 1st Edition, 2014. (All Units)
- 2. Mehta V K, "Principles of Electronics", S.Chand& Company Ltd, 1994.
- 3. Gary S. Rogers, " An Introduction to Wireless Technology", Pearson Education, 2008

REFERENCE BOOKS:

- 1. Vincent Del Toro, Electrical Engineering Fundamentals, Prentice Hall, 2006.
- Del Toro, "Electrical Engineering Fundamentals", Pearson Education, New Delhi, 2007
- 3. V.K.Mehta&Rohit Mehta, Principles of Electrical Engineering, S.Chand publications, 2nd Edition, 2003.
- 4. Simon Haykin, —Communication Systems^I, 4th Edition, Wiley, 2014.

OBJECTIVES: To develop capacity to predict the effect of force and motion in the course of carrying out the design functions of engineering.

UNIT-I STATICS OF PARTICLES

Introduction – Units and Dimensions – Laws of Mechanics – Lami's theorem, Parallelogram and triangular Law of forces – Vectorial representation of forces – Vector operations of forces - additions, subtraction, dot product, cross product – Coplanar Forces – rectangular components – Equilibrium of a particle – Forces in space – Equilibrium of a particle in space – Equivalent systems of forces – Principle of transmissibility.

UNIT-II EQUILIBRIUM OF RIGID BODIES 9+6

Free body diagram – Types of supports –Action and reaction forces – stable equilibrium – Moments and Couples – Moment of a force about a point and about an axis – Vectorial representation of moments and couples – Scalar components of a moment – Varignon's theorem – Single equivalent force -Equilibrium of Rigid bodies in two dimensions – Equilibrium of Rigid bodies in three dimensions

UNIT-III ROPERTIES OF SURFACES AND SOLIDS 9+6

Centroids and centre of mass – Centroids of lines and areas - Rectangular, circular, triangular areas by integration – T section, I section, - Angle section, Hollow section by using standard formula – Theorems of Pappus - Area moments of inertia of plane areas – Rectangular, circular, triangular areas by integration – T section, I section, Angle section, Hollow section by using standard formula – Parallel axis theorem and perpendicular axis theorem – Principal moments of inertia of plane areas – Principal axes of inertia-Mass moment of inertia –mass moment of inertia for solids from first principle – Relation to area moments of inertia.

UNIT-IV DYNAMICS OF PARTICLES 9+6

Displacements, Velocity and acceleration, their relationship – Relative motion – Curvilinear motion – Newton's laws of motion – Work Energy Equation– Impulse and Momentum – Impact of elastic bodies.

UNIT-V FRICTION AND RIGID BODY DYNAMICS 9+6

9+6

Friction force – Laws of sliding friction – equilibrium analysis of simple systems with sliding friction – wedge friction-. Rolling resistance -Translation and Rotation of Rigid Bodies – Velocity and acceleration – General Plane motion of simple rigid bodies such as cylinder, disc/wheel and sphere.

TOTAL : 45+30 = 75 PERIODS

OUTCOMES:

On successful completion of this course, the student will be able to

- illustrate the vectorial and scalar representation of forces and moments
- analyse the rigid body in equilibrium
- evaluate the properties of surfaces and solids
- calculate dynamic forces exerted in rigid body
- determine the friction and the effects by the laws of friction

TEXT BOOKS:

- Beer, F.P and Johnston Jr. E.R., "Vector Mechanics for Engineers (In SI Units): Statics and Dynamics", 8th Edition, Tata McGraw-Hill Publishing company, New Delhi (2004).
- 2. Rajasekaran S and Sankarasubramanian G., "Engineering Mechanics Statics and Dynamics", 3rd Edition, Vikas Publishing House Pvt. Ltd., 2005.

REFERENCES:

- 1. Bhavikatti, S.S and Rajashekarappa, K.G., "Engineering Mechanics", New Age International (P) Limited Publishers, 1998.
- 2. Hibbeller, R.C and Ashok Gupta, "Engineering Mechanics: Statics and Dynamics", 11th Edition, Pearson Education2010.
- 3. Irving H. Shames and Krishna Mohana Rao. G., "Engineering Mechanics Statics and Dynamics", 4th Edition, Pearson Education2006.
- 4. Meriam J.L. and Kraige L.G., "Engineering Mechanics- Statics Volume 1, Dynamics- Volume 2", Third Edition, John Wiley &Sons,1993.

OBJECTIVES:

To provide exposure to the students with hands on experience on various basic engineering practices in Civil, Mechanical, Electrical and Electronics Engineering.

GROUP A (CIVIL & MECHANICAL)

I CIVIL ENGINEERING PRACTICE

Buildings:

(a) Study of plumbing and carpentry components of residential and industrial buildings. Safety aspects.

Plumbing Works:

- (a) Study of pipeline joints, its location and functions: valves, taps, couplings, Unions, reducers, elbows in household fittings.
- (b) Study of pipe connections requirements for pumps and turbines.

(c) Preparation of plumbing line sketches for water supply and sewage works.

(d) Hands-on-exercise: Basic pipe connections – Mixed pipe material connection – .pipe connections with different joining components.

(e) Demonstration of plumbing requirements of high-rise buildings.

Carpentry using Power Tools only:

- (a) Study of the joints in roofs, doors, windows and furniture.
- (b) Hands-on-exercise: Wood work, joints by sawing, planing and cutting.

II MECHANICAL ENGINEERING PRACTICE

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Welding:

- (a) Preparation of butt joints, lap joints and T- joints by Shielded metal arc welding.
- (b) Gas welding practice

Basic Machining:

- (a) Simple Turning and Taper turning
- (b) Drilling Practice

Sheet Metal Work:

(a) Forming & Bending:

- (b) Model making Trays and funnels.
- (c) Different type of joints.

Machine assembly practice:

- (a) Study of centrifugal pump
- (b) Study of air conditioner

Demonstration on:

(a) Smithy operations, upsetting, swaging, setting down and bending. Example -

Exercise – Production of hexagonal headed bolt.

- (b) Foundry operations like mould preparation for gear and step cone pulley.
- (c) Fitting Exercises Preparation of square fitting and V fitting models.

GROUP -B (ELECTRICAL & ELECTRONICS)

III ELECTRICAL ENGINEERING PRACTICE

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- 1. Residential house wiring using switches, fuse, indicator, lamp and energy meter.
- 2. Fluorescent lamp wiring.
- 3. Stair case wiring
- 4. Measurement of electrical quantities voltage, current, power & power factor in

RLC circuit.

5. Measurement of energy using single phase energy meter.

6. Measurement of resistance to earth of electrical equipment.

IV ELECTRONICS ENGINEERING PRACTICE

1. Study of Electronic components and equipments – Resistor, colour coding measurement of AC Signal parameter (peak-peak, rms period, frequency) using CR.

- 2. Study of logic gates AND, OR, EX-OR and NOT.
- 3. Generation of Clock Signal.
- Soldering practice Components Devices and Circuits Using general purpose PCB.
- 5. Measurement of ripple factor of HWR and FWR.

TOTAL PERIODS : 60

OUTCOMES:

On successful completion of this course, the student will be able to

- 1. Fabricate carpentry components and pipe connections including plumbing works.
- 2. Use welding equipments to join the structures.
- 3. Carry out the basic machining operations
- 4. Make the models using sheet metal works
- 5. Illustrate on centrifugal pump, Air conditioner, operations of smithy, foundry and fittings
- 6. Carry out basic home electrical works and appliances
- 7. Measure the electrical quantities
- 8. Elaborate on the components, gates, soldering practices.

EE1204 BASIC ELECTRICAL AND ELECTRONICS LABORATORY L T P C 0 0 4 2

OBJECTIVES:

- To train the students in performing various tests on electrical drives and sensors
- To enability the students to understand the behavior of semiconductor device based on experimentation.
- To learn the characterizing of circuit behavior with digital ICs.

LIST OF EXPERIMENTS:

- 1. Verification of KVL and KCL Laws
- 2. Measurement of three phase power
- 3. Load test on separately excited DC generator
- 4. Load test on Single phase Transformer
- 5. Load test on Induction motor
- 6. Load test on DC shunt motor.
- 7. Characteristics of LVDT
- 8. Calibration of Ammeter and Voltmeter
- 9. RTD and Thermistor
- 10. Characteristics of PN Diode and Zener Diode
- 11. CE Characteristics of NPN Transistor
- 12. Application of Diode-Half Wave Rectifier and Full Wave Rectifier
- 13. Verification of Half Adder and Flip-Flops,

Minimum of 10 Experiments to be carried out :-

TOTAL PERIODS : 60

CY1201 ENVIRONMENTAL SCIENCE AND ENGINEERING

L T P C 2 0 0 0

COURSE OBJECTIVES

- To understand nature and the facts about the environment.
- To find and implement scientific, technological, economic and political solutions to environmental problems.
- To study the interrelationship between living organism and environment.
- To appreciate the importance of environment by assessing its impact on the human world; envision the surrounding environment, its functions and its value.
- To study the dynamic processes and understand the features of the earth's interior and surface.
- To study the integrated themes and biodiversity, natural resources, pollution control and waste management

UNIT I ENVIRONMENT, ECOSYSTEMS AND BIODIVERSITY

Definition, scope and importance of environment – need for public awareness – concept of an ecosystem – structure and function of an ecosystem – producers, consumers and decomposers – energy flow in the ecosystem – ecological succession – food chains, food webs and ecological pyramids – Introduction, types, characteristic features, structure and function of major ecosystem – Introduction to biodiversity definition: genetic, species and ecosystem diversity – value of biodiversity – Biodiversity at global, national and local levels – India as a mega-diversity nation – hot-spots of biodiversity – threats to biodiversity – endangered and endemic species of India – conservation of biodiversity: In-situ and ex-situ conservation of biodiversity.

UNIT II ENVIRONMENTAL POLLUTION

Definition – causes, effects and control measures of: (a) Air pollution (b) Water pollution (c) Soil pollution (d) Marine pollution (e) Noise pollution (f) Thermal pollution (g) Nuclear hazards – solid waste management: causes, effects and control measures of municipal solid wastes – role of an individual in prevention of pollution – pollution case studies – disaster management: floods, earthquake, cyclone and landslides.

UNIT III NATURAL RESOURCES

Forest resources: Use and over-exploitation, deforestation, case studies- dams and their effects on forests and tribal people – Water resources: Use and over- utilization of surface and ground water – Mineral resources: environmental effects of extracting and using mineral resources, case studies – Food resources: changes caused by agriculture and overgrazing, effects of modern agriculture, case studies – Energy resources: Growing energy needs, renewable and non renewable energy sources, use of alternate energy sources. case studies – Land resources: Land as a resource, land degradation, man induced landslides, soil erosion and desertification

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12 Principles of Green chemistry, role of an individual in conservation of natural resources
 Equitable use of resources for sustainable lifestyles.

UNIT IV SOCIAL ISSUES AND THE ENVIRONMENT

From unsustainable to sustainable development – urban problems related to energy – water conservation, rain water harvesting, watershed management – resettlement and rehabilitation of people; its problems and concerns, environmental ethics: Issues and possible solutions – climate change, global warming, acid rain, ozone layer depletion, nuclear accidents and holocaust, case studies – environment protection act – Air (Prevention and Control of Pollution) act – Water (Prevention and control of Pollution) act – Widlife protection act – Forest conservation act –- central and state pollution control boards.

UNIT V HUMAN POPULATION AND THE ENVIRONMENT

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Population growth, variation among nations – population explosion – family welfare programme – environment and human health – human rights – value education – HIV / AIDS – women and child welfare – role of information technology in environment and human health.

TOTAL PERIODS: 45

OUTCOMES

- Students will be able to understand the functions of ecosystems and appreciate the bio diversity.
- Students will be able to know the measures to control environmental pollution.
- Students will be able to understand the usage as well as the effects of over exploitation of natural resources.
- Students will have knowledge about finding technological, economic and political solutions to environmental problems with various Environmental Protection Act in mind.
- Students will be able to understand the interrelationship between population explosion and the environment and also role of IT in environment and human health.
- Students will be able to understand that Environmental problems can only be solved by Public participation in all aspects and cannot be solved by mere laws.

TEXT BOOKS

Environmental Science and Engineering by Anubha Kaushik and C.P.Kaushik-New Age International Publishers. New Delhi, 2017.

REFERENCES

1.Benny Joseph , Environmental Studies, Tata mcgraw-Hill Publishing Company, Ltd., New Delhi, 2006.

2. Dr.B.S.Chauhan, Environmental Studies, University Science Press, New Delhi, 2011.

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- Solve differential equations using Fourier series analysis which plays a vital role in engineering applications.
- Appreciate the physical significance of Fourier series techniques in solving one dimensional heat flow problems and one dimensional wave equations.
- Appreciate the physical significance of Fourier series techniques in solving two dimensional heat flow problems in Mechanical Engineering.
- Understand the mathematical principles on transforms and partial differential equations would provide them the ability to formulate and solve some of the physical problems of engineering.

TEXT BOOKS :

- 1. Grewal B.S., "Higher Engineering Mathematics", 43rd Edition, Khanna Publishers, New Delhi, 2014.
- 2. Narayanan S., Manicavachagom Pillay.T.K and Ramanaiah.G "Advanced Mathematics for Engineering Students", Vol. II & III, S.Viswanathan Publishers Pvt. Ltd, Chennai, 1998.

REFERENCES:

- 1. Andrews, L.C and Shivamoggi, B, "Integral Transforms for Engineers" SPIE Press, 1999.
- 2. Bali. N.P and Manish Goyal, "A Textbook of Engineering Mathematics", 9th Edition, Laxmi Publications Pvt. Ltd, 2014.
- 3. Erwin Kreyszig, "Advanced Engineering Mathematics ", 10th Edition, John Wiley, India, 2016.
- 4. James, G., "Advanced Modern Engineering Mathematics", 3rd Edition, Pearson Education, 2007.
- 5. Ramana. B.V., "Higher Engineering Mathematics", McGraw Hill Education Pvt. Ltd, New Delhi, 2016.
- 6. Wylie, R.C. and Barrett, L.C., "Advanced Engineering Mathematics "Tata McGraw Hill Education Pvt. Ltd, 6th Edition, New Delhi, 2012.

| ME1301 | ENGINEERING THERMODYNAMICS | L | Τ | P | С |
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OBJECTIVES:

- To understand the fundamentals of thermodynamics
- To study about the second law of thermodynamics and entropy principles.
- To understand the concept of steam power cycle.
- To study about the thermodynamic relations.
- To learn gas mixture concept and psychrometric processes .

(Use of Standard and approved Steam Table, Mollier Chart, Compressibility Chart and Psychrometric Chart permitted)

UNIT I BASIC CONCEPTS AND FIRST LAW

Basic concepts - concept of continuum, comparison of microscopic and macroscopic approach. System, Property, specific quantities, Temperature and Temperature scales. Quasi-static, reversible and irreversible processes. Displacement work and other modes of work. Zeroth law of thermodynamics, Thermodynamic

states, equilibrium, process cycle, work, heat and other energy – First law of thermodynamics –application to closed and open systems – steady and unsteady flow processes. General Energy equation.

UNIT II SECOND LAW AND ENTROPY PRINCIPLES

Kelvin-Planck and Clausius statements-heat engines and heat pump, reversibility, Carnot cycle, Carnot theorem and performance. Clausius theorem, Concept of entropy, T-s diagram, Tds Equations, entropy change for - pure substance, ideal gases - different processes.

UNIT III PROPERTIES OF PURE SUBSTANCE AND STEAM POWER CYCLE

Formation of steam and its thermodynamic properties, p-v, p-T, T-v, T-s, h-s diagrams. p-v-T surface. Determination of dryness fraction. Application of I and II law for pure substances. Ideal and actual Rankine cycle.

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PERIODS

UNIT IV IDEAL AND REAL GASES, THERMODYNAMIC RELATIONS

Properties of Ideal gas- Ideal and real gas comparison- Equations of state for ideal and real gases- Reduced properties. Compressibility factor - Principle of Corresponding states. - Generalized Compressibility Chart and its use. Maxwell relations, Energy equation, Joule-Thomson Coefficient and Clausius Clapeyron equation.

UNIT V GAS MIXTURES AND PSYCHROMETRY

Mole and Mass fraction, Dalton's and Amagat's Law. Properties of gas mixture – Molar mass, gas constant, density, change in internal energy, enthalpy, entropy and Gibbs function. Psychrometric properties, Psychrometric charts. Property calculations of air vapour mixtures. Psychrometric processes – adiabatic saturation, sensible heating and cooling, humidification, dehumidification, evaporative cooling and adiabatic mixing. Simple Applications

TOTAL:

45

OUTCOMES:

On successful completion of this course, the student will be able to

- Apply the first law of thermodynamics for simple open and closed systems.
- Apply second law of thermodynamics to open and closed systems and calculate entropy .
- Apply the concepts of Rankine cycle to steam power plant.
- Derive simple thermodynamic relations of ideal and real gases.
- Calculate the properties of gas mixtures and moist air and its use in psychometric processes.

TEXTBOOKS:

- 1. R.K.Rajput, "A Text Book Of Engineering Thermodynamics ",Fifth Edition,2017.
- 2. Nag.P.K., "Engineering Thermodynamics", 5th Edition, Tata McGraw-Hill, New Delhi, 2013..

REFERENCES:

- 1. Arora C.P, "Thermodynamics", Tata McGraw-Hill, New Delhi, 2019.
- 2. Borgnakke & Sonnatag, "Fundamental of Thermodynamics", 8th Edition, 2016.
- 3. Chattopadhyay, P, "Engineering Thermodynamics", Oxford University Press, 2016.
- 4. Michael J. Moran, Howard N. Shapiro, "Fundamentals of Engineering Thermodynamics", 8th

Edition.

ME1302 FLUID MECHANICS AND MACHINERY

OBJECTIVES:

- To understand the basic properties of fluid and solve problems on fluid statics.
- To understand fluid kinematics, fluid dynamics and to analyze and appreciate the complexities involved in solving the fluid flow problems.
- To understand the importance of dimensional analysis.
- To study the conservation laws in flow through pipes are studies.
- To understand the importance of various types of flow in pump and turbine.

UNIT I FLUID PROPERTIES AND FLUID STATICS

Units and dimensions -Properties of Fluids - density, specific weight, specific volume, specific gravity, viscosity, compressibility, vapour pressure, capillarity and surface tension. Fluid statics: concept of fluid static pressure - Atmospheric pressure, Gauge Pressure and Absolute pressure - Pressure measurements by manometers. Hydrostatic Forces on surface – buoyancy and floatation.

UNIT II FLUID KINEMATICS AND DYNAMICS

Fluid Kinematics – Classification and types of flow – Continuity equation for 3D flow in cartesian Coordinates - continuity equation for 1D flow. Fluid Dynamics - Forces acting on fluid in motion - Navier Strokes equation - Euler's Equation - Bernoulli's Equation. Application of Bernoulli's Equation - Venturi meter- Orifice meter-Pitot tube- Momentum Equation and its application to pipe bend.

UNIT III DIMENSIONAL ANALYSIS AND MODEL STUDIES

Need for dimensional analysis - Fundamental dimensions - dimensional homogeneity - Rayleigh's method and Buckingham Pi- theorem - Dimensionless Numbers – Model Analysis – Similitude – Model Law - Dimensionless parameters - application of dimensionless parameters – Model analysis.

UNIT IV FLOW THROUGH PIPES

Flow of viscous fluid through circular pipe - Reynold's experiment – Types of flow. Boundary Layer Theory. Energy and head losses through pipes – Major loss – Minor loss – Hydraulic Grade Line and Total Energy Line – Pipes in Series - Pipes in Parallel – Power Transmission by Pipe Line - Moody's diagram.

UNIT V PUMPS AND TURBINES

Impact of jets- Euler's equation- Theory of roto dynamic machines- Centrifugal pumps– working principlework done by the impeller - performance curves - Reciprocating pump- working principle. Classification of turbines – heads and efficiencies – velocity triangles. Axial, radial and mixed flow turbines. Pelton wheel, Francis turbine and Kaplan turbines- working Principles of operation of turbine calculation of main dimensions, regulation and performance - governing of turbines.

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| On successful com | pletion of this course, the student will be able to | | | | | |
| • Gain basic | knowledge on fluid properties, solve problems on static. | | | | | |
| | lems on fluid kinematic and dynamic. | | | | | |
| - | cally predict the nature of physical quantities. | | | | | |
| | d calculate major and minor losses associated with pipe flow | v in | | | | |
| piping netv | vorks. | | | | | |
| • Analyze the | e performance of pumps and turbines. | | | | | |
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| TEXTBOOKS: | | | | | | |
| | K., "Fluid Mechanics and Hydraulic Machines", Laxmi Publicatio | | | v Del | hi, 20 |)15. |
| 2. Jain.A.K | , "Fluid Mechanics" (Including Hydraulic Machines), Khar | ına Publisl | hers, | | | |
| Twelth E | Edition, 2016. | | | | | |
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| REFERENCES: | | | | | | |
| | 7.P, "Engineering Fluid Mechanics", Taylor & Francis, Indian Rep | | | | | |
| | L., "Engineering Fluid Mechanics", Eurasia Publishing House(p) | | | | | |
| | Fox, Alan T. McDonald, Philip J.Pritchard, "Fluid Mechanics and | • | r", 201 | 11. | | |
| | . L. and Wylie E. B., "Fluid Mechanics", McGraw Hill Publishing | | Ŧ | | n | |
| EE1308 | ELECTRICAL DRIVES AND CONTROL | 4 | L | Т | P | C |
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| OBJECTIVES: • To unders • To unders • To study t | tand the concepts of Battery Technologies. he different methods of starting D.C motors and inductio | | d the | | _ | _ |
| OBJECTIVES: • To unders • To unders • To study t • To unders | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. | | d the | | _ | _ |
| OBJECTIVES: • To unders • To unders • To study t • To unders | tand the concepts of Battery Technologies. he different methods of starting D.C motors and inductio | | d the | | _ | _ |
| OBJECTIVES: • To unders • To unders • To study t • To unders | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. | | d the | | _ | _ |
| OBJECTIVES: • To unders • To unders • To study t • To unders • To study t | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives | | d the | | _ | manco |
| OBJECTIVES: • To unders: • To unders: • To study ti • To unders: • To study ti UNIT I | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION | on motors | d the | ir pe | rfor | manco |
| OBJECTIVES: • To unders: • To study ti • To study ti • To study ti • To study ti UNIT I Basic Elements – | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of | on motors | d the al dri | ir pe | rforn | manco |
| OBJECTIVES: • To unders: • To unders: • To study ti • To unders: • To study ti UNIT I Basic Elements – cooling curves – | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of Loading conditions and classes of duty – Selection of pow | on motors | d the al dri | ir pe | rforn | manco |
| OBJECTIVES: • To unders: • To unders: • To study ti • To unders: • To study ti UNIT I Basic Elements – cooling curves – | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of | on motors | d the al dri | ir pe | rforn | manco |
| OBJECTIVES: • To unders: • To unders: • To study ti • To unders: • To study ti UNIT I Basic Elements – cooling curves – | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of Loading conditions and classes of duty – Selection of pow | on motors | d the al dri | ir pe | rforn | manco |
| OBJECTIVES: • To unders: • To unders: • To study ti • To unders: • To study ti UNIT I Basic Elements – cooling curves – 1 | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of Loading conditions and classes of duty – Selection of pow | on motors | d the al dri | ir pe | rforn | manco |
| OBJECTIVES: To unders: To study ti To study ti To study ti To study ti UNIT I Basic Elements – cooling curves – 1 regard to thermal contents UNIT II | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of Loading conditions and classes of duty – Selection of powerloading. Types of Batteries, Characteristics of Batteries. DRIVE MOTOR CHARACTERISTICS | on motors | d the . al dri | ir pe ves - drive | - hea mot | mance 9 ting a ors w |
| OBJECTIVES: • To unders: • To study ti • To study ti • To study ti • To study ti • To study ti UNIT I Basic Elements – cooling curves – I regard to thermal co UNIT II Mechanical characo of Electrical moto | tand the concepts of Battery Technologies. he different methods of starting D.C motors and induction tand the starting methods of DC & AC motors. he conventional and solid-state drives DC & AC drives INTRODUCTION Types of Electric Drives – factors influencing the choice of Loading conditions and classes of duty – Selection of powoverloading. Types of Batteries, Characteristics of Batteries. | on motors | d the al dri for a | ir pe | - hea mot | mance 9 tting a ors w 9 Braki |

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|----------------------|--|----------------|--------|-------|---------|---------|
| UNIT III | STARTING METHODS | | | | | 9 |
| | r starters – Typical control circuits for shunt and series moto | ors – Three | e pha | se sq | uirrel | cage |
| and slip ring induct | on motors. | | | | | |
| | | | | ~ | | |
| UNIT IV | CONVENTIONAL AND SOLID STATE SPEED CON | VTROL O | FD. | C. | | 9 |
| | DRIVES | X7 1 T | 1 | | 1 | L |
| 1 | C series and shunt motors – Armature and field control, V rolled rectifiers & choppers-converter and chopper fed DC of | | nard | conti | roi sy | stem – |
| | | | | | | |
| UNIT V | CONVENTIONAL AND SOLID STATE SPEED CON | TROL O | FA. | C. | | 9 |
| | DRIVES | | | | | |
| Speed control of the | ee phase induction motor – Voltage control, voltage / freque | ency contro | ol, sl | ip po | wer | |
| recovery scheme – | Using inverters and AC voltage regulators – applications. | | | | | |
| | | | | | | |
| | ТОТ | AL | 45 | PE | RIOD |)S |
| OUTCOMES: | | | | | | |
| | f this subject, the students can able to explain | | | | | |
| • Differ | ent types of electrical machines and their performance and b | attery tech | niqu | es | | |
| • Dc and | l Ac motor performances | | | | | |
| Startin | g methods of Ac and Dc motors | | | | | |
| Solid s | state speed control of Dc drives | | | | | |
| Solid s | state speed control of Ac drives | | | | | |
| TEXTBOOKS | | | | | | |
| 1. Nagrath .I.J. | & Kothari .D.P, "Electrical Machines", Tata McGraw-Hill, | 2006 | | | | |
| 2. Vedam Subr | ahmaniam, "Electric Drives (Concepts and Applications)", | Tata McGi | raw-l | Hill, | 2010 | |
| REFERENCES: | | | | | | |
| 1. Partab. H., " | Art and Science and Utilisation of Electrical Energy", Dhan | pat Rai an | d So | ns, 2 | 017 | |
| 2. Pillai.S.K "A | A First Course on Electric Drives", Wiley Eastern Limited, 2 | 2012 | | | | |
| 3. Singh. M.D. | , K.B.Khanchandani, "Power Electronics", Tata McGraw-H | lill, 2006. | | | | |
| 4. David Linde | en and Thomas B. Reddy, "Handbook of Batteries" McGraw | -Hill Profe | essio | nal,2 | 001 | |
| | | | | | | |
| ME1303 | PRODUCTION TECHNOLOGY | | L | Τ | Р | С |
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVES: | | | | | | |
| To study the | basic casting processes, various metal joining processes and | d gain rele | vant | skill | s. | |
| • To learn abo | out the theory behind metal cutting and principle of working | of basic m | nachi | nes | | |
| • To learn abo | out the various plastic moulding and forming processes and t | o make sir | nple | plast | tic par | rt. |
| • To provide | the knowledge on various bulk deformation processes a | nd variou | s abi | rasiv | e ma | chining |
| processes. | | | | | | |

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• To expose knowledge on sheet metal forming processes and special forming processes and to make small sheet metal parts.

UNIT I CASTING PROCESSES AND METAL JOINING PROCESSES

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Introduction to production processes and its classifications - Pattern Types and Allowances. Moulding sand – Types & Properties. Moulding machines and its types. Melting furnaces. Sand casting defects. Special casting processes – Centrifugal casting and Investment casting. Introduction to welding processes - Principle of Gas welding and arc welding. Principle of Resistance welding, Gas metal arc welding, Submerged arc welding, Tungsten Inert Gas welding, Thermit welding and Electron beam welding

UNIT II THEORY OF METAL CUTTING AND BASIC MACHINES

Mechanics of metal cutting, orthogonal and oblique cutting, Mechanism of chip formation, Types of chips, Merchant's Circle Diagram, Cutting Force Measurements, Tool life & Cutting Tool Materials. Centre lathe, constructional features, specification, operations – taper turning methods, thread cutting methods, Capstan and turret lathes- tool layout, Shaper - Basic operations. Milling operations - types of milling cutter.

UNIT III MOULDING AND FORMING OF PLASTICS

Introduction to plastics - Moulding of Thermoplastics - Principle and applications of Injection moulding and its types, Blow moulding, Rotational moulding, Thermoforming and Extrusion. Moulding of Thermosets - Principle and applications of Compression moulding and Transfer moulding - Bonding of Thermoplastics - Fusion and solvent methods.

UNIT IV BULK DEFORMATION PROCESSES AND ABRASIVE MACHINING

Introduction - Hot and cold working of metals - Forging processes - Open and close die forging, Forging equipments. Rolling -Types of Rolling mills, Tube piercing and Defects. Principle of Extrusion and its types. Abrasive processes: grinding wheel – specifications and selection, types of grinding process – cylindrical grinding, surface grinding, centreless grinding and internal grinding.

UNIT V SHEET METAL AND SPECIAL FORMING PROCESSES

Sheet metal characteristics – shearing, bending and drawing operations – Stretch forming operations – Formability of sheet metal – Test methods –special forming processes – Working principle and applications – Hydro forming – Rubber pad forming – Metal spinning– Introduction of Explosive forming, magnetic pulse forming, peen forming, Super plastic forming – Micro forming

TOTAL: 45

5 PERIODS

OUTCOMES:

Upon the completion of this course the students will be able to

- Explain different metal casting processes, compare different metal joining processes merits and demerits
- Describe the mechanism of material removal processes and operational features of centre lathe, shaper

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and milling machines

- Distinguish various methods of manufacturing plastic components
- Summarize various hot working and cold working methods of metals, grinding and other super finishing processes
- Explain various sheet metal making special forming processes

TEXTBOOKS:

- 1. Hajra Chouldhary S.K and Hajra Choudhury. AK., "Elements of workshop Technology", Volume I and II, Media promoters and Publishers Private Limited, Mumbai, 2008
- 2. Kalpakjian. S, "Manufacturing Engineering and Technology", Pearson Education India Edition, 2013

REFERENCES:

- 1. Rao, P.N. "Manufacturing Technology Foundry, Forming and Welding", 4th Edition, TMH-2013
- 2. Sharma, P.C., "A Text book of production Technology", S.Chand and Co. Ltd., 2014.
- 3. HMT, "Production Technology", Tata McGraw Hill, 1998.
- 4. Geofrey Boothroyd, "Fundamentals of Metal Machining and Machine Tools", McGraw Hill, 1984
- 5. Roy. A.Lindberg, "Process and Materials of Manufacture," Fourth Edition, PHI/Pearson Education 2006

| ME1304 | ENGINEERING METALLURGY | L | Т | Р | С |
|--------|------------------------|---|---|---|---|
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OBJECTIVES:

- To study alloys formation, phase diagrams, invariant reactions and iron-carbon diagram
- To introduce concept of heat treatment processes, Explain isothermal transformation, continuous cooling diagrams and different surface heat treatment methods.
- To study the effect of alloying elements on ferrous and non-ferrous metals and properties, applications of various alloys.
- To explain the properties and applications of non-metallic materials and smart materials.
- To impart knowledge on the testing of mechanical properties of materials and principles of plastic deformation mechanisms.

Review (Not for Exam):

• Crystal structure – BCC, FCC and HCP structure – unit cell – crystallographic planes and directions, miller indices – crystal imperfections, point, line, planar and volume defects – Grain size, ASTM grain size number- Atomic Diffusion

UNIT I ALLOYS AND PHASE DIAGRAMS

Constitution of alloys – Solid solutions, substitutional and interstitial – phase diagrams, Isomorphous, eutectic, eutectoid, peritectic and peritectoid reactions, Iron – carbon equilibrium diagram. Classification of steel, properties and applications.

UNIT II HEAT TREATMENT OF METALS

Purpose of Heat treatment- Full annealing, stress relief, recrystallization and spheroidising - normalizing,

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hardening and Tempering of steel. Isothermal transformation diagrams – cooling curves superimposed on I.T. diagram, CCR – Hardenability, Jominy end quench test – Austempering, martempering – case hardening, carburizing, Nitriding, cyaniding, carbonitriding – Flame and Induction hardening – Vacuum and Plasma hardening.

UNIT III FERROUS AND NON-FERROUS METALS

Effect of alloying additions on steel- α and β stabilizers– stainless and tool steels – HSLA, Maraging steels – Cast Iron – Grey, white, malleable, spheroidal – alloy cast irons, Copper and copper alloys – Brass, Bronze and Cupronickel – Aluminium alloys and Al-Cu – precipitation strengthening treatment – Mg-alloys, Bearing alloys, Ni-based super alloys and Titanium alloys.

UNIT IV NON METALS & SMART MATERIALS

Polymers– types, commodity and engineering polymers – Properties and applications of common thermosetting and thermoplastic polymers - Engineering Ceramics – Properties and applications-Composites- Classifications-FRP,MMC,CMC-Applications of Composites, Fiber Optic materials, Piezo Electrics – Shape Memory Alloys

UNIT V MECHANICAL PROPERTIES AND DEFORMATION MECHANISMS

Mechanisms of plastic deformation, slip and twinning – Types of fracture – Testing of materials under tension, compression and shear loads – Hardness tests (Brinell, Vickers and Rockwell) hardness tests, Impact test- lzod and charpy, fatigue and creep failure mechanisms-testing.

TOTAL: 45 PERIODS

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OUTCOMES:

Upon the completion of this course the students will be able to

- Explain alloys and phase diagram, Iron-Iron carbon diagram and steel classification.
- Explain isothermal transformation, continuous cooling diagrams and different heat treatment processes.
- Clarify the effect of alloying elements on ferrous and non-ferrous metals
- Summarize the properties and applications of non metallic materials.
- Explain the testing of mechanical properties. .

TEXTBOOKS:

- 1. Williams D Callister, "Material Science and Engineering" Wiley India Pvt Ltd, Revised Indian Edition 2014
- 2. O.P. Khanna, A text book of Materials Science and Metallurgy, Khanna Publishers, 2003

REFERENCES:

- 1. Kenneth G.Budinski and Michael K. Budinski, "Engineering Materials", Prentice Hall of India Private Limited, 2010.
- 2. Raghavan.V, "Materials Science and Engineering", Prentice Hall of India Pvt. Ltd., 2015.
- **3.** U.C.Jindal : Material Science and Metallurgy, "Engineering Materials and Metallurgy", First Edition, Dorling Kindersley, 2012

| 4. | Upadhyay. G.S. and Anish Upadhyay, "Materials Science and Engineering", Viva Books Pvt. Ltd., |
|----|---|
| | New Delhi, 2006. |

5. Avner, S.H., "Introduction to Physical Metallurgy", McGraw Hill Book Company, 1997.

| EE1309 | ELECTRICAL ENGINEERING LABORATORY | L | Τ | P | C |
|------------------------|--|-------------|------|-------|-----------|
| | | 0 | 0 | 4 | 2 |
| Objectives: | | i | • | | |
| • To validate t | ne principles studied in theory by performing experiments in the | e laborator | ry | | |
| | LIST OF EXPERIMENTS: | | | | |
| 1. Load te | t on DC Shunt & DC Series motor | | | | |
| 2. O.C.C & | Load characteristics of DC Shunt and DC Series generator | | | | |
| 3. Speed c | ontrol of DC shunt motor (Armature, Field control) | | | | |
| 4. Load te | t on single phase transformer | | | | |
| 5. O.C & S | .C Test on a single phase transformer | | | | |
| 6. Regulat | on of an alternator by EMF & MMF methods. | | | | |
| 7. V curve | s and inverted V curves of synchronous Motor | | | | |
| 8. Load te | t on three phase squirrel cage Induction motor | | | | |
| 9. Speed c | ontrol of three phase slip ring Induction Motor | | | | |
| 10. Study o | DC & AC Starters | | | | |
| | T | OTAL PH | ERIO | DS: 6 | 60 |
| Course Outcomes | | | | | |
| • Ability to pa | form speed characteristic of different electrical machine | | | | |

• Ability to perform speed characteristic of different electrical machine

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

| S.No. | NAME OF THE EQUIPMENT | Qty. |
|-------|---|------|
| 1 | DC Shunt motor | 2 |
| 2 | DC Series motor | 1 |
| 3 | DC shunt motor-DC Shunt Generator set | 1 |
| 4 | DC Shunt motor-DC Series Generator set | 1 |
| 5 | Single phase transformer | 2 |
| 6 | Three phase alternator | 2 |
| 7 | Three phase synchronous motor | 1 |
| 8 | Three phase Squirrel cage Induction motor | 1 |
| 9 | Three phase Slip ring Induction motor | 1 |

| ME1305 | PROD | UCTIO | ON TECHNO | OLOGY LA | ABOR | ATORY | | L | T | Р | C |
|--------------------|-------------------------|-----------|-----------------|---------------|---------|--------------|----------|-------|-------|-----|-------|
| | | | | | | | | 0 | 0 | 4 | 2 |
| Objectives: | | | | | | | | | | | |
| | • | - | ice the variou | - | | - | | | - | | |
| | illing mac dustries. | chines of | etc. and to | equip with | the p | ractical kno | wledge r | equir | ed in | the | core |
| | | | L | IST OF EX | KPERI | MENTS: | | | | | |
| | ng and Ma 1al Thread | | g time estimat | ions for: | | | | | | | |
| 2. Intern | al Thread (| Cutting | | | | | | | | | |
| 3. Eccen | tric Turnir | ng | | | | | | | | | |
| 4. Knurl | ing | | | | | | | | | | |
| 5. Hexag | gonal Head | l Shapii | ng | | | | | | | | |
| 6. Contou | ur milling u | using v | ertical milling | g machine | | | | | | | |
| 7.gear cu | itting in m | illing n | nachine | | | | | | | | |
| 8.Gear g | eneration i | in hobb | ing machine | | | | | | | | |
| 9.Gear g | eneration i | in gear | shaping mach | ine | | | | | | | |
| 10.Tool | angle grind | ding wi | th tool and C | utter Grinde | er | | | | | | |
| 11.Meas | urement of | fcutting | g forces in Mi | illing / Turn | ing Pro | ocess | | | | | |
| | | | | | | | ΤΟ | TAL | PER | IOD | S: 60 |
| Course Outc | | | | | | | | | | | |
| Upon complet | ion of this | course | students will | be | | | | | | | |
| | | | achine tools to | | - | - | | | | | |
| • Able t | o use diffe | rent ma | achine tools fo | or finishing | operati | ions | | | | | |

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

| 1 | Centre Lathes | 7 Nos. |
|---|----------------------------|-----------|
| 2 | Shaper | 1 No. |
| 3 | Horizontal Milling Machine | 1 No |
| 4 | Vertical Milling Machine | 1 No |
| 5 | Turret and Capstan Lathes | 1 No each |

| 6 | Radial Drilling Machine | 1 No. |
|----|-----------------------------|-------|
| 7 | lathe Tool Dynamometer | 1 No |
| 8 | Milling Tool Dynamometer | 1 No |
| 9 | Gear Hobbing Machine | 1 No |
| 10 | Tool Makers Microscope | 1 No |
| 11 | Gear Shaping machine | 1 No |
| 12 | Centerless grinding machine | 1 No |
| 13 | Tool and cutter grinder | 1 No |

| MA1404 | STATISTICS AND NUMERICAL METHODS | L | Т | P | C |
|-------------|--|--------|-------|------|-------|
| | | 4 | 0 | 0 | 4 |
| OBJECTIVE | 5: | | | | |
| • This cour | se aims at providing the necessary basic concepts of a few statistical and nun | nerica | ıl me | thod | s and |
| give proc | edures for solving numerically different kinds of problems occurring in engine | neerir | ng an | d | |
| technolog | у. | | | | |

- To acquaint the knowledge of testing of hypothesis for small and large samples which plays an important role in real life problems.
- To introduce the basic concepts of solving algebraic and transcendental equations.
- To introduce the numerical techniques of interpolation in various intervals and numerical techniques of differentiation and integration which plays an important role in engineering and technology disciplines.
- To acquaint the knowledge of various techniques and methods of solving ordinary differential equations.
- UNIT I TESTING OF HYPOTHESIS

Sampling distributions - Estimation of parameters - Statistical hypothesis - Large sample tests based on Normal distribution for single mean, and difference of means -Tests based on t, Chi-square and F distributions for mean, variance and proportion - Contingency table (test for independent) - Goodness of fit.

UNIT II DESIGN OF EXPERIMENTS AND STATISTICAL QUALITY CONTROL

One way and two way classifications - Completely randomized design - Randomized block design - Latin square design - 2^2 factorial design-Control charts for measurements (X and R charts) – Control charts for attributes (p and c charts).

UNIT III SOLUTION OF EQUATIONS AND EIGENVALUE PROBLEMS

Solution of algebraic and transcendental equations - Fixed point iteration method -Bisection- Regula -Falsi Method-Newton Raphson method - Solution of linear system of equations - Gauss elimination method -Pivoting - Gauss Jordan method -Secant method- Iterative methods of Gauss Jacobi and Gauss Seidel -Eigenvalues of a matrix by Power method and Jacobi^{**}s method for symmetric matrices.

UNIT IV INTERPOLATION, NUMERICAL DIFFERENTIATION AND NUMERICAL INTEGRATION

Lagrange"s and Newton"s divided difference interpolations - Newton"s forward and backward difference interpolation - Approximation of derivates using interpolation polynomials - Numerical single and double integrations using Trapezoidal and Simpson"s 1/3 rules and 3/8 rules-Romberg"s Method - Two point and three point Gaussian quadrature formulae.

| UNIT V | NUMERICAL SOLUTION OF DIFFERENTIAL EQUATIONS |
|--------|--|
|--------|--|

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Single step methods : Taylor"s series method - Euler"s method - Modified Euler"s method - Fourth order

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Runge-Kutta method for solving first order equations - Multi step methods : Milne"s and Adams - Bash forth predictor corrector methods for solving first order equations-Finite difference methods for solving second order equations - Finite difference solution of one dimensional heat equation by explicit and implicit methods.

TOTAL:

60

PERIODS

OUTCOMES :

Upon successful completion of the course, students will be able to:

- Apply the concept of testing of hypothesis for small and large samples in real life problems.
- Apply the basic concepts of classifications of design of experiments in the field of in the field of statistical quality control.
- Appreciate the numerical techniques of interpolation in various intervals and apply the numerical techniques of differentiation and integration for engineering problems.
- Understand the knowledge of various techniques and methods for solving first and second order ordinary differential equations.
- Solve the partial and ordinary differential equations with initial and boundary conditions by using certain techniques with engineering applications

TEXT BOOKS :

- 1. Grewal. B.S. and Grewal. J.S., "Numerical Methods in Engineering and Science", 10 th Edition, Khanna Publishers, New Delhi, 2015.
- 2. Johnson, R.A., Miller, I and Freund J., "Miller and Freund"s Probability and Statistics for Engineers", Pearson Education, Asia, 8 th Edition, 2015.

REFERENCES :

- 1. Burden, R.L and Faires, J.D, "Numerical Analysis", 9 th Edition, Cengage Learning, 2016.
- 2. Devore. J.L., "Probability and Statistics for Engineering and the Sciences", Cengage Learning, New Delhi, 8 th Edition, 2014.
- 3. Gerald. C.F. and Wheatley. P.O. "Applied Numerical Analysis" Pearson Education, Asia, New Delhi, 2006.
- 4. Spiegel. M.R., Schiller. J. and Srinivasan. R.A., "Schaum"s Outlines on Probability and Statistics ", Tata McGraw Hill Edition, 2004.
- 5. Walpole. R.E., Myers. R.H., Myers. S.L. and Ye. K., "Probability and Statistics for Engineers and Scientists", 8 th Edition, Pearson Education, Asia, 2007.

| ME1401 | MANUFACTURING PROCESSES | L | Τ | P | С |
|--------------|-------------------------|---|---|---|---|
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| OD IECTIVES. | | | | | |

OBJECTIVES:

- To attain exposure on computerized numerical machine tools and micromachining processes
- To learn about the various non-traditional machining processes, their working principles and material removal mechanisms
- To understand about the high speed machining techniques
- To earn knowledge on various types of rapid prototyping techniques
- To learn about the role of computer aided engineering, Industry 4.0 and IOT in manufacturing,

UNIT I C

CNC MACHINING

Numerical Control (NC) machine tools – CNC types, constructional details, special features, part programming fundamentals CNC – manual part programming – micromachining – wafer machining.

UNIT II NON TRADITIONAL MACHINING PROCESSES

Introduction to unconventional machining processes – Working Principle – Material removal mechanism -Parametric analysis and applications of processes such as ultrasonic machining, Abrasive jet machining, Electrochemical machining, Electro discharge machining, Electron beam machining, Laser beam machining processes - process parameters, tool wear, tool life and Machinability.

UNIT III

HIGH-SPEED MACHINING

High-Speed machining centers, high-speed spindles, spindle sped, feed rate, cutting velocity, surface finish, selection of process parameters, ultra-high-speed machining centers, hard machining.

UNIT IV RAPID PROTOTYPING

Introduction to rapid Prototyping (RP), Need of RP -Rapid Manufacturing Process Optimization: factors influencing accuracy. Classification of different RP techniques based on raw materials, layering technique (2D or 3D) and energy sources-Laminated object manufacturing, Solid ground curing, Repetitive masking and deposition, Selective laser melting and Selective laser sintering

UNIT V

CAE & SMART MANUFACTURING

Need for CAE in manufacturing, simulation of molten metal flow, inspections of casting, analysis of forging & welding processes using CAE Techniques, Introduction to Industry 4.0 and IOT in Manufacturing Industry.

TOTAL: 45

PERIODS

OUTCOMES:

Upon the completion of this course the students will be able to

- Describe about the various types of CNC machines and part programming techniques
- Explain the working principle and material removal mechanism of various types of non traditional machining processes
- Summarize the process of high speed machining
- Distinguish between various types of rapid prototyping techniques
- Explain the application of computer aided engineering, Industry 4.0 and IOT in manufacturing

TEXTBOOKS:

- 1. Vijay.K. Jain "Advanced Machining Processes" Allied Publishers Pvt. Ltd., New Delhi, 2007.
- 2. Paul DeGarmo E, Black J T and Ronald A Kohjer, "Materials and Processes in Manufacturing, John Wiley India, 2011.

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| REFE | CRENCES: | | | | | |
|-------------|------------------|--|---------|--------|-------|----|
| 1. | Mikell P Grov | ver "Principles of Modern Manufacturing (SI Version)" John Wiley & Sons, 2 | 2014 | • | | |
| 2. | Kaushish J P, | "Manufacturing Processes", Prentice Hall India, 2013. | | | | |
| 3. | Kapil Gupta, . | J.Paulo Davim, "High Speed Machining", Academic Press,2020. | | | | |
| 4. | Richerd R Ki | ibbe, John E. Neely, Roland O. Merges and Warren J.White "Machine Te | 'ool] | Pract | ices | ", |
| | Prentice Hall | of India, 1998. | | | | |
| 5. | Rapid Prototy | ping and Engineering Applications, Frank W. Liou, CRC Press | | | | |
| 6. | Geofrey Boot | hroyd, "Fundamentals of Metal Machining and Machine Tools", Mc Graw Hi | ill, 19 | 984 | | |
| 7. | Philip F Ostv | wald and Jairo Munoz, "Manufacturing Processes and Systems" John Wil | ley I | ndia, | Ne | W |
| | Delhi, 2013. | | | | | |
| 8. | Benny Rapha | el and Ian Alan Smith, Fundamentals of Computer Aided Engineering", Wile | y-Bl | ackw | /ell, | |
| | 2003. | | | | | |
| 9. | Apurba Kuma | ar Roy, Divya Zindani, and J. Paulo Davim, Industry 4.0: Developments Tow | ards | the H | Four | th |
| | Industrial Rev | volution, Springer, 2019. | | | | |
| ME14 | 02 | STRENGTH OF MATERIALS | L | T P | • 0 | |
| | | | 3 (| 0 0 | 3 | |
| OBJE | CTIVES: | | | | | |
| • | To understand | the concepts of stress, strain, principal stresses and principal planes. | | | | |
| • | | concept of shearing force and bending moment due to external loads in dete | ermir | nate l | bean | ns |
| | and their effect | | | | | |
| • | | stresses and deformation in circular shafts and helical spring due to torsion. | | | | |
| • | | lopes and deflections in determinate beams by various methods. | | | | |
| • | 1 | stresses and deformations induced in thin and thick shells. | | | | |
| - | To study the s | | | | | |
| UNIT | Ι | STRESS, STRAIN AND DEFORMATION OF SOLIDS | | | 9 | |
| | | formable solids – Tension, Compression and Shear Stresses – Deformation | of s | simp | e ar | nd |
| - | | hermal stresses – Elastic constants – Volumetric strains –Stresses on inc | | - | | |
| 1 | | principal planes. | | - F | | |
| <u>r 1</u> | | | | | | |
| UNIT | II | TRANSVERSE LOADING ON BEAMS AND STRESSES IN BEAM | | | 9 | |
| Beams | s – types transv | verse loading on beams – Shear force and bending moment in beams – Cantil | lever | s - S | imp | ly |
| | • • | d over – hanging beams. Theory of simple bending– bending stress distri | | | - | - |
| | | roportioning of sections – Flitched beams – Shear stress distribution. | | | | |
| 2 | | | | | | |
| UNIT | III | TORSION | | | 9 | |
| | | stresses and deformation in circular and hollows shafts– Deflection in sha | fts f | ixed | | he |
| | | in helical springs – Deflection of helical springs. | | | 11 | |
| 2000 0 | | | | | | |
| | | | | | | |

| UNIT IV | DEFL | ECTION OF BEAMS | | | | 9 |
|----------------------------------|-------------|---|-------------------------|----------|-----------|---------|
| Double Integration | method | - Macaulay"s method - Area momen | t method for comput | ation c | of slopes | and |
| deflections in beam | s - Conju | gate beam and strain energy – Maxwell | s reciprocal theorems. | | | |
| | | | | | | |
| UNIT V | THIN | CYLINDERS, SPHERES AND THIC | K CYLINDERS | | | 9 |
| Stresses in thin cyli | ndrical sł | nell due to internal pressure circumfere | ntial and longitudinal | stresse | es and | |
| deformation in thin a | and thick | cylinders – spherical shells subjected to | internal pressure –Def | ormati | on in sph | ierical |
| shells – Lame"s theo | orem. | | | | | |
| | | | | | 1 | |
| | | | TOTAL: | 45 | PERI | ODS |
| OUTCOMES: | | | | | | |
| Students will be able | | | | | | |
| | - | ots of stress and strain in simple and con | pound bars, the import | rtance | of princi | pal |
| stresses and j | | | | _ | | |
| • Understand t moment. | he Distril | oution of load on beams and stress dist | ribution due to shearin | ng forc | e and be | nding |
| • Apply basic of | equation of | of simple torsion in designing of shafts a | nd helical spring | | | |
| • Calculate the | slope and | l deflection in beams using different met | thods. | | | |
| • Analyze and | design th | in and thick shells for the applied interna | and external pressure | es. | | |
| | - | | - | | | |
| TEXTBOOKS: | | | | | | |
| 1. Egor. P.Popo | v "Engin | eering Mechanics of Solids" Prentice Ha | ll of India, New Delhi | , 2002 | | |
| 2. Bansal, R.K. | , "Strengt | h of Materials", Laxmi Publications (P) | Ltd., 2016 | | | |
| | | | | | | |
| REFERENCES: | | | | | | |
| 1. Ferdinand P. | Been, Ru | ssell Johnson, J.r. and John J. Dewole "M | Mechanics of Material | s", Tata | a McGra | W |
| Hill Publishi | ng "co. Li | d., New Delhi, 2005. | | | | |
| 2. Hibbeler, R.C | C., "Mech | anics of Materials", Pearson Education, | Low Price Edition, 20 | 13 | | |
| | R., "Stre | ngth of Materials", Oxford University Pr | ess, Oxford Higher Ec | lucatio | n Series, | |
| 2010. | | | | | | |
| | "Strength | of Materials", Asian Books Pvt. Ltd., No | ew Delhi, 2009 | | - r - r | 1 |
| ME1403 | | THERMAL ENGINEERING | | Ι | | |
| | | | | 3 | 6 0 0 | 3 |
| OBJECTIVES: | | | | | | |
| • To integrate of cyclic proc | - | ots, laws and methodologies from the fir | st course in thermody | namics | into ana | lysis |
| | | nd performance of Internal combustion | engines. | | | |
| | - | namic concepts in Steam nozzles and S | • | | | |
| | • | king principle and performance of air Co | | | | |
| | | | r | | | |

• To study the concepts of Refrigeration and Air conditioning systems (Use of standard refrigerant property data book, Steam Tables, Mollier diagram and Psychrometric chart permitted)

9

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9

9

PERIODS

TOTAL:

45

UNIT I GAS POWER CYCLES

Air standard efficiency and mean effective pressure calculation for Otto, Diesel, Dual and Brayton cycles, Comparison of air standard cycles.

UNIT II INTERNAL COMBUSTION ENGINES

Classification – Components and their function. Valve timing diagram and port timing diagram – actual p-V diagram of four stroke and two stroke engines. Carburettor. MPFI, Diesel pump and injector system. Battery and Magneto Ignition System – Principles of Combustion and knocking in SI and CI Engines. Lubrication and Cooling systems.

UNIT III

STEAM NOZZLES AND TURBINES

Impulse and Reaction principles, Flow of steam through nozzles, effect of friction, critical pressure ratio, supersaturated flow, compounding, velocity diagram for simple and multi-stage turbines, speed regulations – Governors.

UNIT IV

AIR COMPRESSOR

Classification and working principle of various types of compressors, work of compression with and without clearance, Volumetric efficiency derivation, Multistage air compressor and inter cooling –work of multistage air compressor, working of rotary compressor.

UNIT V

REFRIGERATION AND AIR CONDITIONING

Refrigerants and its properties - Vapour compression refrigeration cycle- super heat, sub cooling – Performance calculations - working principle of vapour absorption system, Ammonia –Water, Lithium bromide – water systems (Description only) and Thermoelectric refrigeration . Air conditioning systems, concept of RSHF, GSHF and ESHF, Cooling load calculations.

OUTCOMES:

Upon completion of this course, the students will be able

- to apply the thermodynamic concepts in different gas power cycles
- to explain the functioning, components, auxiliaries and performance parameters of I.C.Engines
- to explain the flow and solve problems in steam nozzles and steam turbines
- to solve problems in single stage and multistage air compressors
- to solve problems using refrigerant table / charts and psychrometric charts

| TEXTBOOKS: | | | | |
|-------------------------------|--|--------|----------|---------|
| | nal Engineering" Laxmi Publication ,10 th edition. | | | |
| | Domkundwar. S,Domkundwar. A.V., "A course in thermal Engineerin | ıg", " | 'Dha | anpat |
| Rai & sons , 2019 | | | | |
| REFERENCES: | | | | |
| | l Engineering" Tata McGraw-Hill Publishers, 2007 | | | |
| | tion and Air Conditioning," Tata McGraw-Hill Publishers 2008 | | | |
| _ | Combustion Engines", Third Edition, Tata Mcgraw-Hill 2007 | | | |
| | hermal Engineering ",Tata McGraw-Hill, New Delhi,2006 | | | |
| _ | Thermal Engineering", SCITECH Publications (India) Pvt. Ltd., 2009. | | | |
| en an Grand and | | | | |
| ME1404 | Mechanics of Machine-I | / T | P | С |
| | 3 | 0 | 0 | 3 |
| OBJECTIVES: | | | <u> </u> | |
| • To understand the basic | components and layout of linkages in the assembly of a system /machi | ne. | | |
| • To understand the prin- | ciples in analyzing the assembly with respect to the displacement, | velo | city | , and |
| acceleration at any point | t in a link of a mechanism. | | | |
| • To understand the cam r | nechanisms for specified output motions. | | | |
| • To understand the basic | c concepts of toothed gearing and kinematics of gear trains in motion | ı trar | ısmi | ission |
| and in machine compone | ents. | | | |
| • To understand the friction | on concepts in machine elements. | | | |
| | | | | |
| | CS OF MECHANISMS | | | 9 |
| | ns - Basic kinematic concepts and definitions - Degree of freedom | | | - |
| | r"s criterion – Grashof"s Law – Kinematic inversions of four-bar ch | | | |
| | ns – Mechanical advantage – Transmission Angle – Description of s | | con | nmon |
| mechanisms – Quick return n | nechanisms, Straight line generators, Universal Joint – rocker mechani | sms. | | |
| | | | — | |
| | MATIC ANALYSIS OF LINKAGE MECHANISMS | | <u> </u> | 9 |
| | nd acceleration analysis of simple mechanisms – Graphical method- | | - | |
| | city analysis using instantaneous centres – kinematic analysis of simpl | | chai | nısms |
| – Coincident points – Corioli | s component of Acceleration – Introduction to linkage synthesis proble | m. | | |
| UNIT III KINE | MATICS OF CAM MECHANISMS | | <u> </u> | 9 |
| | nd followers – Terminology and definitions – Displacement diagram | me | Un | - |
| | armonic and cycloidal motions – Derivatives of follower motions – L | | | |
| | tour cams – Circular arc and tangent cams – Pressure angle and underc | - | | - |
| of cams. | tour carns — Cricular are and tangent carns — I ressure angle and undere | attill | 5 - 3 | JILIIIE |
| or cumb. | | | | |
| | | | | |

| UNIT IV | GEARS A | ND GEAR TRAINS | | | | 9 |
|------------------------------|-----------------|---|---------------|-------------------------------|---------|--|
| Law of toothed § | gearing – Invo | lutes and cycloidal tooth profiles -Spur Gear | terminology | and def | initio | ns –Gea |
| ooth action – conta | ct ratio – Inte | rference and undercutting. Helical, Bevel, Wo | rm, Rack an | d Pinio | n gear | s [Basic |
| only]. Gear trains – | Speed ratio, t | train value – Parallel axis gear trains – Epicycl | ic Gear Train | ns. | | |
| | | | | | | |
| UNIT V | | N IN MACHINE ELEMENTS | | | | 9 |
| | - | upward motion and downward motion - Frict | ion in screw | thread | s – Be | arings - |
| classification and a | pplication – lu | brication – types – Friction clutches. | | | | |
| _ | | | Γ | | | |
| _ | | | TOTAL: | 45 | PE | RIODS |
| OUTCOMES: | | | | | | |
| 1 1 | | the students can able to | | | | |
| | basics of mec | | | | | |
| | - | celeration of simple mechanisms | | | | |
| • Develop car | - | | | | | |
| | - | and gear trains | | | | |
| | ction in mach | ine elements. | | | | |
| TEXTBOOKS: | | | | | | |
| | | and Shigley, J.E., "Theory of Machines and M | Aechanisms' | $^{\rm rd}$, $3^{\rm rd}$ Ed | lition, | Oxford |
| University F | | | | | | |
| | "Theory of M | Iachines", 3rd Edition, Tata McGraw-Hill, 200 | 19. | | | |
| REFERENCES: | | | | | | |
| | • | of Machines", 3rd Edition, CBS Publishers and | | s, 2005. | | |
| C | , | nisms of Machines", Oxford University Press, | | | | |
| | | natics and Dynamics of Machinery", Tata McC | | 109. | | |
| | | atics and Linkage Design", Prentice Hall, 1961 | | t West | D-4 I | 4.1 |
| 5. Gnosh. A an New Delhi, | | .K., "Theory of Mechanisms and Machines", A | Annaled Eas | st-west | PVI. I | <i>.</i> , |
| , | | .V. "Mechanisms and Machine Theory", Wiley | -Fastern I to | l New | Delhi | 1007 |
| | - | as R.C., "Mechanics of Machines", Viva Low-J | | | | |
| | 1 | tics of Machines", Narosa Publishing House, 2 | | | 511, 17 | <i>,</i> ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, |
| | | Machines",14th Edition, S Chand Publication | | | | |
| | • | Iachines, "Kinematics of Machine", Third Edit | | Educat | ion, 2 | 012. |
| ME1405 | | I OF MATERIALS AND FLUID MECHAN | | | P | С |
| | | HNERY LABORATORY | | | | |
| | | | 0 | 0 | 4 | 2 |
| Objectives: | | | 0 | | | |
| • | v the mechan | ical properties of materials when subjected to | different ty | nes of 1 | oadin | <u> </u> |
| | • | les studied in Fluid Mechanics theory by perf | • • | - | | - |
| | ry une princip | ies suched in Fluid Meenanies theory by peri | orning exp | | эшl | <i>i</i> 0. |

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П

- 1. Tension test on a mild steel rod
- 2. Double shear test on Mild steel and Aluminium rods
- 3. Torsion test on mild steel rod
- 4. Impact test on metal specimen
- 5. Hardness test on metals Brinnell and Rockwell Hardness Number
- 6. Deflection test on beams
- 7. Compression test on helical springs
- 8. Strain Measurement using Rosette strain gauge
- 9. Effect of hardening- Improvement in hardness and impact resistance of steels.
- 10. Tempering- Improvement Mechanical properties Comparison
 - (i) Unhardened specimen

| (ii) |) Quenched Specimen and | |
|-----------------|--|----------|
| (iii | i) Quenched and tempered specimen. | |
| 11. M | Icroscopic Examination of | |
| (i) | Hardened samples and | |
| (ii) | Hardened and tempered samples. | |
| FLUID MI | ECHANICS AND MACHINES LABORATORY | 30 |
| 1. | Determination of the Coefficient of discharge of given Orifice meter. | · |
| 2. | Determination of the Coefficient of discharge of given Venturi meter. | |
| 3. | Calculation of the rate of flow using Rota meter. | |
| 4. | Determination of friction factor for a given set of pipes. | |
| 5. | Conducting experiments and drawing the characteristic curves of centrifugal p submergible pump | oump/ |
| 6. | Conducting experiments and drawing the characteristic curves of reciprocatin | g pump. |
| 7. | Conducting experiments and drawing the characteristic curves of Gear pump. | |
| 8. | Conducting experiments and drawing the characteristic curves of Pelton whee | 1. |
| 9. | Conducting experiments and drawing the characteristics curves of Francis turb | bine. |
| 10. | Conducting experiments and drawing the characteristic curves of Kaplan turb | ine. |
| | TOTAL: 60 PERIODS |) |
| Course O | utcomes: | |
| • Abi | lity to perform Tension, Torsion, Hardness, Compression, and Deformation test | on Solid |

- materials.
- Upon completion of this course, the students will be able to:
 - Perform Tension, Torsion, Hardness, Compression, and Deformation test on Solid materials.
 - Use the measurement equipments for flow measurement.
 - Perform test on different fluid machinery.

LIST OF EQUIPMENT FOR BATCH OF 30 STUDENTS

| S.No. | NAME OF THE | Qty. |
|-------|--|------|
| | EQUIPMENT | |
| 1 | Universal Tensile Testing machine with double 1 shear attachment – | 1 |
| | 40 Ton Capacity | |
| 2 | Torsion Testing Machine (60 NM Capacity) | 1 |
| 3 | Impact Testing Machine (300 J Capacity) | 1 |
| 4 | Brinell Hardness Testing Machine | 1 |
| 5 | Rockwell Hardness Testing Machine | 1 |
| 6 | Spring Testing Machine for tensile and compressive loads (2500 N) | 1 |
| 7 | Metallurgical Microscopes | 3 |
| 8 | Muffle Furnace (800 C) | 1 |

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

| S. NO. | NAME OF THE EQUIPMENT | Qty. |
|--------|---|------|
| 1 | Orifice meter setup | 1 |
| 2 | Venturi meter setup | 1 |
| 3 | Rotameter setup | 1 |
| 4 | Pipe Flow analysis setup | 1 |
| 5 | Centrifugal pump/submergible pump setup | 1 |
| 6 | Reciprocating pump setup | 1 |
| 7 | Gear pump setup | 1 |
| 8 | Pelton wheel setup | 1 |
| 9 | Francis turbine setup | 1 |
| 10 | Kaplan turbine setup | 1 |

| ME1406 | | CAD & CNC LABORATORY | L | Т | Р | C |
|-------------------|---------------|--|---------------|-------|------|---|
| | I | | 0 | 0 | 4 | 2 |
| Objectives | • | | | • | | • |
| ٠ | To gain pract | tical experience in handling 2D drafting and 3D modellin | g software sy | stems | 5. | |
| • | To study the | features of CNC Machine Tool. | | | | |
| • | To expose st | udents to modern control systems (Fanuc, Siemens etc.,) | | | | |
| • | To know the | application of various CNC machines like CNC lathe, C | NC vertical N | Aachi | ning | |
| | centre, CNC | EDM and CNC wire-cut and studying of Rapidprototyp | ing. | | | |
| | | 1.3D GEOMETRIC MODELLING | | | 30 | |
| | | | | | | |

LIST OF EXPERIMENTS:

| Creation of 3D assembly model of following machine elements using 3D M | Modelling software |
|---|--------------------|
| a. Plummer Block | |
| b. Screw Jack | |
| c. Lathe Tailstock | |
| d. Universal Joint | |
| e. Machine Vice | |
| f. Stuffing box | |
| g. Crosshead | |
| h. Safety Valves | |
| i. Non-return valves | |
| j. Connecting rod | |
| k. Piston | |
| 1. Crankshaft | |
| * Students may also be trained in manual drawing of some of the above co | omponents |
| 2. MANUAL PART PROGRAMMING | 30 |
| (i) Part Programming -CNC Machining Centre | |
| () I at i rogramming -Cive macmining Contro | |
| a) Linear Cutting. | |
| | |
| a) Linear Cutting.b) Circular cutting.c) Cutter Radius | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. d) Drilling and Tapping Cycle. | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. d) Drilling and Tapping Cycle. 3. COMPUTER AIDED PART PROGRAMMING | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. d) Drilling and Tapping Cycle. 3. COMPUTER AIDED PART PROGRAMMING e) CL Data and Post process generation using CAM packages. | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. d) Drilling and Tapping Cycle. 3. COMPUTER AIDED PART PROGRAMMING | |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. d) Drilling and Tapping Cycle. 3. COMPUTER AIDED PART PROGRAMMING e) CL Data and Post process generation using CAM packages. pplication of CAPP in Machining and Turning Centre. | TOTAL PERIODS: 60 |
| a) Linear Cutting. b) Circular cutting. c) Cutter Radius d) Compensation. d) Canned Cycle Operations. (ii) Part Programming - CNC Turning Centre a) Straight, Taper and Radius Turning. b) Thread Cutting. c) Rough and Finish Turning cycle. d) Drilling and Tapping Cycle. 3. COMPUTER AIDED PART PROGRAMMING e) CL Data and Post process generation using CAM packages. | TOTAL PERIODS: 60 |

| S.No. | Description of Equipment | Qty |
|----------|--|-------------|
| HARDWARE | | |
| 1. | Computer Server | 1 |
| | Computer nodes or systems (High end CPU with atleast 1 | |
| 2. | GB main memory) networked to the server | 30 |
| 3. | A3 size plotter | 1 |
| 4. | Laser Printer | 1 |
| 5. | CNC Lathe | 1 |
| 6. | CNC milling machine | 1 |
| SOFTWARE | | |
| | Any High end integrated modeling and manufacturing CAD | |
| 7. | / CAM software | 15 licenses |
| | CAM Software for machining centre and turning centre | |
| 8. | (CNC Programming and tool path simulation for FANUC / | 15 licenses |
| | Sinumeric and Heidenhain controller) | |
| 9. | Licensed operating system | Adequate |
| 10. | Support for CAPP | Adequate |

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

HV1401 UNIVERSAL HUMAN VALUES (Common to all B.E / B.TECH Branches)

Universal Human Values : Understanding Harmony

COURSE OBJECTIVES:

The objective of the course is four fold:

- Development of a holistic perspective based on self-exploration about themselves (human being), family, society and nature/existence.
- Understanding (or developing clarity) of the harmony in the human being, family, society and nature/existence
- Strengthening of self-reflection.
- Development of commitment and courage to act.

COURSE TOPICS:

Module 1: Course Introduction - Need, Basic Guidelines, Content and Process for Value Education

- 1. Purpose and motivation for the course, recapitulation from Universal Human Values-I
- 2. Self-Exploration–what is it? Its content and process; 'Natural Acceptance' and Experiential Validation-as the process for self-exploration
- 3. Continuous Happiness and Prosperity- A look at basic Human Aspirations
- 4. Right understanding, Relationship and Physical Facility- the basic requirements for fulfilment of aspirations of every human being with their correct priority
- 5. Understanding Happiness and Prosperity correctly- A critical appraisal of the current scenario
- 6. Method to fulfil the above human aspirations: understanding and living in harmony at various levels.

Include practice sessions to discuss natural acceptance in human being as the innate acceptance for living with responsibility (living in relationship, harmony and co-existence) rather than as arbitrariness in choice based on liking-disliking

Module 2: Understanding Harmony in the Human Being - Harmony in Myself!

- 7. Understanding human being as a co-existence of the sentient 'I' and the material 'Body'
- 8. Understanding the needs of Self ('I') and 'Body' happiness and physical facility
- 9. Understanding the Body as an instrument of 'I' (I being the doer, seer and enjoyer)

10. Understanding the characteristics and activities of 'I' and harmony in 'I'

11. Understanding the harmony of I with the Body: Sanyam and Health; correct appraisal of Physicalneeds, meaning of Prosperity in detail

12. Programs to ensure Sanyam and Health.

Include practice sessions to discuss the role others have played in making material goods available to me. Identifying from one's own life. Differentiate between prosperity and accumulation. Discuss program for ensuring health vs dealing with disease.

Module 3: Understanding Harmony in the Family and Society- Harmony in Human Human Relationship

13. Understanding values in human-human relationship; meaning of Justice (nine universal values in relationships) and program for its fulfilment to ensure mutual happiness; Trust and Respect as the foundational values of relationship

14. Understanding the meaning of Trust; Difference between intention and competence

15. Understanding the meaning of Respect, Difference between respect and differentiation; the other salient values in relationship

16. Understanding the harmony in the society (society being an extension of family): Resolution,

Prosperity, fearlessness (trust) and co-existence as comprehensive Human Goals

17. Visualizing a universal harmonious order in society- Undivided Society, Universal Order- from family to world family.

Include practice sessions to reflect on relationships in family, hostel and institute as extended family, real life examples, teacher-student relationship, goal of education etc. Gratitude as a universal value in relationships. Discuss with scenarios. Elicit examples from students' lives.

Module 4: Understanding Harmony in the Nature and Existence - Whole existence as Coexistence

18. Understanding the harmony in the Nature

19. Interconnectedness and mutual fulfilment among the four orders of nature recyclability and self regulation in nature

20. Understanding Existence as Co-existence of mutually interacting units in all pervasive space

21. Holistic perception of harmony at all levels of existence.

Include practice sessions to discuss human being as cause of imbalance in nature (film "Home" can be used), pollution, depletion of resources and role of technology etc.

Module 5: Implications of the above Holistic Understanding of Harmony on Professional Ethics

22. Natural acceptance of human values

23. Definitiveness of Ethical Human Conduct

- 24. Basis for Humanistic Education, Humanistic Constitution and Humanistic Universal Order
- 25. Competence in professional ethics:

a. Ability to utilize the professional competence for augmenting universal human order

b. Ability to identify the scope and characteristics of people friendly and eco-friendly production systems,

c. Ability to identify and develop appropriate technologies and management patterns for above production systems.

26. Case studies of typical holistic technologies, management models and production systems

27. Strategy for transition from the present state to Universal Human Order:

a. At the level of individual: as socially and ecologically responsible engineers, technologists and managers

b. At the level of society: as mutually enriching institutions and organizations

28. Sum up.

Include practice Exercises and Case Studies will be taken up in Practice (tutorial) Sessions eg. To

discuss the conduct as an engineer or scientist etc.

TOTAL PERIODS : 30 (L) +15 (T) = 45 Periods

REFERENCE BOOKS :

- 1. Jeevan Vidya: Ek Parichaya, A Nagaraj, Jeevan Vidya Prakashan, Amarkantak, 1999.
- 2. Human Values, A.N. Tripathi, New Age Intl. Publishers, New Delhi, 2004.
- 3. The Story of Stuff (Book).
- 4. The Story of My Experiments with Truth by Mohandas Karamchand Gandhi
- 5. Small is Beautiful E. F Schumacher.
- 6. Slow is Beautiful Cecile Andrews
- 7. Economy of Permanence J C Kumarappa
- 8. Bharat Mein Angreji Raj PanditSunderlal
- 9. Rediscovering India by Dharampal
- 10. Hind Swaraj or Indian Home Rule by Mohandas K. Gandhi
- 11. India Wins Freedom Maulana Abdul Kalam Azad
- 12. Vivekananda Romain Rolland (English)13. Gandhi Romain Rolland (English)

ME1501

OBJECTIVES:

To understand the force-motion relationship in components subjected to external forces and analysis of standard mechanisms.

MECHANICS OF MACHINES – II

- To understand the undesirable effects of unbalances resulting from prescribed motions in mechanism.
- To understand the effect of Dynamics of undesirable vibrations.
- To understand the principles in mechanisms used for speed control and stability control

UNIT I FORCE ANALYSIS

Dynamic force analysis - Inertia force and Inertia torque- D Alembert's principle -Dynamic Analysis in reciprocating engines - Gas forces - Inertia effect of connecting rod- Bearing loads - Crank shaft torque - Turning moment diagrams -Fly Wheels -Flywheels of punching presses

UNIT II BALANCING

Static and dynamic balancing – Balancing of rotating masses – Balancing a single cylinder engine –Balancing of Multi-cylinder inline, V-engines - Partial balancing in engines - Balancing machines-Field balancing of discs and rotors

UNIT III FREE VIBRATION

Basic features of vibratory systems - Degrees of freedom - single degree of freedom - Free vibration- Equations of motion -Natural frequency - Types of Damping - Damped vibration- Torsional vibration of shaft - Critical speeds of shafts-Torsional vibration of two rotor system

FORCED VIBRATION **UNIT IV**

Response of one degree freedom systems to periodic forcing – Harmonic disturbances – Disturbance caused by unbalance – Support motion -transmissibility - Vibration isolation. Vibration Measurement Instruments

UNIT V MECHANISM FOR CONTROL

Governors - Porter, Proell and Hartnell Governor - Characteristics - Effect of friction - Controlling force curves. Gyroscopes -Gyroscopic forces and torques – Gyroscopic stabilization – Gyroscopic effects in Automobiles, ships and airplanes.

> **TOTAL: 45 PERIODS**

OUTCOMES:

Upon successful completion of the course, students will be able to:

- Calculate static and dynamic forces of mechanisms.
- Calculate the balancing masses and their locations of reciprocating and rotating masses.
- Compute the frequency of free vibration.
- Compute the frequency of forced vibration and damping coefficient.
- Calculate the speed and lift of the governor
- Estimate the gyroscopic effect on automobiles, ships and airplanes. •

TEXT BOOKS:

- 1. Rattan, S.S, "Theory of Machines", 4 th Edition, Tata McGraw-Hill, 2014.
- 2. Uicker, J.J., Pennock G.R and Shigley, J.E., "Theory of Machines and Mechanisms", 4 th Edition, Oxford University Press, 2014.

REFERENCES:

- 1. Cleghorn. W. L, "Mechanisms of Machines", Oxford University Press, 2014
- 2. Ghosh. A and Mallick, A.K., "Theory of Mechanisms and Machines", 3 rd Edition Affiliated East-West Pvt. Ltd., New Delhi, 2006.
- 3. Rao.J.S. and Dukkipati.R.V. "Mechanisms and Machine Theory", Wiley-Eastern Ltd., New Delhi, 1992.
- 4. Robert L. Norton, "Kinematics and Dynamics of Machinery", Tata McGraw-Hill, 2009.
- 5. V.Ramamurthi, "Mechanics of Machines", Narosa Publishing House, 2002.
- 6. Sadhu Singh "Theory of Machines" Pearson Education, 2002.
- 7. Thomas Bevan, "Theory of Machines", CBS Publishers and Distributors, 1984.
- 8. Khurmi, R.S.,"Theory of Machines", 14th Edition, S Chand Publications, 2005.

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STANDARDS:

- 1. IS 11717: 2000, Vocabulary on Vibration and Shock
- 2. IS 13301: 1992, Guidelines for vibration isolation for machine foundations
- 3. IS 10000: Part 7: 1980, Methods of tests for internal combustion engines: Part 7 Governing tests for constant speed engines and selection of engines for use with electrical generators
- 4. IS 13274: 1992, Mechanical vibration Balancing Vocabulary
- 5. IS 13277 : 1992, Balancing machine Description and evaluation

ME 1502 METROLOGY AND COMPUTER AIDED INSPECTION L T P C

OBJECTIVES:

- To provide knowledge on various Metrological equipment available to measure the dimension of the components.
- To provide knowledge on the correct procedure to be adopted to measure the dimension of the components.

UNIT I BASICS OF METROLOGY

Introduction to Metrology – Need for measurement – Dimensional and Form tolerances – Elements – Work piece, Instruments – Persons – Environment –their effect on Precision and Accuracy – Errors in Measurements – Causes & Types – Control – Types of standards & Practice.

UNIT II LINEAR AND ANGULAR MEASUREMENTS

Linear Measuring Instruments – Evolution – Types – Classification – Limit gauges – gauge design – terminology – procedure – concepts of interchange ability and selective assembly – Angular measuring instruments – Types – Bevel protractor, Angle gauges, Sine bar – Angle alignment telescope – Autocollimator – Applications.

UNIT III FORM AND LASER MEASUREMENT

Principles and Methods of straightness – Flatness measurement – Thread measurement, gear measurement, surface finish measurement, Roundness measurement – Applications. Use of Lasers – Principle – Laser Interferometer – Application in Linear and Angular measurements – Testing of machine tools using Laser Interferometer.

UNIT IV CO-ORDINATE MEASURING MACHINE AND MACHINE VISION

Co-ordinate measuring machine (CMM) – Contact type CMM – Configurations, parts and its features, types of probes, probe compensation. Non-Contact type CMM – Features, probes, Specifications. Errors in CMM measurement, Machine vision system – Methods for sensing objects, image processing, segmentation, pattern recognition – Image histogram and processing

UNIT V MEASUREMENT OF FLOW, PRESSURE AND TEMPERATURE

Measurement of Flow: Differential Pressure Meters, Rotameters, Turbine Meters, Electromagnetic Flow meters, Ultrasonic Flow meters. Measurement of Pressure: Dead-Weight Tester, Bourdon-tube pressure gauges, Diaphragm and Bellows. Measurement of Temperature: Bimetallic strip, Resistance Temperature Detectors, Thermistor, Thermocouples, Pyrometers.

OUTCOMES:

Upon successful completion of the course, students will be able to:

- Describe the concepts of measurements to apply in various metrological instruments
- Outline the principles of linear and angular measurement tools used for industrial applications
- Explain the procedure for conducting computer aided inspection
- Demonstrate the techniques of form measurement used for industrial components
- Discuss various measuring techniques of mechanical properties in industrial applications
- Explain the procedure for conducting Advance Measuring instruments

TEXT BOOKS:

- 1. Jain R.K. "Engineering Metrology", Khanna Publishers, 19th Edition, 2005.
- 2. Gupta. I.C., "Engineering Metrology", Dhanpatrai Publications, 2005.

REFERENCES:

- 1. Charles Reginald Shotbolt, "Metrology for Engineers", 5th edition, Cengage Learning EMEA, 1990.
- 2. Beckwith, Marangoni, Lienhard, "Mechanical Measurements", Pearson Education , 2006.
- 3. Galyer J.F.W. and Shotbolt C.R., "Metrology for Engineers", O.R.Cassel, London, 1993.
- 4. Thomas, "Engineering Metrology", Butthinson & Co., 1984.

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TOTAL: 45 PERIODS

5. Bewoor A.K. and Kulkarni V.A., "Metrology and Measurements", Tata McGraw-Hill, 2009.

6. Whitehouse D.J., The Handbook of Surface and Nanometrology, CRC Press, 2011

| ME | E1503 DESIGN OF MACHINE ELEMENTS | L | Т | Р | С |
|---|---|---------------|------|--------|-----|
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| OBJEC | CTIVES: | | | | |
| • | To familiarize the various steps involved in the Design Process | | | | |
| • To understand the principles involved in evaluating the shape and dimensions of a component to satis strength requirements. | | nt to satisfy | func | tional | and |

- To learn to use standard practices and standard data
- To learn to use catalogues and standard machine components (Use of P S G Design Data Book is permitted)

UNIT I STATIC STRESSES AND VARIABLE STRESSES IN MACHINE MEMBERS

Introduction to the design process - factors influencing machine design, selection of materials based on mechanical properties -Preferred numbers – Calculation of principle stresses for various load combinations, eccentric loading – curved beams – crane hook and 'C' frame- Factor of safety - theories of failure – Design based on strength and stiffness – stress concentration – Design for variable loading.

UNIT II SHAFTS AND COUPLINGS

Design of solid and hollow shafts based on strength, rigidity and critical speed – Keys, keyways and splines - Rigid and flexible couplings.

UNIT III TEMPORARY AND PERMANENT JOINTS

Threaded fasteners - Bolted joints including eccentric loading, Knuckle joints, Cotter joints - Welded joints for structures - theory of bonded joints.

UNIT IV ENERGY STORING ELEMENTS

Various types of springs, optimization of helical springs - Flywheels considering stresses in rims and arms for engines and punching machines.

UNIT V BEARINGS

Sliding contact and rolling contact bearings - Hydrodynamic journal bearings, Sommerfeld Number, Raimondi and Boyd graphs, -- Selection of Rolling Contact bearings.

TOTAL: 45 PERIODS

OUTCOMES:

Upon successful completion of the course, students will be able to:

- Explain the influence of steady and variable stresses in machine component design.
- Apply the concepts of design to shafts, keys and couplings.
- Apply the concepts of design to temporary and permanent joints.
- Apply the concepts of design to energy absorbing members.
- Apply the concepts of design to bearings.
- Design machine components for various industrial applications.

TEXT BOOKS:

1. Bhandari V, "Design of Machine Elements", 4th Edition, Tata McGraw-Hill Book Co, 2016.

2. Joseph Shigley, Charles Mischke, Richard Budynas and Keith Nisbett "Mechanical Engineering Design", 9th Edition, Tata McGraw-Hill, 2011.

REFERENCES:

- 1. Alfred Hall, Halowenko, A and Laughlin, H., "Machine Design", Tata McGraw-Hill BookCo.(Schaum's Outline), 2010
- 2. Ansel Ugural, "Mechanical Design An Integral Approach", 1st Edition, Tata McGraw-Hill Book Co, 2003.
- 3. P.C. Gope, "Machine Design Fundamental and Application", PHI learning private ltd, New Delhi, 2012.
- 4. R.B. Patel, "Design of Machine Elements", MacMillan Publishers India P Ltd., Tech-Max Educational resources, 2011.
- 5. Robert C. Juvinall and Kurt M. Marshek, "Fundamentals of Machine Design", 4th Edition, Wiley, 2005
- 6. Sundararajamoorthy T. V. Shanmugam .N, "Machine Design", Anuradha Publications, Chennai, 2015.

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7. Robert L. Norton, "Machine Design An Integrated Approach", fifth edition Pearson Education India, 2013.

HEAT AND MASS TRANSFER L Т Р С **ME1504**

OBJECTIVES:

- To understand the mechanisms of heat transfer under steady and transient conditions. •
- To understand the concepts of heat transfer through extended surfaces.
- To learn the thermal analysis and sizing of heat exchangers and to understand the basic concepts of mass transfer. (Use of standard HMT data book permitted)

UNIT I CONDUCTION

General Differential equation of Heat Conduction- Cartesian and Polar Coordinates - One Dimensional Steady State Heat Conduction — plane and Composite Systems - Conduction with Internal Heat Generation - Extended Surfaces - Unsteady Heat Conduction - Lumped Analysis - Semi Infinite and Infinite Solids - Use of Heisler's charts.

CONVECTION UNIT II

Free and Forced Convection – Hydrodynamic and Thermal Boundary Layer. Free and Forced Convection during external flow over Plates and Cylinders and Internal flow through tubes.

PHASE CHANGE HEAT TRANSFER AND HEAT EXCHANGERS **UNIT III**

Nusselt's theory of condensation - Regimes of Pool boiling and Flow boiling. Correlations in boiling and condensation. Heat Exchanger Types - Overall Heat Transfer Coefficient - Fouling Factors - Analysis - LMTD method - NTU method.

UNIT IV RADIATION

Black Body Radiation – Grey body radiation – Shape Factor – Electrical Analogy – Radiation Shields. Radiation through gases.

UNIT V MASS TRANSFER

Basic Concepts - Diffusion Mass Transfer - Fick's Law of Diffusion - Steady state Molecular Diffusion - Convective Mass Transfer - Momentum, Heat and Mass Transfer Analogy - Convective Mass Transfer Correlations

> **TOTAL: 45 PERIODS**

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OUTCOMES:

Upon successful completion of the course, students will be able to:

- Apply heat conduction equations to different surface configurations under steady state and transient conditions and solve problems
- Apply free and forced convective heat transfer correlations to internal and external flows through/over various surface . configurations and solve problems
- Explain the phenomena of boiling and condensation, apply LMTD and NTU methods of thermal analysis to different types of heat exchanger configurations and solve problems
- Explain basic laws for radiation and apply these principles to radiative heat transfer between different types of surfaces to solve problems
- Apply diffusive and convective mass transfer equations and correlations to solve problems for different applications
- Apply heat transfer and mass transfer concepts in industrial applications.

TEXT BOOKS:

1. R.C. Sachdeva, "Fundamentals of Engineering Heat & Mass transfer", New Age International Publishers, 2009.

2. Yunus A. Cengel, "Heat Transfer A Practical Approach", Tata McGraw Hill, 5th Edition 2015

REFERENCES:

1. Frank P. Incropera and David P. Dewitt, "Fundamentals of Heat and Mass Transfer", John Wiley & Sons, 1998.

- 2. Kothandaraman, C.P., "Fundamentals of Heat and Mass Transfer", New Age International, New Delhi, 1998.
- 3. Nag, P.K., "Heat Transfer", Tata McGraw Hill, New Delhi, 2002
- 4. Ozisik, M.N., "Heat Transfer", McGraw Hill Book Co., 1994.
- 5. Holman, J.P., "Heat and Mass Transfer", Tata McGraw Hill, 2000

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| ME 1505 | METROLOGY & INSPECTION LABORATORY | L | Т | Р | С |
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OBJECTIVE:

• To become familiar with different measurement equipment and use this for Quality inspection.

LIST OF EXPERIMENTS

- 1. Calibration and use of measuring instruments Vernier caliper, micrometer, Vernier height gauge using gauge blocks
- 2. Calibration and use of measuring instruments bore gauge, telescopic gauge
- 3. Measurement of angles using bevel protractor and sine bar
- 4. Inspect, whether the dimensions of the given specimens are within the tolerance limit or not, using Comparators
- 5. Measurement of screw thread parameters using Floating carriage micrometer
- 6. Measurement of gear tooth thickness using gear tooth vernier caliper
- 7. Measurement of features in a prismatic component using Coordinate Measuring Machine (CMM)
- 8. Measurement of thread parameters by Tool Maker's Microscope
- 9. Measurement of Surface Roughness using portable surface roughness tester
- 10. Straightness /Flatness Testing using Autocollimator
- 11. Measurement of force, torque and temperature

OUTCOMES:

Upon successful completion of the course, students will be able to:

• Select a suitable measuring instrument for measurement of linear and angular dimensions and use the same for carrying out measurements.

TOTAL:

60 PERIODS

- Calibrate simple linear measuring instruments like Vernier caliper, micrometer, Vernier height gauge, etc. using gauge blocks.
- Use advanced measuring equipment like coordinate measuring machines, Toolmakers microscope, and surface finish measuring equipment to carryout measurements.
- Measure the gear tooth dimensions, straightness. Flatness and thread parameters.
- Measure temperature, force, displacement, torque.
- Handle Measuring Equipment with latest technologies.

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

| S.No. | NAME OF THE EQUIPMENT | Qty. |
|-------|--|------|
| 1 | Micrometer | 5 |
| 2 | Vernier Caliper | 5 |
| 3 | Vernier Height Gauge | 2 |
| 4 | Vernier depth Gauge | 2 |
| 5 | Slip Gauge Set | 1 |
| 6 | Gear Tooth Vernier | 1 |
| 7 | Sine Bar | 1 |
| 8 | Floating Carriage Micrometer | 1 |
| 9 | Profile Projector / Tool Makers Microscope | 1 |
| 10 | Mechanical / Electrical / Pneumatic Comparator | 1 |
| 11 | Autocollimator | 1 |
| 12 | Temperature Measuring Setup | 1 |
| 13 | Force Measuring Setup | 1 |
| 14 | Torque Measuring Setup | 1 |

| 15 | Coordinate measuring machine | 1 |
|----|------------------------------------|---|
| 16 | Surface finish measuring equipment | 1 |
| 17 | Bore gauge | 1 |
| 18 | Telescope gauge | 1 |

| ME 1506 | KINEMATICS AND DYNAMICS LABORATORY | L | Т | Р | С |
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OBJECTIVE:

- To supplement the principles learnt in kinematics and Dynamics of Machinery.
- To understand how certain measuring devices are used for dynamic testing.

LIST OF EXPERIMENTS

- a) Study of gear parameters.
 b) Experimental study of velocity ratios of simple, compound, Epicyclic and differential gear trains.
- a)Kinematics of Four Bar, Slider Crank, Crank Rocker, Double crank, Double rocker, Oscillating cylinder Mechanisms.
 b) Kinematics of single and double universal joints.
- a) Determination of Mass moment of inertia of Fly wheel and Axle system.
 b)Determination of Mass Moment of Inertia of axisymmetric bodies using Turn Table apparatus.
 c) Determination of Mass Moment of Inertia using bifilar suspension and compound pendulum.
- 4. Motorized gyroscope Study of gyroscopic effect and couple.
- 5. Governor Determination of range sensitivity, effort etc., for Watts, Porter, Proell, and Hartnell Governors.
- 6. Cams Cam profile drawing, Motion curves and study of jump phenomenon
- a) Single degree of freedom Spring Mass System Determination of natural Frequency and verification of Laws of springs –Damping coefficient determination
 b) Multi degree freedom suspension system Determination of influence coefficient.
- 8. a) Determination of torsional natural frequency of single and Double Rotor systems.- Undamped and Damped Natural frequencies.
 b)Vibration Absorber Tuned vibration absorber.
- 9. Vibration of Equivalent Spring mass system undamped and damped vibration.
- 10. Whirling of shafts Determination of critical speeds of shafts with concentrated loads.
- 11. a) Balancing of rotating masses. (b) Balancing of reciprocating masses.
- 12. a) Transverse vibration of Free-Free beam with and without concentrated masses.
 - b) Forced Vibration of Cantilever beam Mode shapes and natural frequencies.
 - c) Determination of transmissibility ratio using vibrating table.

OUTCOMES:

Upon successful completion of the course, students will be able to:

- Explain gear parameters, kinematics of mechanisms, gyroscopic effect and working of lab equipments.
- Determine mass moment of inertia of mechanical element, governor effort and range sensitivity, natural frequency and damping coefficient, torsional frequency, critical speeds of shafts, balancing mass of rotating and reciprocating masses, and transmissibility ratio.

TOTAL:

60 PERIODS

| S.No. | NAME OF THE EQUIPMENT | Qty. |
|-------|---|-------|
| 1 | Cam follower setup. | 1 No. |
| 2 | Motorised gyroscope. | 1 No. |
| 3 | Governor apparatus - Watt, Porter, Proell and Hartnell governors. | 1 No. |
| 4 | Whirling of shaft apparatus. | 1 No. |
| 5 | Dynamic balancing machine. | 1 No. |
| 6 | Two rotor vibration setup. | 1 No. |
| 7 | Spring mass vibration system. | 1 No. |
| 8 | Torsional Vibration of single rotor system setup. | 1 No. |
| 9 | Gear Models | 1 No. |
| 10 | Kinematic Models to study various mechanisms. | 1 No. |
| 11 | Turn table apparatus. | 1 No. |
| 12 | Transverse vibration setup of | 1 No. |
| | a) cantilever | |

DESIGN OF MECHANICAL TRANSMISSION SYSTEMS L Т Р С **ME1601**

OBJECTIVES:

- To gain knowledge on the principles and procedure for the design of Mechanical power Transmission components. •
- To understand the standard procedure available for Design of Transmission of Mechanical elements
- To learn to use standard data and catalogues (Use of P S G Design Data Book permitted)

UNIT I **DESIGN OF BELT, ROPES AND CHAIN**

Design of Flat belts and pulleys - Selection of V belts and pulleys -Selection of hoisting wire ropes and pulleys -Design of Transmission chains and Sprockets.

UNIT II **DESIGN OF SPUR AND HELICAL GEARS**

Speed ratios and number of teeth-Force analysis -Tooth stresses - Dynamic effects -Fatigue strength - Factor of safety - Gear materials -Design of straight tooth spur & helical gears based on strength and wear considerations - Pressure angle in the normal and transverse plane-Equivalent number of teeth-forces for helical gears.

UNIT III **DESIGN OF BEVEL AND WORM GEARS**

Straight bevel gear: Tooth terminology, tooth forces and stresses, equivalent number of teeth. Estimating the dimensions of pair of straight bevel gears. Worm Gear: Merits and demerits-terminology. Thermal capacity, materials-forces and stresses, efficiency, estimating the size of the worm gear pair. Cross helical: Terminology-helix angles-Estimating the size of the pair of cross helical gears.

UNIT IV **DESIGN OF GEAR BOXES**

Geometric progression - Standard step ratio - Ray diagram, kinematics layout -Design of sliding mesh gear box - Design of multi speed gear box for machine tool applications - Constant mesh gear box - Speed reducer unit. -Variable speed gear box, Fluid Couplings, Torque Converters for automotive applications.

UNIT V **DESIGN OF CLUTCHES AND BRAKES**

Design of plate clutches -axial clutches-cone clutches-internal expanding rim clutches-Electromagnetic clutches. Band and Block brakes - external shoe brakes - Internal expanding shoe brake.

> TOTAL: **45 PERIODS**

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OUTCOMES:

Upon successful completion of the course, students will be able to:

Apply the concepts of design to belts, chains and rope drives.

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- Apply the concepts of design to spur, helical gears.
- Apply the concepts of design to worm and bevel gears.
- Apply the concepts of design to gear boxes.
- Apply the concepts of design to brakes and clutches.
- Design the power transmission elements for industrial applications.

TEXT BOOKS:

1. Bhandari V, "Design of Machine Elements", 4th Edition, Tata McGraw-Hill Book Co, 2016.

2. Richard Budynas and Keith Nisbett "Shigley's Mechanical Engineering Design", 10th Edition, Tata McGraw-Hill, 2014.

REFERENCES:

1. Merhyle F. Spotts, Terry E. Shoup and Lee E. Hornberger, "Design of Machine Elements" 8th Edition, Printice Hall, 2003.

- 2. Orthwein W, "Machine Component Design", Jaico Publishing Co, 2003.
- 3. Prabhu. T.J., "Design of Transmission Elements", Mani Offset, Chennai, 2000.

4. Robert C. Juvinall and Kurt M. Marshek, "Fundamentals of Machine Design",4th Edition, Wiley, 2005

5. Sundararajamoorthy T. V, Shanmugam .N, "Machine Design", Anuradha Publications, Chennai, 2003

| Μ | E1602 | FINITE ELEMENT ANALYSIS | L | Т | Р | С |
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OBJECTIVES:

- To introduce the concepts of Mathematical Modeling of Engineering Problems.
- To appreciate the use of FEM to a range of Engineering Problems

UNIT I INTRODUCTION

Historical Background – Mathematical Modeling of field problems in Engineering – Governing Equations – Discrete and continuous models – Boundary, Initial and Eigen Value problems–Weighted Residual Methods – Variational Formulation of Boundary Value Problems – Ritz Technique – Basic concepts of the Finite Element Method.

UNIT II ONE DIMENSIONAL ANALYSIS

One Dimensional Second Order Equations – Discretization – Element types- Linear and Higher order Elements – Derivation of Shape functions and Stiffness matrices and force vectors-Assembly of Matrices - Solution of problems from solid mechanics. Fourth Order Beam Equation- Problems on it.

UNIT III APPLICATION OF ONE-DIMENSIONAL ELEMENT TO HEAT TRANSFER AND VIBRATION

Derivation of matrices and vector for heat transfer. Problems on Heat transfer. Natural frequencies of longitudinal vibration and mode shapes. Transverse Natural frequencies of beams.

UNIT IV TWO-DIMENSIONAL ANALYSIS

Second Order 2D Equations involving Scalar Variable Functions – Variational formulation –Finite Element formulation – Triangular elements and Quadrilateral elements- Shape functions and element matrices and vectors. Application to Field Problems. Equations of elasticity – Plane stress, plane strain and axisymmetric problems – Constitutive matrices and Strain displacement matrices – Stiffness matrix – Stress calculations.

UNIT V ISOPARAMETRIC FORMULATION AND NUMERICAL INTEGRATION

Natural co-ordinate systems – Isoparametric elements – Shape functions for isoparametric elements – One and two dimensions – Serendipity elements – Numerical integration - Introduction to non-linearity.

TOTAL: 45 PERIODS

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OUTCOMES:

Upon successful completion of the course, students will be able to:

- Develop mathematical models for Boundary Value Problems and their numerical solution
- Apply the concepts of Finite Element Analysis to solve one dimensional problem in structural analysis
- Apply the concepts of Finite Element Analysis to solve one dimensional problem in Heat transfer and Dynamics
- Apply the concepts of Finite Element Analysis to solve two dimensional problems in structural analysis
- Apply the Isoparametric transformation and the use of numerical integration for various analysis
- Apply FEA concepts in all Engineering Applications.

TEXT BOOKS:

- 1. Rao S. S, "The Finite Element Method in Engineering", 6th Edition, ButterworthHeinemann,2018.
- 2. Tirupathi R. Chandrupatla and Ashok D. Belegundu, "Introduction to Finite Elements in Engineering", International Edition, Pearson Education Limited, 2014.

REFERENCES:

- 1. David Hutton, "Fundamentals of Finite Element Analysis", Tata McGrawHill, 2017.
- 2. Reddy, J.N. "Introduction to the Finite Element Method", 4thEdition, Tata McGrawHill,2018.
- 3. Robert D. Cook, David S. Malkus, Michael E. Plesha, Robert J. Witt, "Concepts and Applications of Finite Element Analysis", 4th Edition, Wiley Student Edition, 2007.
- 4. Seshu. P, "Text Book of Finite Element Analysis", PHI Learning Pvt. Ltd., NewDelhi, 2013.
- 5. Bhatti Asghar M, "Fundamental Finite Element Analysis and Applications", John Wiley & Sons, 2005 (Indian Reprint 2013).

| ME1603 | HYDRAULICS AND PNEUMATICS | L | Т | Ρ | С |
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OBJECTIVES:

- To provide students with an understanding of the fluids and components utilized in modern industrial fluid power system and manufacturing Industries.
- To develop a measurable degree of competence in the design, construction and operation of fluid power circuits.

UNIT I FLUID POWER PRINICIPLES AND HYDRAULIC PUMPS

Introduction to Fluid power – Advantages and Applications – Fluid power systems – Types of fluids- Properties of fluids and selection – Basics of Hydraulics – Pascal's Law - Pumping Theory – Pump Classification – Construction, Working, Advantages, Disadvantages – Fixed and Variable displacement pumps

UNIT II HYDRAULIC ACTUATORS AND CONTROL COMPONENTS

Hydraulic Actuators: Cylinders – Types and construction, Application, Hydraulic cushioning – Hydraulic motors - Control Components: Direction Control, Flow control and pressure control valves – Types, Construction and Operation – Servo and Proportional valves – Applications – Accessories: Reservoirs, Pressure Switches – Applications – Fluid Power ANSI Symbols

UNIT III HYDRAULIC CIRCUITS AND SYSTEMS

Accumulators, Intensifiers, Industrial hydraulic circuits – Regenerative, Pump Unloading, Double- Pump, Pressure Intensifier, Air-over oil, Sequence, Reciprocation, Synchronization, Fail-Safe, Speed Control, Hydrostatic transmission, Electro hydraulic circuits, Mechanical hydraulic servo systems.

UNIT IV PNEUMATIC AND ELECTRO PNEUMATIC SYSTEMS

Properties of air – Perfect Gas Laws – Compressor – Filters, Regulator, Lubricator, Muffler, Air control Valves, Quick Exhaust Valves, Pneumatic actuators, Design of Pneumatic circuit – Cascade method – Electro Pneumatic System – Elements – Ladder diagram – Introduction to fluidics and pneumatic logic

UNIT V TROUBLE SHOOTING AND APPLICATIONS

Installation, Selection, Maintenance, Trouble Shooting and Remedies in Hydraulic and Pneumatic systems, Design of hydraulic circuits for Drilling, Planning, Shaping, Surface grinding, Press and Forklift applications. Design of Pneumatic circuits for Pick and Place applications and tool handling in CNC Machine tools – Low-cost Automation – Hydraulic and Pneumatic power packs.

TOTAL: 45 PERIODS

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OUTCOMES:

At the end of the course the students would be able to

- Apply the working principles of fluid power systems and hydraulic pumps.
- Apply the working principles of hydraulic actuators and control components.
- Design and develop hydraulic circuits and systems.
- Apply the working principles of pneumatic circuits and power system and its components.
- Identify various troubles shooting methods in fluid power systems.
- Explain the working of automation with different Hydraulic and Pneumatic systems.

TEXTBOOKS:

- 1. Srinivasan.R., "Hydraulic and Pneumatic Controls", Vijay Nicole Imprints, 3rd edition, 2019.
- 2. Anthony Esposito, "Fluid Power with Applications", Prentice Hall, 2009

REFERENCES:

- 1. Jagadeesha. T., "Pneumatics Concepts, Design and Applications ", Universities Press, 2015.
- 2. Dudelyt, A. Pease and John T. Pippenger, "Basic Fluid Power", Prentice Hall, 1987.
- 3. Majumdar, S.R., "Oil Hydraulics Systems Principles and Maintenance", Tata McGraw Hill, 2001.
- 4. Joshi.P., Pneumatic Control", Wiley India, 2008.
- 5. Shanmugasundaram.K., "Hydraulic and Pneumatic Controls". Chand & Co, 2006
- 6. James A. Sullivan, "Fluid Power Theory and Applications", Fourth Edition, Prentice Hall, 1997

ME 1604 COMPUTER AIDED DESIGN AND MANUFACTURING L T P C

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OBJECTIVES:

- To provide an overview of how computers are being used in mechanical component design
- To understand the application of computers in various aspects of Manufacturing viz., Design, Proper planning, Manufacturing cost, Layout & Material Handling system.

UNIT I INTRODUCTION

Product cycle- Design process- sequential and concurrent engineering- Computer aided design – CAD system architecture-Computer graphics – co-ordinate systems- 2D and 3D transformations - homogeneous coordinates – Line drawing -Clippingviewing transformation-Brief introduction to CAD and CAM – Manufacturing Planning, Manufacturing control. Automation in CAD/CAM & related Concepts.

UNIT II GEOMETRIC MODELING

Representation of curves- Hermite curve- Bezier curve- B-spline curves-rational curves-Techniques for surface modeling – surface patch- Coons and bicubic patches- Bezier and B-spline surfaces. Solid modeling techniques- CSG and B-rep

UNIT III CAD STANDARDS

Standards for computer graphics- Graphical Kernel System (GKS) – standards for exchange images- Open Graphics Library (OpenGL) – Data exchange standards – IGES, STEP, CALS etc. – communication standards

UNIT IV FUNDAMENTAL OF CNC AND PART PROGRAMING

Introduction to NC systems and CNC – Machine axis and Co-ordinate system- CNC machine tools - Principle of operation CNC- Construction features including structure- Drives and CNC controllers - 2D and 3D machining on CNC- Introduction of Part Programming, types – Detailed Manual part programming on Lathe & Milling machines using G codes and M codes-Cutting Cycles, Loops, Sub program and Macros- Introduction of CAM package

UNIT V GROUP TECHNOLOGY AND FLEXIBLE MANUFACTURING SYSTEM (FMS)

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Introduction, needs of GT, part families, classification and coding systems, Simple Problems in Opitz Part Coding system, GT machine cells, benefits of GT. Computer integrated manufacturing (CIM) system, Types of Flexibility, FMS – FMS Components – FMS Application & Benefits – FMS Planning and Control.

TOTAL: 45 PERIODS

OUTCOMES:

Upon the completion of this course the students will be able to

- Explain the 2D and 3D transformations, clipping algorithm, Manufacturing models and Metrics
- Explain the fundamentals of parametric curves, surfaces and Solids
- Summarize the different types of Standard systems used in CAD
- Apply NC & CNC programming concepts to develop part programme for Lathe & Milling Machines
- Summarize the different types of techniques used in Cellular Manufacturing and FMS
- Apply fundamentals of CAD concepts and techniques for modelling industrial components.

TEXT BOOKS:

- 1. Ibrahim Zeid "Mastering CAD CAM" Tata McGraw-Hill PublishingCo.2007
- 2. Radhakrishnan P, Subramanyan S. and Raju V., "CAD/CAM/CIM", 2nd Edition, New Age International (P) Ltd, New Delhi,2000

REFERENCES:

- 1. Chris McMahon and Jimmie Browne "CAD/CAM Principles", "Practice and Manufacturing management "Second Edition, Pearson Education, 1999.
- 2. William M Neumann and Robert F.Sproul "Principles of Computer Graphics", McGraw Hill Book Co. Singapore, 1989.
- 3. Donald Hearn and M. Pauline Baker "Computer Graphics". Prentice Hall, Inc, 1992.
- 4. Foley, Wan Dam, Feiner and Hughes "Computer graphics principles & practice" Pearson Education -2003
- 5. Mikell.P.Groover "Automation, Production Systems and Computer Integrated Manufacturing", Prentice Hall of India, 2008.

| ME 1613 | THERMAL ENGINEERING LABORATORY | L | Т | Р | С |
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OBJECTIVES:

- To study the valve timing, p-V diagram and performance of IC Engines
- To Study the characteristics of fuels/Lubricates used in IC Engines
- To study the heat transfer phenomena predict the relevant coefficient using implementation
- To study the performance of refrigeration cycle / components

LIST OF EXPERIMENTS

- 1. Valve Timing diagram of four stroke engine.
- 2. Port Timing diagram of two stroke engine.
- 3. Performance & Heat Balance Test on 4 stroke Diesel Engine.
- 4. Morse Test on Multi-cylinder Petrol Engine.
- 5. Determination of Flash Point and Fire Point of various fuels / lubricants
- 6. Determination of viscosity in Redwood Viscometer
- 7. Effectiveness of Parallel / counter flow heat exchanger.
- 8. Determination of Stefan Boltzmann constant.
- 9. Heat transfer from pin-fin apparatus (natural & forced convection modes)
- 10. Thermal conductivity measurement of pipe insulation using lagged pipe apparatus.
- 11. Determination of Thermal conductivity of insulating powder.
- 12. Determination of heat transfer coefficient under forced convection from a tube.
- 13. Determination of Thermal conductivity of composite wall.
- 14. Performance test on a reciprocating air compressor
- 15. Determination of COP of a refrigeration system

OUTCOMES:

Upon successful completion of the course, students will be able to:

- Conduct tests on heat conduction apparatus and evaluate thermal conductivity of materials.
- Conduct tests on natural and forced convective heat transfer apparatus and evaluate heat transfer coefficient.
- Conduct tests on radiative heat transfer apparatus and evaluate Stefan Boltzmann constant and emissivity.
- Conduct tests to evaluate the performance of parallel/counter flow heat exchanger apparatus and reciprocating air compressor.
- Conduct tests to evaluate the performance of refrigeration and air conditioning test rigs.
- Conduct tests to evaluate Convective and Radiative heat transfer.

| S.No. | NAME OF THE EQUIPMENT | Qty. |
|-------|--|-------|
| 1 | I.C Engine – 2 stroke and 4 stroke model | 1 SET |
| 2 | Apparatus for Flash and Fire Point | 1 No. |
| 3 | Redwood Viscometer apparatus | 1 No. |
| 4 | 4-stroke Diesel Engine with mechanical/electrical loading. | 1 No. |
| 5 | 4-stroke Diesel Engine with hydraulic loading. | 1 No. |
| 6 | Multi-cylinder Petrol Engine | 1 No. |
| 7 | Lagged pipe apparatus | 1 No. |
| 8 | Forced convection inside tube apparatus | 1 No. |
| 9 | Composite wall apparatus | 1 No. |
| 10 | Thermal conductivity of insulating powder apparatus | 1 No. |
| 11 | Stefan-Boltzmann apparatus | 1 No. |
| 12 | Emissivity measurement apparatus | 1 No. |
| 13 | Parallel/counter flow heat exchanger apparatus | 1 No. |
| 14 | Single/two stage reciprocating air compressor | 1 No. |
| 15 | Refrigeration test rig | 1 No. |
| | | |

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

ME1614

INNOVATIVE PROJECT

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OBJECTIVE:

• The main objective is to give an opportunity to the student to get hands on training in the fabrication of one or more components of a complete working model, which is designed by them.

GUIDELINE FOR REVIEW AND EVALUATION

The students may be grouped into 2 to 4 and work under a project supervisor. The device/ system/component(s) to be fabricated may be decided in consultation with the supervisor and if possible with an industry. A project report to be submitted by the group and the fabricated model, which will be reviewed and evaluated for internal assessment by a Committee constituted by the Head of the Department. At the end of the semester examination the project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the Head of the Department.

TOTAL: 60 PERIODS

OUTCOMES:

Upon successful completion of the course, students will be able to

- Design the machine element or the mechanical product.
- Fabricate the machine element or the mechanical product.
- Develop the solutions for specific real time problems.
- Apply the principles of engineering and codes of practice while developing solutions.
- Able to develop team work.
- Demonstrate the working model of the machine element or the mechanical product.

ME1605 DESIGN OF JIGS, FIXTURES AND PRESS TOOL L T P C

OBJECTIVES:

- To understand the functions and design principles of Jigs, fixtures and press tools
- To gain proficiency in the development of required views of the final design

UNIT I LOCATING AND CLAMPING PRINCIPLES:

Objectives of tool design-Function and advantages of Jigs and fixtures – Basic elements – principles of location – Locating methods and devices – Redundant Location – Principles of clamping – Mechanical actuation – pneumatic and hydraulic actuation Standard parts – Drill bushes and Jig buttons – Tolerances and materials used.

UNIT II JIGS AND FIXTURES

Design and development of jigs and fixtures for given component- Types of Jigs – Post, Turnover, Channel, latch, box, pot, angular post jigs – Indexing jigs – General principles of milling, Lathe, boring, broaching and grinding fixtures – Assembly, Inspection and Welding fixtures – Modular fixturing systems- Quick change fixtures.

UNIT III PRESS WORKING TERMINOLOGIES AND ELEMENTS OF CUTTING DIES

Press Working Terminologies - operations – Types of presses – press accessories – Computation of press capacity – Strip layout – Material Utilization – Shearing action – Clearances – Press Work Materials – Centre of pressure- Design of various elements of dies – Die Block – Punch holder, Die set, guide plates – Stops – Strippers – Pilots – Selection of Standard parts – Design and preparation of four standard views of simple blanking, piercing, compound and progressive dies.

UNIT IV BENDING AND DRAWING DIES

Difference between bending and drawing – Blank development for above operations – Types of Bending dies – Press capacity – Spring back – knockouts – direct and indirect – pressure pads – Ejectors – Variables affecting Metal flow in drawing operations – draw die inserts – draw beads- ironing – Design and development of bending, forming, drawing, reverse redrawing and combination dies – Blank development for axisymmetric, rectangular and elliptic parts – Single and double action dies.

UNIT V FORMING TECHNIQUES AND EVALUATION

Bulging, Swaging, Embossing, coining, curling, hole flanging, shaving and sizing, assembly, fine Blanking dies – recent trends in tool design- computer Aids for sheet metal forming Analysis – basic introduction - tooling for numerically controlled machines- setup reduction for work holding – Single minute exchange of dies – Poka Yoke.

TOTAL: 45 PERIODS

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OUTCOMES:

Upon successful completion of the course, students will be able to :

- Summarize the different methods of Locating Jigs and Fixtures and Clamping principles
- Design and develop jigs and fixtures for given component
- Discuss the press working terminologies and elements of cutting dies
- Distinguish between Bending and Drawing dies.
- Discuss the different types of forming techniques
- Design jigs, fixtures and press tool for different components and come up with the cost of making the tool.

TEXT BOOKS:

1. Joshi, P.H. "Jigs and Fixtures", Second Edition, Tata McGraw Hill Publishing Co., Ltd., New Delhi, 2010.

2. Joshi P.H "Press tools - Design and Construction", wheels publishing, 1996

REFERENCES:

- 1. ASTME Fundamentals of Tool Design Prentice Hall of India.
- 2. Design Data Hand Book, PSG College of Technology, Coimbatore.
- 3. Donaldson, Lecain and Goold "Tool Design", 5th Edition, Tata McGraw Hill, 2017.
- 4. Hoffman "Jigs and Fixture Design", Thomson Delmar Learning, Singapore, 2004.
- 5. Kempster, "Jigs and Fixture Design", Third Edition, Hoddes and Stoughton, 1974.
- 6. Venkataraman. K., "Design of Jigs Fixtures & Press Tools", Tata McGraw Hill, New Delhi, 2005.

| ME1606 | DESIGN FOR MANUFACTURE AND ASSEMBLY | L | Т | Р | С |
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OBJECTIVES:

To know the concept of design for manufacturing and assembly

To know the computer application in design for manufacturing and assembly.

UNIT I INTRODUCTION

General design principles for manufacturability - strength and mechanical factors, mechanisms selection, evaluation method, Process capability - Feature tolerances Geometric tolerances - Assembly limits -Datum features - Tolerance stacks.

UNIT II FACTORS INFLUENCING FORM DESIGN

Working principle, Material, Manufacture, Design- Possible solutions - Materials choice – Influence of materials on form design - form design of welded members, forgings and castings.

UNIT III COMPONENT DESIGN - MACHINING CONSIDERATION

Design features to facilitate machining - drills - milling cutters - keyways - Doweling procedures, counter sunk screws - Reduction of machined area- simplification by separation - simplification by amalgamation - Design for machinability - Design for economy - Design for clampability – Design for accessibility - Design for assembly – Product design for manual assembly - Product design for automatic assembly – Robotic assembly.

UNIT IV COMPONENT DESIGN – CASTING CONSIDERATION

Redesign of castings based on Parting line considerations - Minimizing core requirements, machined holes, redesign of cast members to obviate cores. Identification of uneconomical design - Modifying the design - group technology - Computer Applications for DFMA

UNIT V COMPONENT DESIGN – WELDING CONSIDERATION

Appraisal of various welding processes, factors in design of weldments, general design guidelines, pre and post treatment of welds, effects of thermal stresses in weld joints.

TOTAL: 45 PERIODS

OUTCOMES:

Upon successful completion of the course, students will be able to

- Understand the design principles for manufacturability
- Understand the factors influencing form design
- Apply the machining considerations when design the components for machinability
- Apply the casting considerations when design the components for casatability
- Apply the welding considerations when design the components for weldability
- Apply the design principles with manufacturing and assembly considerations.

TEXT BOOKS:

1. Harry Peck , Designing for manufacture, Pitman-1973

REFERENCES:

- 1. Boothroyd, G, 1980 Design for Assembly Automation and Product Design. New York, Marcel Dekker.
- 2. Boothroyd, G, Heartz and Nike, Product Design for Manufacture, Marcel Dekker, 1994.
- 3. Bralla, Design for Manufacture handbook, McGraw hill, 1999.

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4. Dickson, John. R, and Corroda Poly, Engineering Design and Design for Manufacture and Structural Approach, Field Stone Publisher, USA, 1995.

5. Fixel, J. Design for the Environment McGraw Hill., 1996.

- 6. Graedel T. Allen By. B, Design for the Environment Angle Wood Cliff, Prentice Hall. Reason Pub., 1996.
- 7. Kevin Otto and Kristin Wood, Product Design. Pearson Publication, (Fourth Impression) 2009.

| ME1607 | MATERIAL CHARACTERIZATION | L | Т | Р | С |
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OBJECTIVES:

- To expose the students with thermal, microscopic, electrical and spectroscopic methods of characterization.
- To study and understand the various Non-Destructive Evaluation and Testing methods, theory and their industrial applications.

OPTICAL METALLOGRAPHIC TECHNIQUES UNIT I

Importance of material characterization -classification of material characterization techniques -mechanical characterization process -measurement of hardness -fracture toughness through nano indentation -adhesion test-surface profilometry tribological studies of materials, Optical microscopic techniques. Macro examination-applications -metallurgical microscope principle, construction and working, metallographic specimen preparation.

UNIT II SURFACE ANALYSIS TECHNIQUES

Importance of surface characterization techniques-principle, working and applications of AFM, Surface area, pore volume measurements by B.E.T. method, Mercury porosimetry -Particle size measurement, Principle and working of SEM, STEM, TEM, imaging dark and bright field-specimen preparation techniques-merits and demerits-applications

UNIT III X RAY DIFFRACTION & ION BEAM TECHNIQUES

Characteristic X-ray spectrum-Bragg's Law-Diffraction methods-Laue method, rotating crystal method, powder method -X ray diffractometer-determination of crystal structure-lattice parameter-measurement of residual stress. Rutherford Backscattering Spectrometry (RBS), Secondary Ion Mass Spectroscopy, Electron backscatter diffraction (EBSD), Focused Ion Beam (FIB), elastic recoil detection analysis and nuclear reaction analysis

UNIT IV **OVERVIEW OF NDT**

NDT Versus Mechanical testing, Overview of the Non Destructive Testing Methods for the detection of manufacturing defects as well as material characterization. Relative merits and limitations, Various physical characteristics of materials and their applications in NDT, Visual inspection - Unaided and aided.

UNIT V SURFACE NDE METHODS

Liquid Penetrant Testing - Principles, types and properties of liquid penetrants, developers, advantages and limitations of various methods, Testing Procedure, Interpretation of results. Magnetic Particle Testing- Theory of magnetism, inspection materials Magnetization methods, Interpretation and evaluation of test indications, Principles and methods of demagnetization, Residual magnetism.

> TOTAL: 45 PERIODS

OUTCOMES:

Upon successful completion of the course, students will be able to

- categorize the various types of material characterization techniques
- illustrate the several types of surface characterization techniques
- visualize the importance of X-ray diffraction and Ion beam techniques
- elaborate the different methods of non-destructive testing
- summarize the various methods available for non-destructive evaluation
- describe the practical applications of several surface analysis techniques

TEXT BOOKS:

1. A. Mammoli, C. A. Brebbia and A. Klemm, Materials Characterization, WIT Press, 1stedition, (2011).

2. Baldev Raj, T.Jayakumar, M.Thavasimuthu "Practical Non-Destructive Testing", Narosa Publishing House, 2009.

REFERENCES:

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- 1. B. D. Cullity, Elements of X-ray Diffraction, Prentice Hall, 3rd edition, (2001).
- 2. V. A. Phillips, Modern Metallographic Techniques and their Applications, John Wiley & Sons, 1stedition, (1972).
- 3. V. T. Cherepin and A. K. Mallic, Experimental Techniques in Physical Metallurgy, Asia Publishing Company, (1967)
- 4. V. Voort, Metallography: Principle and practice, ASM International, (1999).
- 5. Paul E Mix, "Introduction to Non-destructive testing: a training guide", Wiley, 2nd Edition New Jersey, 2005
- 6. Charles, J. Hellier, Handbook of Non-destructive evaluation", McGraw Hill, New York 2001.
- 7. K. R. Hebbar, Basics of X-Ray Diffraction and its Applications, I.K. International Publishing House Pvt Ltd, (2007)
- 8. Ravi Prakash, "Non-Destructive Testing Techniques", 1st revised edition, New Age International Publishers, 2010

| ME1608 |
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RENEWABLE ENERGY SOURCES

OBJECTIVES:

The main learning objective of this course is to prepare the students for:

- Describing the current energy scenario in terms of conventional renewable energy and future plan.
- Applying the principle of various solar energy generating devices. •
- Applying the principle of various wind energy devices.
- Applying the principle of various bio energy devices. .
- Applying the principle of various ocean and geothermal energy devices

UNIT I **ENERGY SCENARIO**

Indian energy scenario in various sectors - domestic, industrial, commercial, agriculture, transportation and others - Present conventional energy status - Present renewable energy status - Potential of various renewable energy sources - Global energy status-Per capita energy consumption in various countries - Future energy plans.

UNIT II SOLAR ENERGY

Solar radiation - Measurements of solar radiation and sunshine - Solar thermal collectors - Flat plate and concentrating collectors - Solar thermal applications - Solar thermal energy storage - Fundamentals of solar photo voltaic conversion - Solar cells - Solar PV Systems - Solar PV applications

UNIT III WIND ENERGY

Wind data and energy estimation – Betz limit - Site selection for wind farms – characteristics Horizontal axis wind turbine – components - Vertical axis wind turbine - Wind turbine generators and its performance - Hybrid systems - Environmental issues - Applications.

UNIT IV **BIO-ENERGY**

Bio resources - Biomass direct combustion - thermochemical conversion - biochemical conversion - mechanical conversion -Biomass gasifier - Types of biomass gasifiers - Cogeneration - Carbonisation - Pyrolysis - Biogas plants - Digesters - Biodiesel production - Ethanol production - Applications.

UNIT V **OCEAN AND GEOTHERMAL ENERGY**

Small hydro - Tidal energy - Wave energy - Open and closed OTEC Cycles - Limitations - Geothermal energy - Geothermal energy sources - Types of geothermal power plants - Applications - Environmental impact.

TOTAL:

OUTCOMES:

Upon completion of this course, the students will be able to:

- Describe the current energy scenario in terms of conventional renewable energy and future plan.
- Apply the principle of various solar energy generating devices.
- Apply the principle of various wind energy devices.
- Apply the principle of various bio energy devices.
- Apply the principle of various ocean and geothermal energy devices.
- Understand techniques in direct energy conversion. •

TEXT BOOKS:

1. G.D. Rai, "Non-Conventional Energy Sources", Standard Publishers Distributors, 1992.

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45 PERIODS

2. John Twidell, Tony Weir, and Anthony D. Weir, Renewable Energy Resources, Taylor & Francis, 2006.

REFERENCES:

- 1. B.H. Khan, "Non-Conventional Energy Resources", McGraw Hill, 2009.
- 2. G.N. Tiwari, "Solar Energy Fundamentals Design, Modelling and applications", Alpha Science, 2015.
- 3. Godfrey Boyle, "Renewable Energy, Power for a Sustainable Future", Oxford University Press, 2012.
- 4. N.K. Bansal, Non-Conventional Energy Resources, Vikas Publishing House, 2014.
- 5. S.P. Sukhatme, "Solar Energy: Principles of Thermal Collection and Storage", Tata McGraw Hill, 2009.

| ME1609 | GAS DYNAMICS AND JET PROPULSION | L | Т | Р | С |
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OBJECTIVES:

- To understand the basic difference between incompressible and compressible flow. •
- To understand the phenomenon of shock waves and its effect on flow. To gain some basic knowledge about jet propulsion and Rocket Propulsion.

(Use of Standard Gas Tables permitted)

UNIT I FUNDAMENTALS OF COMPRESSIBLE FLOW

Basics of Thermodynamics & Fluid Mechanics, Energy and momentum equations of compressible fluid flows - Stagnation states, Mach waves and Mach cone - Effect of Mach number on compressibility.

UNIT II **ISENTROPIC FLOWS (VARIABLE AREA DUCT)**

Isentropic flow through variable area ducts, T-s and h-s diagrams for nozzle and diffuser flows, area ratio as a function of Mach number, mass flow rate through nozzles and diffusers, effect of friction in flow through nozzles.

FLOW THROUGH CONSTANT AREA DUCT **UNIT III**

One-dimensional flow with heat addition (Rayleigh flow) - analysis and working equations for perfect gas - thermal chocking reference state and Rayleigh table. One-dimensional flow with friction (Fanno flow) - analysis and working relations for perfect gas - limiting point - friction chocking - reference state and Fanno table.

NORMAL AND OBLIQUE SHOCKS UNIT IV

Governing equations - Normal and oblique shocks, causes and effects of shocks, Prandtl-Meyer and Rankin-Hugoniot equation equations - Applications.

UNIT V **PROPULSION SYSTEMS**

Fundamentals of jet & Rocket propulsion - Thrust power and propulsive efficiency - principle, propulsion cycle, power and efficiency calculations of Ram jet, Turbojet, Turbofan and Turbo Prop engines. Rocket engines - Propellants - Feeding systems - Ignition and combustion - Theory of rocket propulsion - Performance - Staging - Terminal and characteristic velocity -Applications - space flights

> TOTAL: **45 PERIODS**

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OUTCOMES:

Upon successful completion of the course, students will be able to

- Derive and apply equations for one-dimensional compressible flow from integral forms of the governing equations
- Determine geometric design parameters required to accelerate or decelerate an isentropic flow for a given type of nozzle or diffuser, operating under specified conditions
- Estimate the length of a one-dimensional constant area duct to achieve desired changes in properties via the effects of friction and heat transfer
- Evaluate changes in physical properties when a normal shock & oblique shock occurs
- Understand different components of aircraft propulsion systems using principles of thermodynamics
- Analyze different aircraft propulsion systems.

TEXT BOOKS:

1. John D. Anderson, Jr., "Modern Compressible Flow with Historical Perspective", McGraw-Hill, 3rd Edition 2004.

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2. Yahya S. M., "Fundamentals of Compressible Flow with Aircraft and Rocket Propulsion", New Age International (P) Ltd., 3rd Edition, 2003.

REFERENCES:

- 1. Robert D. Zucker, Oscar Biblarz, "Fundamentals of Gas Dynamics", Wiley India Pvt. Ltd., 2nd Edition, 2011.
- 2. Radhakrishnan E., "Gas Dynamics", Prentice Hall of India, New Delhi, 2006.
- 3. Saravanamuttoo, GFC Rogers, and Cohen. H, "Gas Turbine Theory", Pearson Education, 5th Edition, 2003.
- 4. Philip Hill, Carl Peterson, "Mechanics and Thermodynamics of Propulsion", Pearson Education, 2nd Edition, 2011.
- 5. Babu V., "Fundamentals of Gas Dynamics", John Wiley & Sons, 2015. 6. Oosthuizen P. H. and Carscallen W.E., "Compressible Fluid Flow", McGraw Hill, 1997. 6. Ganesan V., "Gas Turbine", Tata McGraw-Hill, New Delhi, 2005.

| ME1610 | OPERATIONS RESEARCH | L | Т | Р | С |
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OBJECTIVE:

To learn the basics of deterministic optimization tools.

UNIT I LINEAR MODELS

The phase of an operation research study – Linear programming – Graphical method– Simplex algorithm – Duality formulation - Sensitivity analysis.

UNIT II TRANSPORTATION MODELS AND NETWORK MODELS

Transportation Assignment Models -- Traveling Salesman problem-Networks models -- Shortest route -- Minimal spanning tree – Maximum flow models – Project network – CPM and PERT networks – Critical path scheduling – Sequencing models.

Inventory models – Economic order quantity models – Quantity discount models – Stochastic inventory models –

Multi product models – Inventory control models in practice.

UNIT IV

UNIT III

QUEUEING MODELS

DECISION MODELS

INVENTORY MODELS

Queueing models - Queueing systems and structures - Notation parameter - Single server and multi server models - Poisson input - Exponential service - Constant rate service - Infinite population - Simulation...

UNIT V

Decision models - Game theory - Two person zero sum games - Graphical solution- Algebraic solution- Linear Programming solution - Replacement models - Models based on service life - Economic life- Single / Multi variable search technique - Dynamic Programming - Simple Problem

> TOTAL: 45 PERIODS

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OUTCOMES:

Upon successful completion of the course, students will be able to

- Formulate and solve linear programming problems.
- Solve duality, transportation and assignment.
- Understand about Inventory Control Techniques •
- Understand and formulate Queuing Models
- Understand about the Decision models
- Formulate and optimize various problems. •

TEXT BOOKS:

1. G.Srinivasan., "Operations Research Principles and Applications", PHI, 2008. R.Panneerselvam, "Operations Research", PHI, 2006

REFERENCES:

Philips, Ravindran and Solberg, "Operations Research", John Wiley, 2002 Hamdy A Taha, "Operations Research - An Introduction", Prentice Hall India, 2003. Ronald L Rardin, "Optimisation in Operations Research", Pearson, 2003.

David R. Anderson, et al, "An Introduction to Management Science" - Quantitative approaches to Decision Making, Thomson, 2003. Hillier and Lieberman, "Introduction to Operations Research", TMH, 2000.

| ME1611 | TOTAL QUALITY MANAGEMENT | L | Т | Р | С |
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OBJECTIVES:

- Teach the need for quality, its evolution, basic concepts, contribution of quality gurus, TQM framework, Barriers and . Benefits of TQM.
- Explain the TQM Principles for application. •
- Define the basics of Six Sigma and apply Traditional tools, New tools, Benchmarking and FMEA.
- Describe Taguchi's Quality Loss Function, Performance Measures and apply Techniques like QFD, TPM, COQ and BPR.
- Illustrate and apply QMS and EMS in any organization.

INTRODUCTION UNIT I

Introduction - Need for quality - Evolution of quality - Definition of quality - Dimensions of product and service quality -Definition of TOM-- Basic concepts of TOM -- Gurus of TOM (Brief introduction) -- TOM Framework- Barriers to TOM --Benefits of TOM.

UNIT II **TOM PRINCIPLES**

Leadership - Deming Philosophy, Quality Council, Quality statements and Strategic planning- Customer Satisfaction -Customer Perception of Quality, Feedback, Customer complaints, Service Quality, Kano Model and Customer retention -Employee involvement - Motivation, Empowerment, Team and Teamwork, Recognition & Reward and Performance Appraisal--Continuous process improvement -Juran Trilogy, PDSA cycle, 5S and Kaizen - Supplier partnership - Partnering, Supplier selection, Supplier Rating and Relationship development.

TOM TOOLS & TECHNIQUES I UNIT III

The seven traditional tools of quality - New management tools - Six-sigma Process Capability- Bench marking - Reasons to benchmark, Benchmarking process, What to Bench Mark, Understanding Current Performance, Planning, Studying Others, Learning from the data, Using the findings, Pitfalls and Criticisms of Benchmarking - FMEA - Intent, Documentation, Stages: Design FMEA and Process FMEA.

UNIT IV **TOM TOOLS & TECHNIQUES II**

Quality circles – Quality Function Deployment (QFD) - Taguchi quality loss function – TPM – Concepts, improvement needs – Performance measures- Cost of Quality - BPR.

UNIT V **OUALITY MANAGEMENT SYSTEM**

Introduction-Benefits of ISO Registration-ISO 9000 Series of Standards-Sector-Specific Standards - AS 9100, TS16949 and TL Requirements-Implementation-Documentation-Internal Audits-Registration-ENVIRONMENTAL 9000---ISO 9001 MANAGEMENT SYSTEM: Introduction-ISO 14000 Series Standards-Concepts of ISO 14001-Requirements of ISO 14001-Benefits of EMS.

> TOTAL: 45 PERIODS

OUTCOMES:

Upon successful completion of the course, students will be able to

- Ability to apply TQM concepts in a selected enterprise.
- Ability to apply TQM principles in a selected enterprise.
- Ability to understand Six Sigma and apply Traditional tools, New tools, Benchmarking and FMEA.
- Ability to understand Taguchi's Quality Loss Function, Performance Measures and apply QFD, TPM, COQ and BPR.
- Ability to apply QMS and EMS in any organization. .
- Summarize the basic concepts in total quality management relevant to manufacturing and service sectors.

TEXT BOOKS:

1. Dale H.Besterfiled, Carol B.Michna, Glen H. Bester field, MaryB.Sacre, Hemant Urdhwareshe and RashmiUrdhwareshe, "Total Quality Management", Pearson Education Asia, Revised Third Edition, Indian Reprint, Sixth Impression, 2013.

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REFERENCES:

1. Joel.E. Ross, "Total Quality Management – Text and Cases", Routledge., 2017.

- 2. Kiran.D.R, "Total Quality Management: Key concepts and case studies, Butterworth Heinemann Ltd, 2016.
- 3. Oakland, J.S. "TQM Text with Cases", Butterworth Heinemann Ltd., Oxford, Third Edition, 2003.

4. Suganthi, L and Anand Samuel, "Total Quality Management", Prentice Hall (India) Pvt. Ltd., 2006.

ME1612 ENTREPRENEURSHIP AND DEVELOPMENT OF INDUSTRIES L Т Р С

OBJECTIVE:

Study of this subject provides an understanding of the scope of an entrepreneur, key areas of development, financial assistance by the institutions, methods of taxation and tax benefits, etc.

UNIT I **ENTREPRENEURSHIP**

Entrepreneur - Types of Entrepreneurs - Difference between Entrepreneur and Intrapreneur Entrepreneurship in Economic Growth, Factors Affecting Entrepreneurial Growth.

UNIT II MOTIVATION

Major Motives Influencing an Entrepreneur - Achievement Motivation Training, Self Rating, Business Game, Thematic Apperception Test – Stress Management, Entrepreneurship Development Programs – Need, Objectives.

UNIT III BUSINESS

Small Enterprises - Definition, Classification - Characteristics, Ownership Structures - Project Formulation - Steps involved in setting up a Business - Identifying, selecting a Good Business opportunity, Market Survey and Research, Techno Economic Feasibility Assessment- Preparation of Preliminary Project Reports - Project Appraisal - Sources of Information -Classification of Needs and Agencies.

UNIT IV FINANCING AND ACCOUNTING

Need - Sources of Finance, Term Loans, Capital Structure, Financial Institution, Management of working Capital, Costing, Break Even Analysis, Network Analysis Techniques of PERT / CPM - Taxation - Income Tax, Excise Duty - Sales Tax.

UNIT V SUPPORT TO ENTREPRENEURS

Sickness in small Business - Concept, Magnitude, Causes and Consequences, Corrective Measures - Government Policy for Small Scale Enterprises - Growth Strategies in small industry - Expansion, Diversification, Joint Venture, Merger and Sub Contracting.

> TOTAL: **45 PERIODS**

OUTCOMES:

Upon completion of the course, students will be able to

- Understand the concept of entrepreneurship •
- Understand self-rating processes and development methods •
- Understand good practices involved in business, survey and market analysis •
- Understand fundamentals of financing and accounting •
- Understand consequences and government policies.
- Gain knowledge and skills needed to run a business successfully.

TEXT BOOKS:

- 1. S.S.Khanka, "Entrepreneurial Development" S.Chand & Co. Ltd. Ram Nagar New Delhi, 1999.
- 2. Kurahko & Hodgetts, "Enterprenuership Theory, process and practices", Thomson learning 6th edition.

REFERENCES:

1. Hisrich R D and Peters M P, "Entrepreneurship" 5th Edition Tata McGraw-Hill, 2002.

2. Mathew J Manimala," Enterprenuership theory at cross roads: paradigms and praxis" Dream tech, 2nd edition 2006.

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3. Rabindra N. Kanungo, "Entrepreneurship and innovation", Sage Publications, New Delhi, 1998.

4. EDII "Faulty and External Experts – A Hand Book for New Entrepreneurs Publishers: Entrepreneurship Development", Institute of India, Ahmadabad, 1986.

| OME501 | INTERNAL COMBUSTION ENGINES | L | Т | Р | С |
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| OBJECTIVES: | | | | | |
| To study the conceTo impart the knowTo understand the or | lge in various manufacturing methods in developing automotive components. ppts of automobile engineering. wledge in various parts of automotive engine. concepts of fuel and transmission system. developments in automobile industries. | | | | |
| UNIT I INTROI | DUCTION TO IC ENGINES | | | | 9 |
| - | tandard cycles, Otto, Diesel, Stirling, Ericsson cycles, Actual cycle analysis, T Valve timing diagram, Rotary engines, stratified charge engine. | . wo | and f | our si | troke |
| UNIT II FUELS | | | | | 9 |
| | , important qualities of SI engine fuels, Rating of SI engine fuels, Important qu seous fuels, LPG, CNG, Biogas, Producer gas, Alternative fuels for IC engines | ıalitie | es of | CI er | ngine |
| UNIT III SI ENGI | INES | | | | 9 |
| Ignition delay, abnormal co | rements, Carburetor types, Theory of carburetor, MPFI, Combustion in SI en ombustion and its control, combustion chamber design for SI engines. Ignition sy on systems, ignition timing and spark plug, electronic ignition. | | | | |

UNIT IV CI ENGINES

Fuel injection in CI engines, Requirements, Types of injection systems, Fuel pumps, Fuel injectors, Injection timing. Combustion in CI engines, Ignition delay, Knock and its control, Combustion chamber design of CI engines. Scavenging in 2 Stroke engines, pollution, and its control.

UNIT V ENGINE TESTING & PERFORMANCE

Supercharging - Effect of altitude on power output, types of supercharging. Testing and Performance, Performance parameters, Basic measurements, blow by measurement, Testing of SI and CI engines.

TOTAL: 45 PERIODS

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OUTCOMES:

Upon successful completion of the course, students will be able to

- Understand basics and principles of engine operation.
- Gain knowledge on fuels used in IC engines.
- Understand the working principles and components of SI engines.
- Understand the working principles and components of CI engines.
- Learn methods to improve and test the performance of IC engines.
- Understand the concepts of automation and latest technologies in IC Engines.

TEXT BOOKS:

1. Ganesan, V, Internal Combustion Engines, Tata McGraw Hill Book Co., 2003.

- 1. B.P. Pundir Engine Combustion and Emission, Narosa Publishing House, 2011.
- 2. Domkundwar V, A Course in Internal Combustion Engines, Dhanpat Rai & Co. (P) Ltd, 2002.
- 3. John B. Heywood, Internal Combustion Engine Fundamentals, McGraw Hill Book, 1998.
- 4. Mathur, M.L., and Sharma, R.P., A Course in Internal Combustion Engines, Dhanpat Rai Publications Pvt.New Delhi-2, 1993.
- 5. Rajput R.K. Internal Combustion Engines, Laxmi Publications (P) Ltd, 2006.

OME502

OBJECTIVES:

Explaining the concepts of industrial robots with respect to its classification, specifications and coordinate systems. Reviewing the need and application of robots in different engineering fields.

ROBOTICS

- Exemplifying the different types of robot drive systems as well as robot end effectors.
- Applying the different sensors and image processing techniques in robotics to improve the ability of robots.
- Developing robotic programs for different tasks and analyzing the kinematics motions of robot.
- Implementing robots in various industrial sectors and interpolating the economic analysis of robots.

UNIT I **FUNDAMENTALS OF ROBOT**

Robot - Definition - Robot Anatomy - Co-ordinate Systems, Work Envelope Types and Classification- Specifications-Pitch, Yaw, Roll, Joint Notations, Speed of Motion, Pay Load- Robot Parts and their Functions-Need for Robots-Different Applications.

UNIT II **ROBOT DRIVE SYSTEMS AND END EFFECTORS**

Pneumatic Drives-Hydraulic Drives-Mechanical Drives-Electrical Drives-D.C. Servo Motors, Stepper Motors, A.C. Servo Motors-Salient Features, Applications and Comparison of all these Drives, End Effectors-Grippers-Mechanical Grippers, Pneumatic and Hydraulic- Grippers, Magnetic Grippers, Vacuum Grippers; Two Fingered and Three Fingered Grippers; Internal Grippers and External Grippers; Selection and Design Considerations.

UNIT III SENSORS AND MACHINE VISION

Transducers and Sensors - Sensor categories - Tactile array sensor - Touch - Proximity and range sensors - Compliance sensor - Sensing wrist forces - Sensing joint forces. Function of machine vision system - Sensing and Digitizing, Imaging devices -CCD - Videocon camera, Lighting techniques. Image Processing and Analysis - Image data reduction - segmentation - Feature extraction - Object recognition. Training of vision system.

UNIT IV **ROBOT KINEMATICS AND ROBOT PROGRAMMING**

Forward and Inverse kinematics of manipulator with two three Degrees of Freedom (DOF) in two-dimensional space - four degrees of freedom in three-dimensional space. (Elementary treatment only).Lead through Programming, Robot programming Languages-VAL Programming-Motion Commands, Sensor Commands, End Effector commands and simple Programs.

IMPLEMENTATION AND ROBOT ECONOMICS UNIT V

RGV, AGV; Implementation of Robots in Industries-Various Steps; Safety Considerations for Robot Operations - Economic Analysis of Robots

OUTCOMES:

Upon successful completion of the course, students will be able to

- Illustrate the specifications of Industrial Robots. Also Draw the rectangular, polar, cylindrical and jointed arm configurations and work volume of Industrial robots.
- Draw and Illustrate the robot drive systems such as hydraulic, pneumatic, and electrical as well as robot end effectors
- Apply the analog and digital sensors and image processing techniques in robotics to improve the ability of robots.
- Develop robotic programs for manufacturing related tasks and familiarize with the kinematics motions of robot.
- Examine the implementation of robots in various industrial sectors and interpolate the economic analysis of robots using Pay-back period, Rate of Return on Investment methods.
- Apply the basic engineering knowledge for the design of industrial manipulators.

TEXT BOOKS:

1. Fu. K.S, Gonzalez. R.C, Lee. C.S.G "Robotics - Control, Sensing, Vision, and Intelligence", McGraw Hill, 2015

2. Groover Mikell .P, "Industrial Robotics - Technology Programming and Applications", McGraw Hill, 2014.

REFERENCES:

1. Craig J.J., "Introduction to Robotics Mechanics and Control", Pearson Education, 2009.

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TOTAL: **45 PERIODS**

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- Deb S.R., "Robotics Technology and Flexible Automation" Tata McGraw Hill Book Co., 2013.
 Koren Y., "Robotics for Engineers", McGraw Hill Book Co., 1992
 Maja J Mataric, "The Robotics Primer "Universities Press. 2013.
 Robin R. Murphy "Introduction to AI Robotics" PHI Learning Private Limited, 2000.

| | STATISTICAL QUALITY CONTROL | L | ΤP | С |
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| | | 3 | 0 0 | 3 |
| OBJECTIVE | S: | | | |
| | impart knowledge to enable the students to design and implocess Control in any industry. | emer | nt Sta | atistical |
| • To | design and implement acceptance sampling inspection methods ir | n indu | istry. | |
| | | | | |
| UNIT I | QUALITY FUNDAMENTALS | | | 9 |
| Importance | e of quality- evolution of quality- definitions of quality- dimensions | ofqu | ality- | quality |
| control- qu | uality assurance- areas of quality- quality planning- quality object | ives a | and p | olicies- |
| quality cos | sts- economics of quality- quality loss function- quality Vs produce | ctivity | - Qu | ality Vs |
| reliability | | | | |
| | | | | |
| UNIT II | CONTROL CHARTS FOR VARIABLES | | | 9 |
| | riation- preliminary decisions- control limits and their computat | | | |
| | cation of X bar, R and S charts- warning and modified contro | | | |
| - | t for trend, - Comparison of process variation with specification lim | its- C | .C. ci | urve for |
| X bar chart | | | | |
| | | | | 1 - |
| UNIT III | STATISTICAL PROCESS CONTROL | | | 9 |
| | ability- process capability study using control charts- capability ev | aluat | ion- | Cp, Cpk |
| and Com | | | | • • |
| - | capability analysis using histogram and normal probability plot- m | | | pability |
| study- gau | ge capability study - setting statistical tolerances for components | s and | asse | pability mblies- |
| study- gau individual | | s and | asse | pability mblies- |
| study- gau | ge capability study - setting statistical tolerances for components | s and | asse | pability mblies- |
| study- gau individual chart. | ge capability study - setting statistical tolerances for components measurement charts- X-chart, moving average and moving range | s and | asse | pability mblies- ulti-vari |
| study- gau individual chart. UNIT IV | ge capability study - setting statistical tolerances for components measurement charts- X-chart, moving average and moving range CONTROL CHARTS FOR ATTRIBUTES | s and char | asse t, m | pability mblies- ulti-vari |
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• implement statistical process control and acceptance sampling procedures in manufacturing environment to improve quality of processes / products.

TEXTBOOKS:

- 1. Douglus C. Montgomery, "Introduction to Statistical Quality Control", Wiley-India, Seventh Edition, 2013.
- 2. Krishnaiah K.," Applied Statistical Quality Control and Improvement", PHI, 2014.

- 1. Amitava Mitra, "Fundamentals of Quality Control and Improvement", Wiley, Third Edition, 2008.
- 2. Dale H. Besterfield, Quality Control, Pearson Education Asia, Eigth Edition, 2008.
- 3. Eugene L. Grant and Richard S. Leaven Worth, "Statistical Quality Control", McGraw-Hill Education, Seventh Edition, 2000.
- 4. Besterfield D. H. (2009). Quality Control. 8th Edition. Ed. PrenticeHall.
- 5. Devor R. E., Chang T-H. and Sutherland J. W. (2006). Statistical Quality Design and Control. 2nd Edition. Ed. PrenticeHall.

| ME1702 | | POWER PLANT ENGINEERING | L | Т | Ρ | С |
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| | | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | | |
| in o ● Uno | peratir | an overview of power plants and detailing the role of Mecha og the different types of power plant and its maintenance. ding of Power Plant Economics, environmental and safety as ation. | | | - | |
| UNIT I | COAL | BASED THERMAL POWER PLANTS | | | | 9 |
| storage, Pu precipitatio | ulverize on (ES | ant -General layout – working-coal handling and its method d fuel handling system- Ash handling system- Gravity syste P) system- FBC Boilers-Feed water treatment- Mecha | m- | ele | ctr | ostatic |
| Advantage | s and d | | | | | ctnou, |
| | | isadvantages-limitations of Thermal power plant. | | | | |
| UNIT II | DIESE | isadvantages-limitations of Thermal power plant. | | | | 9 |
| | _ | | tio | n sy | /ste | 9 |
| General la | yout ar | L AND GAS TURBINE POWER PLANTS | | | | 9 em, air |
| General lavintake and | yout ar exhaus | L AND GAS TURBINE POWER PLANTS d Components of Diesel power plant- fuel system, lubrica | | | | 9 em, air |
| General lay intake and power plar | yout ar exhaus nt with | L AND GAS TURBINE POWER PLANTS Id Components of Diesel power plant- fuel system, lubrica t system, Site selection of diesel power plant and Comparative | e st | tud | y of | 9 m, air diesel |
| General law intake and power plar Gas turbing | yout ar exhaus nt with e powe | L AND GAS TURBINE POWER PLANTS d Components of Diesel power plant- fuel system, lubrica t system, Site selection of diesel power plant and Comparative steam power plant. | e st ycl | tud e ga | y of as t | 9 em, air diesel urbine |
| General law intake and power plar Gas turbing | yout ar exhaus nt with e powe nt, Com | L AND GAS TURBINE POWER PLANTS d Components of Diesel power plant- fuel system, lubrica t system, Site selection of diesel power plant and Comparative steam power plant. r plant- Schematic diagram & working of open and closed co ponents of Gas turbine power plant- Advantages -disadvanta | e st ycl | tud e ga | y of as t | 9 em, air diesel urbine |
| General lay intake and power plar Gas turbing power plar | yout ar exhaus nt with e powe nt, Com | L AND GAS TURBINE POWER PLANTS d Components of Diesel power plant- fuel system, lubrica t system, Site selection of diesel power plant and Comparative steam power plant. r plant- Schematic diagram & working of open and closed co ponents of Gas turbine power plant- Advantages -disadvanta | e st ycl | tud e ga | y of as t | 9 em, air diesel urbine |

Basics of Nuclear Engineering, Layout and subsystems of Nuclear Power Plants, Working of Nuclear Reactors: Boiling Water Reactor (BWR), Pressurized Water Reactor (PWR), CANada Deuterium- Uranium reactor (CANDU), Breeder - Safety measures for Nuclear Power plants.

UNIT IV POWER FROM RENEWABLE ENERGY

General layout and essential elements of Hydroelectric power plant and its working- Principle, Construction and working of Wind, Tidal, Solar Photo Voltaic (SPV), Solar Thermal, Geo Thermal and Biogas. Fuel Cell Basics – types – working and its performance.

UNIT V ENERGY, ECONOMIC AND ENVIRONMENTAL ISSUES OF POWER PLANTS

Load distribution parameters, Peak load, Base load, Load factor, Load curve, demand factor-Various factor affecting the operation of power plant- Power tariff methods-factors involved in fixing a tariff for power- Pollution control technologies in Waste Disposal Options for Coal and Nuclear Power Plants.

OUTCOMES:

TOTAL: 45 PERIODS

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On successful completion of this course, the student will be able to

- Explain the layout, construction and working of the components inside a thermal power plant.
- Explain the layout, construction and working of the components inside a Diesel, Gas and Combined cycle power plants.
- Explain the layout, construction and working of the components inside nuclear power plants.
- Explain the layout, construction and working of the components inside Renewable energy power plants.
- Explain the applications of power plants while extend their knowledge to power plant economics and environmental hazards.
- Apply their knowledge to audit the various power plants

TEXTBOOKS:

- 1. Nag. P.K., "Power Plant Engineering", Third Edition, Tata McGraw Hill Publishing Company Ltd., 2008
- Arora and Domkundwar ., "Power plant engineering" Eighth Edition, Dhanpat rai & CO (P) LTD

- 1. R K Rajput "A Text Book of Power Plant Engineering" Fifth Edition, Laxmi Publications.
- 2. El-Wakil. M.M., "Power Plant Technology", Tata McGraw Hill Publishing Company Ltd., 2010.
- 3. Godfrey Boyle, "Renewable energy", Open University, Oxford University Press in association with the Open University, 2004.
- 4. Thomas C. Elliott, Kao Chen and Robert C. Swanekamp, "Power Plant Engineering", Second Edition, Standard Handbook of McGraw Hill, 1998.

5. P K Das and A K Das "An Introduction to Thermal Power Plant Engineering and Operation" First Edition, Notion Press, 2018.

| ME1703 | MECHATRONICS | | L | т | Ρ | С |
|-------------|---|-----------|-----|------|------|---------|
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | | |
| • To | impart knowledge about the elements and techniques invo | lved in | N | Лe | chat | tronics |
| sys | tems. | | | | | |
| | understand the emerging field of automation. | | | | | |
| UNIT I | INTRODUCTION | | | | | 9 |
| | on to Mechatronics – Systems – Concepts of Mechatronics | | | | | |
| | ics – Emerging areas of Mechatronics – Classification of Mech | | | | | |
| | rs: Static and dynamic Characteristics of Sensor, Potent | | | | | |
| - | e sensors – Strain gauges – Eddy current sensor – Hall effect s | sensor | - | lei | mpe | rature |
| sensors – L | ight sensors | | | | | |
| UNIT II | MICROPROCESSOR AND MICROCONTROLLER | | | | | 9 |
| | on – Architecture of 8085 – Pin Configuration – Addressing M | odes – | Ins | str | ucti | |
| | gram of 8085 – Concepts of 8051 microcontroller – Block diag | | | | | |
| | <u>, </u> | | | | | |
| UNIT III | PROGRAMMABLE PERIPHERAL INTERFACE | | | | | 9 |
| Introductio | n – Architecture of 8255, Keyboard interfacing, LED display - | -interfa | ac | ing | , AD | C and |
| DAC interfa | ace, and Temperature Control – Stepper Motor Control – Traf | fic Con | tro | ol i | nter | face. |
| | | | | | | |
| UNIT IV | PROGRAMMABLE LOGIC CONTROLLER | | | | | 9 |
| | on – Basic structure – Input and output processing – Program | ming - | - N | ٧n | emo | onics – |
| Timers, co | unters and internal relays – Data handling – Selection of PLC. | | | | | |
| | | | | | | |
| | ACTUATORS AND MECHATRONIC SYSTEM DESIGN | | | | | 9 |
| | tepper and Servo motors – Construction – Working Princip | | | | | |
| | ges. Design process-stages of design process – Traditional and Case studies of Mechatronics systems – Pick and place Robot - | | | | | - |
| • | utomatic car park barrier. | - ciigiii | eı | via | nag | ement |
| System A | | | | | | |
| | ΤΟΤΑ | L: 4 | 5 | | PER | ODS |
| OUTCOME | | I | - | | | |
| On success | ful completion of this course, the student will be able to | | | | | |
| • Une | derstand the interdisciplinary applications of Electronics, Elect | rical, N | Лe | ch | anic | al and |
| Cor | nputer Systems for the Control of Mechanical, Electronic System | ems an | d | sei | nsor | |
| tec | nnology. | | | | | |
| • Un | derstand the architecture of Microprocessor and Microcontro | ller. | | | | |
| • Dis | cuss Programmable Peripheral Interface, Architecture of 8255 | PPI, ar | nd | va | riou | IS |
| dev | ice interfacing. | | | | | |

- Explain the architecture, programming and application of programmable logic controllers to problems and challenges in the areas of Mechatronic engineering.
- Discuss various Actuators for mechatronics applications.
- Design various Mechatronics system using the knowledge and skills acquired through the course.

TEXTBOOKS:

- 1. Bolton, "Mechatronics", Prentice Hall, 2008
- 2. Ramesh S Gaonkar, "Microprocessor Architecture, Programming, and Applications with the 8085", 5th Edition, Prentice Hall, 2008.

REFERENCES:

- 1. Bradley D.A, Dawson D, Buru N.C and Loader A.J, Mechatronics, Chapman and Hall, 1993.
- 2. Clarence W, de Silva, "Mechatronics" CRC Press, First Indian Re-print, 2013
- 3. Devadas Shetty and Richard A. Kolk, Mechatronics Systems Design, PWS publishing company, 2007.
- 4. Krishna Kant, Microprocessors and Microcontrollers, Prentice Hall of India, 2007.
- 5. Michael B.Histand and Davis G.Alciatore, Introduction to Mechatronics and Measurement systems, McGraw Hill International edition, 2007.

| ME 1720 | | COMPUTER AIDED ANALYSIS LABORATORY | L | Т | Ρ | С | | |
|--------------|---|---|--------|---------|-------|-------|--|--|
| | | | 0 | 0 | 4 | 2 | | |
| OBJECTIVE | S: | | | | | | | |
| | • | To give exposure to software tools needed to analyze engin | neerir | ig prol | blem | s. | | |
| | To expose the students to different applications of simulation and analysis | | | | | | | |
| | | tools. | | | | | | |
| | | LIST OF EXPERIMENTS | | | | | | |
| A. SIM | IULA | TION | | | | | | |
| 1.C/MATLA | NB ba | sics, Dealing with matrices, Graphing-Functions of one varial | ble an | d two | varia | ibles | | |
| 2. Use of C | /Mat | lab to solve simple problems in vibration | | | | | | |
| 3. Mechani | ism S | imulation using Multibody Dynamic software | | | | | | |
| | | | | | | | | |
| B. AN | ALYS | IS | | | | | | |
| 1. Force an | d Str | ess analysis using link elements in Trusses, cables etc. | | | | | | |
| 2. Stress ar | nd de | flection analysis in beams with different support conditions | 5. | | | | | |
| 3. Stress ar | nalys | is of flat plates and simple shells. | | | | | | |
| 4. Stress ar | nalys | is of axi – symmetric components. | | | | | | |
| 5. Thermal | stre | ss and heat transfer analysis of plates. | | | | | | |
| 6. Thermal | stre | ss analysis of cylindrical shells. | | | | | | |
| 7. Vibration | n ana | alysis of spring-mass systems. | | | | | | |
| 8. Model a | nalys | sis of Beams. | | | | | | |
| 9. Harmoni | ic, tra | ansient and spectrum analysis of simple systems. | | | | | | |
| | | TOTAL | : | 60 | PERI | ODS | | |
| OUTCOME | S: | | | | | | | |

Upon the completion of this course the students will be able to

- Simulate the working principle of air conditioning system, hydraulic and pneumatic cylinder and cam follower mechanisms using MATLAB.
- Analyze the stresses and strains induced in plates and brackets.
- Analyze the stresses and strains induced in beams.
- Analyze the stresses and strains in heat transfer problems.
- Calculate the natural frequency of 2D components and beams.
- Calculate the mode shape analysis of 2D components and beams.

LIST OF EQUIPMENT FOR A BATCH OF 30 STUDENTS

| S.No. | NAME OF THE EQUIPMENT | Qty. |
|-------|---|-------------|
| 1 | Computer Work Station | 15 |
| 2 | Printer | 01 |
| 3 | Multibody Dynamic Software Suitable for Mechanism | 15 LICENSES |
| | simulation and analysis | |
| 4 | C / MATLAB | 5LICENSES |

| ME172 | 21 | MECHATRONICS AND AUTOMATION LABORATORY | L | Т | Ρ | С | | | |
|------------|--|---|-------|------|------|-----|--|--|--|
| | | | 0 | 0 | 4 | 2 | | | |
| OBJECTIVE: | | | | | | | | | |
| • | To knov | the method of programming the microprocessor and Arduino. | | | | | | | |
| • | To unde | rstand the simulation of basic electrical, hydraulic & pneumati | c Sys | tem | s wh | ich | | | |
| | enable t | he students to understand the concept of mechatronics | | | | | | | |
| | | LIST OF EXPERIMENTS | | | | | | | |
| 1. | Program | nming of <i>Arduino UNO</i> | | | | | | | |
| 2. | Simulat | ion of Arduino Programs by using Tinkercad | | | | | | | |
| 3. | Traffic | ight interface. | | | | | | | |
| 4. | Steppe | r motor interface. | | | | | | | |
| 5. | Study c | f IOT. | | | | | | | |
| 6. | Study c | f hydraulic, pneumatic and electro-pneumatic circuits. | | | | | | | |
| 7. | Simulation of basic hydraulic, pneumatic and electrical circuits using software. | | | | | | | | |
| 8. | Introdu | ction to Networking using Cisco Packet Tracer | | | | | | | |
| | | TOTAL: | | 60 P | ERIC | DS | | | |
| OUTCO | MES: | | | | | | | | |
| Upon su | Upon successful completion of the course, students will be able to: | | | | | | | | |

- Demonstrate the functioning of mechatronics system with various pneumatic, hydraulic and electrical systems.
- Demonstrate the functioning of Arduino with the help of Tinkercad
- Demonstrate the Interfacing of stepper Motor and Traffic Light Kit.
- Gain knowledge about the basics of Internet of Things.
- Demonstrate the interfacing of Internet of things with Cisco Packet Tracer.

• Demonstrate the method of programming the microprocessor and *Arduino and* to understand the simulation of basic electrical, hydraulic & pneumatic Systems.

| S.No. | NAME OF THE EQUIPMENT | Quantity |
|-------|---|----------|
| 1 | Hydraulics and Pneumatics Systems Simulation Software | 10 |
| 2 | Microcontroller kit with stepper motor and drive circuit sets | 2 |
| 3 | Arduino UNO kits | 5 |
| 4 | Arduino IDE software | 10 |
| 5 | Traffic light interface. | 2 |
| 6 | Cisco Packet Tracer software | 10 |
| 7 | Tinkercad software | 10 |

| ME1722 | | COMPREHENSION | | L | Т | Ρ | C |
|--------------|--------|---|-------------|------|------|------|---------|
| | • | | | 0 | 0 | 2 | 0 |
| OBJECTIVE | S: | | | | | | |
| • To | enco | urage the students to comprehend the knowled | lge acquire | ed f | rom | h th | e first |
| Sen | neste | r to Sixth Semester of B.E Degree Course through | periodic ex | erci | se. | | |
| | | | | | | | |
| METHOD C | DF EV | ALUATION: | | | | | |
| The stude | nts v | vill be assessed 100% internally through weekl | y test witl | n ol | ojec | tive | e type |
| questions of | on all | the subject related topics | | | | | |
| | | | | | | | |
| | | | TOTAL: | 30 | P | PERI | ODS |
| OUTCOME | S: | | | | | | |
| On success | ful c | ompletion of this course, the student will be able to | 0 | | | | |
| | - | o understand and comprehend any given prob ring field. | lem relate | d to | m | ech | ianical |

PROFESSIONAL ELECTIVES

| ME1704 | | VIBRATION AND NOISE ENGINEERING | L | Т | Ρ | С |
|-------------------------|--------|--|------|-------|------|----------|
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | | |
| • To 1 | famil | iarize the students with the sources of vibration and noise in r | nac | hine | es. | |
| • To | make | e design modifications to reduce the vibration and noise to imp | ٥ro | /e li | fe (| of the |
| con | npon | ents. | | | | |
| UNIT I | FOI | RCED VIBRATIONS | | | | 9 |
| Introductio | on, ar | nalysis of forced vibration with constant harmonic excitation, | MF, | rot | ati | ng and |
| reciprocati | ing u | nbalances, excitation of support (Relative and absolute amplit | ude | es), | for | ce and |
| motion tra | nsmi | ssibility, energy dissipated due to damping and numerical pro | bler | ns. | | |
| | 1 | | | | | |
| UNIT II | 1 | MERICAL METHODS FOR MULTI DOF SYSTEMS | | | | 9 |
| | | rocal theorem, influence coefficients, Rayleigh's method, Dun | | • | | - |
| | | d, orthogonality principle, method of matrix iteration and r | num | erio | cal. | signal |
| analysis, dy | ynam | ic testing of machines and structures. | | | | |
| | | | | | | |
| | 1 | RATION MEASURING INSTRUMENTS AND WHIRLING OF SHA | - | | | 9 |
| | | nents, vibrometers, accelerometer, frequency measuring i | | | | |
| | | rling of shafts with and without damping. Introduction, Vil | | | | |
| - | | n isolation and motion isolation for harmonic excitation, pra | | | - | |
| vibration a | nalys | is, vibration isolation, Dynamic vibration absorbers and Vibrat | lon | dai | np | ers. |
| | три | | | | | • |
| _ | | ANSIENT VIBRATION OF SINGLE DEGREE-OF FREEDOM SYSTEM | | vcit | | 9 |
| | | ion, arbitrary excitation, Laplace transforms formulation, Puls response spectrum, Shock isolation. | e e | xcit | all | JII allu |
| Tise time, s | DITUCE | | | | | |
| | NO | ISE: SOURCES, ISOLATION AND CONTROL | | | | 9 |
| _ | | of noise on road and in industries, noise due to construction | en | uin | me | - |
| | | ances, industrial noise control, strategies-noise control at | | | | |
| | | enclosures), noise control along the path (with or withou | | | | |
| | | rs); noise control at the receiver, ear defenders, earpl | - | | | |
| | | dness; weighting networks; equivalent sound level, auditory | | | | |
| - | | e, exposure due to machines and equipment's; hearing c | | | | |
| | | teria, daily noise doze. | | | | |
| | | | | | | |
| | | TOTAL: | 45 | P | 'ER | IODS |
| OUTCOME | S: | | | | | |
| On success | sful c | ompletion of this course, the student will be able to | | | | |
| • Cha | aract | erize the single and multi-degrees of freedom systems subject | ed t | o fr | ee | and |
| ford | ced v | ibrations with and without damping. | | | | |
| App | oly th | e method of vibration measurements and its controlling. | | | | |
| • Det | termi | ne vibratory responses of SDOF and MDOF systems to harmor | nic, | per | iod | ic and |
| nor | n-per | iodic excitation. | | | | |

- Analyze the mathematical model of a linear vibratory system to determine its response.
- Obtain linear mathematical models of real-life engineering systems.
- Apply the principles of vibration and noise reduction techniques to real life engineering problems.

TEXTBOOKS:

- 1. Mechanical Vibrations S. S. Rao Pearson Education
- 2. Fundamentals of Mechanical Vibration S. Graham Kelly McGraw-Hill

REFERENCES:

- 1. Mechanical Vibrations G. K. Grover Nem Chand and Bros.
- 2. Theory of Vibration with Application William T. Thomson, Marie Dillon Dahleh, Chandramouli Pearson Education 5th edition
- 3. Mechanical Vibrations V. P. Singh Dhanpat Rai & Company
- 4. Mechanical Vibrations and Noise engineering Amberkar A.G. PHI
- 5. Vibrations and Acoustics Measurements and signal analysis, C Sujatha, Tata McGraw Hill

| ME1705 | CONCURRENT AND REVERSE ENGINEERING | L | Т | Ρ | С |
|------------|------------------------------------|---|---|---|---|
| | | 3 | 0 | 0 | 3 |
| OBIECTIVES | | | | | |

- To understand the principles behind the design of the product,
- To identify ways & methods to redesign and improve the performance of the existing products.

UNIT I INTRODUCTION

Extensive definition of Concurrent Engineering (CE), CE design methodologies, Review of CE techniques like DFM (Design for manufacture), DFA (Design for assembly), QFD (Quality function deployment), RP (Rapid Prototyping), TD (Total design), organizing for CE, CE toolbox, Collaborative product development

UNIT II **USE OF IT & DESIGN STAGE**

9 IT Support Solid modeling, product data management, Collaborative product commerce, expert systems, Software hardware component design. Lifecycle design of products, opportunities for manufacturing enterprises, Modality of Concurrent engineering design, Automated analysis idealization control, CE in optimal structural design, and Real-time constraints.

UNIT III **MANUFACTURING CONCEPTS & ANALYSIS**

Manufacturing competitiveness, Checking the design process, Conceptual design mechanism-Qualitative Physical approach, intelligent design for manufacturing system, JIT system, Low inventory, Modular, Modeling, and reasoning for computer-based assembly planning, Design of Automated manufacturing.

| UNIT IV | BASICS OF REVERSE ENGINEERING | |
|---------|-------------------------------|--|
|---------|-------------------------------|--|

9

Need of reverse engineering, Methodologies for Reverse Engineering, understanding of Reverse Engineering through examples, process for Reverse Engineering, Phases of Reverse Engineering, Conceptual System Reasons for Reverse Engineering, Difficulties in Reverse Engineering, Levels of abstraction: Application level, Functional level, Structural level

UNIT V REVERSE ENGINEERING METHODOLOGY & TOOLS

9

Detailed study of Reverse Engineering for Branch Specific learning, Dissemble the existing selected artefact/product / component/ process/ system to study technical aspects and design detail, Reverse engineering in various computer software/ application, Case Studies: Application & Implementation level

TOTAL: 45 PERIODS

OUTCOMES:

On successful completion of this course, the student will be able to

- Familiarize with the fundamentals of concurrent engineering and design methodologies
- Design the system with Artificial Intelligence and Lifecycle design of products
- Design an Automated manufacturing system
- Understanding Process of Reverse Engineering
- Understand various computer software and application in Reverse engineering
- Design complex shape product with suitable technique in Reverse Engineering methods

TEXTBOOKS:

- 1. Concurrent Engineering Fundamentals: Integrated Product Development-Prasad, Prentice Hall. Author: Biren Prasad ISBN: 0133969460, 9780133969467 Edition: 2, illustrated Publisher: Prentice Hall PTR, 1996
- 2. Reverse Engineering, Wills, Linda M., Newcomb, Philip (Eds.), Springer, 1996, ISBN 978-0-585-27477-53.

- 1. Integrated Product Development-Anderson MM and Hein, L. Berlin, Springer Verlag. 1987 Publication: Lundtofte
- 2. Successful Implementation of Concurrent Product and Process-Sammy G Sinha, Wiley 1993 ISBN: 0471285102, 9780471285106
- 3. V. Raja and K. Fernandes, Reverse Engineering: An Industrial Perspective, Springer-Verlag, 2008. ISBN: 978-1-84628-855-5.
- 4. K. Otto and K. Wood, Product Design: Techniques in Reverse Engineering and New Product Development, 1st edition, Prentice Hall, 2001. ISBN-13: 978-0130212719.
- Concurrent Engineering: Automation Tools and Technology-Andrew Kusaik, Wiley-Interscience; 1st edition (18 December 1992); Cbs Publishers & Distributors Pvt. Ltd 01149349026
- Reversing: Secret of Reverse Engineering, Eldad Eilam, Wiley Publishing, Inc. ISBN-13 978-0764574818 Edition 1st Publisher Wiley Publication date 15 April 2005

| ME1706 | | MICRO MACHINING AND NANOCOMPOSITES | L | | > | <u>C</u> |
|---|--|---|--|--|--|---|
| OBJECTIVE | c. | | 3 | 0 (|) | 3 |
| To i and To i | impar I theii famili | t knowledge on the techniques of micro-machining, mechanic r applications arize the principle behind fabrication of various types of nano- ramics | | - | | |
| | INT | RODUCTION | | | | 9 |
| | hanic | Micro-manufacturing, Features of Micro-Machining, Need a s of micromachining, minimum chip thickness, micro turning, n g. | | | | |
| | MIC | RO MACHINING | | | | 9 |
| Water Jet I | Micro | ro machining – Ultra Sonic Micro Machining – Abrasive Jet Mi Machining – Abrasive Water Jet Micro Machining – Micro tu mical Micro Machining – Electric discharge micro machining. | | | | - |
| | MIC | RO FORMING AND WELDING | | | | 9 |
| Micro extr and Roller | usion Impri | Micro and Nano structured surface development by Nano nting – Micro bending with LASER – LASER micro welding – El | | | | |
| Micro extr and Roller micro weld UNIT IV Definition properties composites nanocomp | usion Impri ling. NAN of na of r s, D osites | Micro and Nano structured surface development by Nano nting – Micro bending with LASER – LASER micro welding – El NO CERAMICS & METAL BASED NANOCOMPOSITES anocomposites - Nanofillers, Classification of nanofillers, Schanofillers - Types of nanocomposites, Metal-Oxide or Motifferent aspects of their preparation techniques, s, some simple preparation techniques and their new e | lecti Syntl Aeta Me | nesis I-Cer | an an | nd nic tal |
| Micro extr and Roller micro weld UNIT IV Definition properties composites nanocomp magnetic p | usion Impri ling. of na of r s, D osites prope | Micro and Nano structured surface development by Nano nting – Micro bending with LASER – LASER micro welding – El NO CERAMICS & METAL BASED NANOCOMPOSITES anocomposites - Nanofillers, Classification of nanofillers, Schanofillers - Types of nanocomposites, Metal-Oxide or Modifierent aspects of their preparation techniques, sc, some simple preparation techniques and their new e rties. | lecti Syntl Aeta Me | nesis I-Cer | an an | nd nd tal nd |
| Micro extr and Roller micro weld UNIT IV Definition properties composites nanocomp magnetic p UNIT V Preparatio | usion Impri ling. of na of r s, D osites orope POL n and | Micro and Nano structured surface development by Nano nting – Micro bending with LASER – LASER micro welding – El NO CERAMICS & METAL BASED NANOCOMPOSITES anocomposites - Nanofillers, Classification of nanofillers, Schanofillers - Types of nanocomposites, Metal-Oxide or Motifferent aspects of their preparation techniques, s, some simple preparation techniques and their new e | Syntl Aeta Me elect | nesis I-Cer etal-r rical | anne a | m fo 9 nd nic tal nd 9 ymer |
| Micro extr and Roller micro weld UNIT IV Definition properties composites nanocomp magnetic p UNIT V Preparatio | usion Impri ling. of na of r s, D osites orope POL n and | Micro and Nano structured surface development by Nanconting – Micro bending with LASER – LASER micro welding – El NO CERAMICS & METAL BASED NANOCOMPOSITES anocomposites - Nanofillers, Classification of nanofillers, Schanofillers - Types of nanocomposites, Metal-Oxide or Mutififerent aspects of their preparation techniques, s, some simple preparation techniques and their new e rties. YMER BASED NANOCOMPOSITES d characterization of di-block Copolymer based nanocomposites, and indust | Syntl Aeta Me elect | nesis I-Cer etal-r rical es; F poss | an an an an an an an an an an an | nd nic tal nd 9 ymer |
| Micro extr and Roller micro weld UNIT IV Definition properties composites nanocomp magnetic p UNIT V Preparatio carbon nar | usion Impri ling. of na of r s, D osites orope POL n and notub | Micro and Nano structured surface development by Nanconting – Micro bending with LASER – LASER micro welding – El NO CERAMICS & METAL BASED NANOCOMPOSITES anocomposites - Nanofillers, Classification of nanofillers, Schanofillers - Types of nanocomposites, Metal-Oxide or Moifferent aspects of their preparation techniques, s, some simple preparation techniques and their new e rties. YMER BASED NANOCOMPOSITES d characterization of di-block Copolymer based nanocomposites, and indust | ilecti Gyntl Meta Me elect | nesis I-Cer etal-r rical es; F poss | an an an an an an an an an an an | m fo 9 nd nic tal nd ymer lities |

TEXTBOOKS:

- 1. Jain V.K., "Introduction to Micro machining", Narosa Publishing House, 2011.
- 2. P. M. Ajayan, L.S. Schadler, P. V. Braun, "Nano-composites Science and Technology", 2006

- 1. Jain V. K., Micro Manufacturing Processes, CRC Press, Taylor & Francis Group, 2012
- 2. T.J. Pinnayain, G.W. Beall, "Polymer-Clay Nanocomposites", Wiley, New York, 2001.
- 3. N.B. Singh, "Nanocomposites", Jenny Stanford Publishing, 2022
- 4. Thomas M. Adams and Richard A. Layton, "Introduction MEMS, Fabrication and Application," Springer 2012.
- 5. Tai Ran Hsu, "MEMS & Micro systems Design and Manufacture" Tata McGraw Hill, New Delhi, 2002
- 6. Kaushik Kumar, Divya Zindani, Nisha Kumari, J. Paulo Davim, "Micro and Nano Machining of Engineering Materials", Springer Cham 2019

| ME1707 | | COMPUTATIONAL FLUID DYNAMICS | L | Т | Ρ | С |
|--------------|--------|---|-----|------|------|---------|
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | | |
| • To | intro | duce Governing Equations of viscous fluid flows and to intro | odu | ce i | านท | nerical |
| mo | delin | g and its role in the field of fluid flow and heat transfer | | | | |
| • To | enab | le the students to understand the various discretization me | eth | ods | , sc | lution |
| pro | cedu | res and turbulence modeling. | | | | |
| UNIT I | GO | VERNING EQUATIONS AND BOUNDARY CONDITIONS | | | | 9 |
| Basics of c | omp | utational fluid dynamics – Need of CFD as tool - Governing e | qua | tior | ns o | f fluid |
| dynamics - | - Cor | ntinuity, Momentum and Energy equations – Physical bound | ary | cor | ndit | ions – |
| | - | equations for Turbulent Flow - Turbulent-Kinetic Energy | | • | | ons – |
| Mathemat | ical b | ehaviour of PDEs on CFD - Elliptic, Parabolic and Hyperbolic ec | qua | tion | IS. | |
| | | | | | | |
| UNIT II | FIN | ITE DIFFERENCE AND FINITE VOLUME METHODS FOR DIFFUS | ON | | | 9 |
| Finite diffe | erenc | e method - forward, backward and central difference schen | nes | , ex | plic | it and |
| • | | ds. Properties of numerical solution methods. Stability | | ' | sis, | error |
| estimation | , diff | erence between the Finite Difference and Finite Volume meth | ods | • | | |
| | 1 | | | | | |
| UNIT III | | ITE VOLUME METHOD FOR CONVECTION DIFFUSION | | | | 9 |
| | | al steady convection and diffusion – Different schemes -C | | | | |
| • • | | liscretization schemes – Conservativeness, Boundedness, T | ran | spo | rtiv | eness, |
| Hybrid, Pov | wer-l | aw and Quick schemes. | | | | |
| | 1 | | | | | |
| UNIT IV | _ | W FIELD ANALYSIS | | | | 9 |
| | | ethods -Representation of the pressure gradient term and cor | | | • | |
| | - | d – Momentum equations – Pressure and Velocity correct | ion | s – | Pro | essure |
| Correction | equa | ition, SIMPLE algorithm and its variants. | | | | |
| | | | | | | |
| UNIT V | | RBULENCE MODELS AND MESH GENERATION | | | | 9 |

Turbulence Energy equations – one dimensional model, mixing length model, Two equation (k-E) models. Choice of grid, grid- oriented velocity components, Cartesian velocity components, staggered and collocated arrangements, adaptive grids.

TOTAL:

45

PERIODS

OUTCOMES:

On successful completion of this course, the student will be able to

- Derive the governing equations and boundary conditions for Fluid dynamics
- Analyze Finite difference and Finite volume methods for Diffusion
- Analyze Finite volume method for Convective diffusion
- Analyze Flow field problems
- Explain and solve the Turbulence models and Mesh generation techniques
- Apply the concepts learnt to solve a fluid dynamics problem using CAE software

TEXTBOOKS:

- 3. John D Anderson, Computational Fluid Dynamics The Basics with Applications , McGraw Hill, New Delhi, 2010.
- 4. Muralidhar K. and Sundararajan T., —Computational Fluid Flow and Heat Transfer||, Narosa Publications, 2009.

- 6. Patankar, S.V. "Numerical Heat Transfer and Fluid Flow", Hemisphere Publishing Corporation, 2004.
- 7. Chung, T.J., "Computational Fluid Dynamics", Cambridge University, Press, 2002.
- 8. Ghoshdastidar P.S., "Heat Transfer", Oxford University Press, 2005
- 9. Muralidhar, K., and Sundararajan, T., "Computational Fluid Flow and Heat Transfer", Narosa Publishing House, New Delhi, 1995.
- 10. Prodip Niyogi, Chakrabarty, S.K., Laha, M.K. "Introduction to Computational Fluid Dynamics", Pearson Education, 2005.
- 11. Anil W. Date, "Introduction to Computational Fluid Dynamics", Cambridge University Press, 2005

| ME1708 | | REFRIGERATION & AIR CONDITIONING L T P | | | | | | | |
|--|--|--|--|--|--|---|--|--|--|
| | | | | | | | | | |
| OBJECTIVE | OBJECTIVES: | | | | | | | | |
| con | To understand the underlying principles of operations in different Refrigeration & Ai conditioning systems and components. To provide knowledge on design aspects of Refrigeration & Air conditioning systems | | | | | | | | |
| UNIT I | INT | RODUCTION | | | | 9 | | | |
| Introduction to Refrigeration - Unit of Refrigeration and C.O.P Ideal cycles- Refrigerants | | | | | | | | | |
| Desirable properties – Classification. | | | | | | | | | |
| | | | | | | | | | |

| UNIT II | VAPOUR COMPRESSION REFRIGERATION SYSTEM | 9 |
|-----------|--|------------------|
| Vapor co | mpression cycle: p-h and T-s diagrams - deviations from theoretical cycle – sub | o cooling |
| and supe | er heating- effects of condenser and evaporator pressure on COP – problems. | |
| Equipme | nt's: Type of Compressors, Condensers, Expansion devices, Evaporators. | |
| | | |
| UNIT III | OTHER REFRIGERATION SYSTEMS | 9 |
| Working | principles of Vapour absorption systems and adsorption cooling systems – S | team jet |
| refrigera | tion- Ejector refrigeration systems- Thermoelectric refrigeration- Air refrige | eration - |
| Magneti | c - Vortex and Pulse tube refrigeration systems | |
| | | |
| UNIT IV | PSYCHROMETRIC PROPERTIES AND PROCESSES | 9 |
| Properti | es of moist Air-Gibbs Dalton law, Specific humidity, Dew point temperature, D | egree of |
| saturatic | on, Relative humidity, Enthalpy, Humid specific heat, wet bulb temperature, I | Ory bulb |
| tempera | ture, Psychrometric chart; Psychrometric of air-conditioning processes, mixing | ng of air |
| streams. | | |
| | | |
| UNIT V | AIR CONDITIONING SYSTEMS AND LOAD ESTIMATION | 9 |
| Air cond | itioning loads: Outside and inside design conditions; Heat transfer through st | ructure, |
| Solar rad | liation, Infiltration and ventilation, internal heat load, calculation of summer 8 | & winter |
| air condi | tioning load, Classifications, Layout of plants, Air Conditioning Systems with C | controls: |
| | ture, Pressure and Humidity sensors, Actuators & Safety controls. | |
| • | | |
| | TOTAL: 45 PE | RIODS |
| OUTCON | ΛΕS: | |
| On succe | essful completion of this course, the student will be able to | |
| | xplain the basic concepts of Refrigeration | |
| | xplain the Vapor compression Refrigeration systems and to solve problems | |
| | Discuss the various types of Refrigeration systems | |
| | alculate the Psychrometric properties and its use in psychrometric processes | |
| | xplain the concepts of Air conditioning and to solve problems | |
| | pply the knowledge of the refrigeration and air conditioning system principle | c |
| • A | | 5. |
| TEXTBO | | |
| | rora, C.P., "Refrigeration and Air Conditioning", 3rd edition, McGraw Hill, Ne | w Dolhi |
| | 010. | w Denn, |
| | toecker, W.F. and Jones J. W., "Refrigeration and Air Conditioning", McGraw F | |
| | velhi, 1986. | 1111, INC W |
| | | |
| REFEREN | | |
| | | |
| | ASHRAE Hand book, Fundamentals, 2010. | -الحميم بروس |
| | ones W.P., "Air conditioning engineering", 5th edition, Elsevier Butte leinemann, 2007. | rwortn- |
| 3. R | oy J. Dossat, "Principles of Refrigeration", 4th edition, Pearson Education Asia | a <i>,</i> 2009. |
| 4. B | allaney. P.L." Thermal Engineering", Khanna publishers, 24th Edition 2012. | |
| 5. K | othandaraman, C.P., Domkundwar. S and Domkundwar A.V.," A course in The | ermal |
| _ | | |

Engineering", Dhanpat Rai & Sons, 2016.

| ME1709 | | CRYOGENICS ENGINEERING | LT | ' P | С |
|---|---|---|---------------------------------------|---------------|--|
| | | | 3 0 | 0 | 3 |
| OBJECTIVE | S: | | | | |
| mai ● To f | terial famil | de the knowledge of evolution of low temperature science an s at low temperature. arize with various gas liquefaction systems and design aspects and transfer lines | - | - | |
| | 1 | RODUCTION TO CRYOGENIC SYSTEMS | | | 9 |
| | | ure properties of Engineering Materials, Mechanical prop | ortio | с. Т | |
| properties- | - Ele | ctric and magnetic properties – Cryogenic fluids and t Cryogenics: Applications in space, Electrical Power and Cutting | their | prop | perties. |
| | LIO | UEFACTION SYSTEMS | | | 9 |
| - | - | ule Thomson expansion, Adiabatic expansion, Linde Hampson | n Cycle | e. Cla | - |
| | | m, Magnetic Cooling, Stirling Cycle, Cryo Coolers. | | | |
| | GAS | S LIQUEFACTION SYSTEMS | | | 9 |
| | | oduction of low temperatures-General Liquefaction systems- | Liaue | facti | on |
| | | on. Hydrogen and Helium –Critical components of Liquefaction | • | | _ |
| | | | | | |
| | CRY | OGENIC REERIGERATION SYSTEMS & CRYOGENIC | | | 9 |
| Ideal Refri | INS gerat | OGENIC REFRIGERATION SYSTEMS & CRYOGENIC TRUMENTATION ion systems Refrigeration using liquids and gases as refrigera vorking media, Pressure flow-level and temperature measure | | - | |
| Ideal Refriguing solid | INS gerat s as v | TRUMENTATION | | - | erators |
| Ideal Refrig using solid heat excha | INS gerat s as v inger | TRUMENTATION ion systems Refrigeration using liquids and gases as refrigera vorking media, Pressure flow-level and temperature measure | | - | erators |
| Ideal Refrig using solid heat excha UNIT V Cryogenic cryogenic t | INS gerat s as v ingera ngera cry Stora temp | TRUMENTATION ion systems Refrigeration using liquids and gases as refrigera working media, Pressure flow-level and temperature measure is used in cryogenic systems Cryo pumping Applications TOGENIC FLUID STORAGE AND TRANSFER SYSTEMS ge vessels and Transportation, Thermal insulation and their eratures, Super Insulations, Vacuum insulation, Powder insul | ement | s. T | erators ypes of 9 ance at |
| Ideal Refrig using solid heat excha UNIT V Cryogenic cryogenic t fluid transf | INS gerat s as v ingera ingera CRY Stora temp fer sy | TRUMENTATION ion systems Refrigeration using liquids and gases as refrigera working media, Pressure flow-level and temperature measure is used in cryogenic systems Cryo pumping Applications TOGENIC FLUID STORAGE AND TRANSFER SYSTEMS ge vessels and Transportation, Thermal insulation and their eratures, Super Insulations, Vacuum insulation, Powder insul stems. | ement | orma , Cry | erators ypes of 9 ance at |
| Ideal Refrig using solid heat excha UNIT V Cryogenic cryogenic t fluid transf | INS gerat s as v ingerat s as v ingerat Stora temp fer sy | TRUMENTATION ion systems Refrigeration using liquids and gases as refrigeration vorking media, Pressure flow-level and temperature measures used in cryogenic systems Cryo pumping Applications OGENIC FLUID STORAGE AND TRANSFER SYSTEMS rege vessels and Transportation, Thermal insulation and their eratures, Super Insulations, Vacuum insulation, Powder insulstems. TOTAL: | ement perfo | orma , Cry | erators ypes of 9 ance at vogenic |
| using solid heat excha UNIT V Cryogenic cryogenic fluid transf OUTCOME The studen | INS gerat s as v ingerat s as v ingerat Stora temp fer sy fer sy fer sy Stora temp fer sy fer sy fer sy fer sy fer sy fer sy fer sy fer sy fer sy | TRUMENTATION ion systems Refrigeration using liquids and gases as refrigera working media, Pressure flow-level and temperature measure is used in cryogenic systems Cryo pumping Applications TOGENIC FLUID STORAGE AND TRANSFER SYSTEMS ge vessels and Transportation, Thermal insulation and their eratures, Super Insulations, Vacuum insulation, Powder insul stems. | ement perfo lation 45 | rs. Tr | erators ypes of 9 ance at ogenic |
| Ideal Refrig using solid: heat excha UNIT V Cryogenic i cryogenic t fluid transf OUTCOME The studen • 1 • 1 • 1 • 1 • 1 • 1 | INS gerat s as wingers s as wingers CRY Stora temp fer sy fer sy Stora temp fer sy fer sy Stora temp fer sy fer sy Stora temp fer sy Stora temp fer sy Unde Get cryog Apply Know | TRUMENTATION ion systems Refrigeration using liquids and gases as refrigeration working media, Pressure flow-level and temperature measures is used in cryogenic systems Cryo pumping Applications COGENIC FLUID STORAGE AND TRANSFER SYSTEMS rege vessels and Transportation, Thermal insulation and their eratures, Super Insulations, Vacuum insulation, Powder insulstems. Il be able to v the properties of material at cryogenic temperatures. rstand the concepts about various liquefaction systems. rstand the concepts about various gas liquefaction systems. rideas on cryogenic refrigeration systems, cryogenic instruction heat exchangers. v the cryogenic concept in fluid storage and transfer systems. | ement perfo lation 45 | rs. Tr | erators ypes of 9 ance at ogenic |

REFERENCES:

- 1. Klaus D.Timmerhaus and Thomas M.Flynn, Cryogenic Process Engineering, Plenum Press, New York, 1989.
- 2. Randal F.Barron, Cryogenic systems, McGraw Hill, 1986
- 3. J G Weisend II, Handbook of cryogenic engineering, Taylor and francis, 1998.
- 4. Thomas Flynn, Cryogenic Engineering, Revised and Expanded, Taylor & Francis, 2004
- Advances in Cryogenic Engineering: Proceedings of the 1968 Cryogenic Engineering Conference Case Western Reserve University Cleveland, Ohio August 19–21, 1968 by K. D. Timmerhaus Springer

| ME1710 | PRODUCT LIFE CYCLE MANAGEMENT | L | Т | Ρ | С |
|--------|-------------------------------|---|---|---|---|
| | | 3 | 0 | 0 | 3 |

OBJECTIVES:

The main learning objective of this course is to prepare the students for:

- Explaining the history, concepts and terminology of PLM and Applying the functions, features of PLM and different modules offered in commercial PLM/PDM tools.
- Implementing PLM/PDM approaches for industrial applications and Integrating PLM/PDM with other applications.

UNIT I INTRODUCTION TO PLM

Introduction to PLM, Need for PLM, opportunities of PLM, Different views of PLM - Engineering Data Management (EDM), Product Data Management (PDM), Collaborative Product Definition Management (CPDM), Collaborative Product Commerce (CPC), Product Lifecycle Management (PLM). PLM/PDM Infrastructure – Network and Communications, Data Management, Heterogeneous data sources and applications.

UNIT II PLM/PDM FUNCTIONS AND FEATURES

User Functions – Data Vault and Document Management, Workflow and Process Management, Product Structure Management, Product Classification and Programme Management. Utility Functions – Communication and Notification, data transport, data translation, image services, system administration and application integration.

UNIT III DETAILS OF MODULES IN A PDM/PLM SOFTWARE

Case studies based on top few commercial PLM/PDM tools

UNIT IV ROLE OF PLM IN INDUSTRIES

Case studies on PLM selection and implementation (like auto, aero, electronic) - other possible sectors, PLM visioning, PLM strategy, PLM feasibility study, change management for PLM, financial justification of PLM, barriers to PLM implementation, ten step approach to PLM, benefits of PLM for-business, organization, users, product or service, process performance

UNIT V BASICS ON CUSTOMISATION/INTEGRATION OF PDM/PLM SOFTWARE

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PLM Customization, use of EAI technology (Middleware), Integration with legacy data base, CAD, SLM and ERP.

OUTCOMES:

TOTAL: 45

5 PERIODS

Upon completion of this course, the students will be able to:

- Explain the history, concepts and terminology of PLM
- Apply the functions and features of PLM/PDM
- Apply different modules offered in commercial PLM/PDM tools
- Implement PLM/PDM approaches for industrial applications.
- Integrate PLM/PDM with other applications.
- Analyse the case studies.

TEXTBOOKS:

- 1. AnttiSaaksvuori and AnselmiImmonen, "Product Lifecycle Management", Springer Publisher, 2008.
- 2. Michael Grieves, "Product Life Cycle Management", Tata McGraw Hill, 2006.

- 1. ArieKarniel and Yoram Reich, Managing the Dynamics of New Product Development Processes: A New Product Lifecycle Management Paradigm, Springer, 2011.
- 2. IvicaCrnkovic, Ulf Asklund and AnnitaPerssonDahlqvist, "Implementing and Integrating Product Data Management and Software Configuration Management", Artech House Publishers, 2003.
- 3. John Stark, "Global Product: Strategy, Product Lifecycle Management and the Billion Customer Question", Springer Publisher, 2007.
- 4. John Stark, "Product Lifecycle Management: 21st Century Paradigm for Product Realisation", Springer Publisher, 2011.
- 5. Kevin Roebuck, Product Lifecycle Management (PLM): High-impact Strategies What You Need to Know: Definitions, Adoptions, Impact, Benefits, Maturity, Vendors, Emereo, 2011.

| ME1711 | | TRIBOLOGY IN DESIGN | L | Т | Ρ | С |
|----------------------|-----------------------|--|------|------|-----|---------|
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | | |
| com cha • To u | npon racte unde | art knowledge in the friction, wear and lubrication aspe ents and understand the material properties which influence eristics of surfaces. rstand the analytical behavior of different types bearings and d n analytical /theoretical approach | e th | e tr | ibo | logical |
| UNIT I | SUI | RFACE INTERACTION AND FRICTION | | | | 7 |

Topography of Surfaces – Surface Features-Properties and measurement – Surface interaction – Adhesive Theory of Sliding Friction –Rolling Friction-Friction properties of metallic and non-metallic materials – friction in extreme conditions –Thermal considerations in sliding contact

UNIT II WEAR AND SURFACE TREATMENT

Types of wear – Mechanism of various types of wear – Laws of wear – Theoretical wear models-Wear of Metals and Nonmetals – Surface treatments – Surface modifications – surface coatings methods- Surface Topography measurements –Laser methods – instrumentation -International standards in friction and wear measurements

UNIT III LUBRICANTS AND LUBRICATION REGIMES

Lubricants and their physical properties- Viscosity and other properties of oils –Additives-and selection of Lubricants- Lubricants standards ISO, SAE, AGMA, BIS standards – Lubrication Regimes –Solid Lubrication-Dry and marginally lubricated contacts- Boundary Lubrication-Hydrodynamic lubrication — Elasto and plasto hydrodynamic - Magneto hydrodynamic lubrication – Gas lubrication.

UNIT IV THEORY OF HYDRODYNAMIC LUBRICATION

Reynolds Equation-Assumptions and limitations-one- and two-dimensional Reynolds Equation-Reynolds and Sommerfeld boundary conditions- Pressure wave, flow, load capacity and friction calculations in Hydrodynamic bearings-long and short bearings-Pad bearings and Journal Bearings-Squeeze film effects-Thermal Considerations.

UNIT V HIGH PRESSURE CONTACTS

Rolling contacts of Elastic solids- contact stresses – Hertzian stress equation- Spherical and cylindrical contacts-Contact Fatigue life- Oil film effects - Film shape within and outside contact zones-Film thickness and friction calculation.

TOTAL: 45 PERIODS

OUTCOMES:

On successful completion of this course, the student will be able to

- familiarize with the surface interaction and friction.
- understand the concepts of wear and surface treatment.
- decide the lubricants and lubrication regimes for different operating conditions.
- understand the concepts of hydrodynamic and hydrostatic lubrication.
- gaining knowledge in the high-pressure contacts and the elasto hydrodynamic lubrication.
- apply the concepts to the industrial problems and identify the wear and friction.

TEXTBOOKS:

- 1. G.W. Stachowiak and A.W. Batchelor, Engineering Tribology, Butterworth Heinemann, UK, 4th Edition, 2013.
- S.K. Basu, S.N. Sengupta and B.B. Ahuja, Fundamentals of Tribology, Prentice –Hall of India Pvt Ltd, New Delhi, 1st edition, 2010.

REFERENCES:

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- 1. Bharat Bhushan, Introduction to Tribology, John Wiley & Sons, New York, 2nd edition, 2013.
- 2. Harish Harani, Fundamentals of Engineering Tribology, Cambridge, 1st edition, 2017.
- 3. Michael M. Khonsari and E. Richard Booser, Applied Tribology Bearing Design and Lubrication, United Kingdom: Wiley, 3rd revised edition, 2017.
- 4. R. Gohar and H. Rahnejat. Fundamentals of Tribology, World Scientific Publishing Company, 3rd Edition, 2018.

5. Williams J.A., Engineering Tribology, Oxford University Press, 1994.

| ME1712 | ADVANCED FINITE ELEMENT ANALYSIS | L | Т | Ρ | С |
|-------------|---|------------|----------|-------|----------------|
| | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | |
| • To | develop a thorough understanding of the advanced finite e | lem | ent | ar | nalysis |
| tech | iniques with an ability to effectively use the tools of the analysis. | | | | |
| • To s | olve the practical problems arising in engineering design. | | | | |
| | | | | | |
| UNIT I | BENDING OF PLATES AND SHELLS | | | | 9 |
| | lasticity Equations – Bending of Plates and Shells – Finite Element | | | | |
| Plate and S | hell Elements - Conforming and Non-Conforming Elements – CO an | id C | 1 C | onti | nuity |
| Elements – | Degenerated shell elements- Application and Examples | | | | |
| | | | | | |
| UNIT II | NON-LINEAR PROBLEMS | | | | 9 |
| Introductio | n – Iterative Techniques – Material non-linearity – Elasto Plastic | ity | – P | last | icity – |
| | icity – Geometric Non linearity – large displacement Formu | latio | on | –So | lution |
| procedure | Application in Metal Forming Process and Contact Problems. | | | | |
| | | | | | |
| UNIT III | DYNAMIC PROBLEM | | | | 9 |
| | ulation – Free, Transient and Forced Response – Solution Procedu | | | • | |
| | bspace Iterative Technique – Response analysis-Houbolt, Wils | | | | |
| | Explicit & Implict Methods- Lanchzos, Reduced method for la | irge | siz | e s | ystem |
| equations | | | | | |
| | | | | | |
| | FLUID MECHANICS AND HEAT TRANSFER | | - | | 9 |
| - | Equations of Fluid Mechanics – Solid structure interaction | | | | |
| • | ible Flow – Potential Formulations – Slow Non-Newtonian Flo | - W | - N | /leta | al and |
| Polymer Fo | rming – Navier Stokes Equation – Steady and Transient Solution. | | | | |
| | | | | | |
| | | | <u>.</u> | | - |
| Error norm | s and Convergence rates – h-refinement with adaptivity – Adaptive | e re | tine | me | nt |
| | | | _ | | |
| | | 45 | P | ERI | UDS |
| | | | | | |
| OUTCOME | | e re 45 | | | 9 nt ODS |

- Understand the Finite Element Formulation of Plate and Shell Elements and its application.
- Gain knowledge in material & geometric non-and plasticity.
- Solve problems under dynamic conditions by applying various techniques.
- Arrive at the solutions for fluid mechanics and heat transfer problems.
- Acquire knowledge in error norms, convergence rates and refinement.
- Solve the real-world engineering problems using FEA.

TEXTBOOKS:

- 1. S.S.Rao, "Finite Element Analysis", 2002 Edition.
- 2. Reddy J.N., "An Introduction to the Finite Element Method", Third Edition, McGraw Hill, International Edition, 2005.

REFERENCES:

 Bathe K.J., "Finite Element Procedures in Engineering Analysis", Prentice Hall, 1990.
 Cook R.D., "Concepts and Applications of Finite Element Analysis", John Wiley and Sons Inc., New York, 1989.

3. Zienkiewicz, O.C. and Taylor, R.L., "The Finite Element Method", Fourth Edition, Volumes 1&2, McGraw Hill International Edition, Physics Services, 1991.

4. Chandrupatla T. R., 'Finite Elements in Engineering', Pearson Edition, 2011, 4th Edition.

5. K. H. Huebner, D. L. Dewhirst, D. E. Smith and T. G. Byron, 'The Finite Element Method for Engineers', John Wiley & Sons Inc., New York, 2001, 4th Edition

| ME1713 | OP' | TIMIZATION TECHNIQUES FOR ENGINEERING SYSTEMS | L | Т | Ρ | С |
|--------------------|---------|--|------|------|------|---------|
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVES: | | | | | | |
| • To in | npart | knowledge on various categories of existing engineerin | gр | rob | len | is and |
| soluti | ons to | such problems through various optimization techniques a | nd a | эрр | roa | ches. |
| • To e | nable | students to learn different approaches of optimizing | (m | axir | niz | ing or |
| minin | nizing) | an engineering problem or a function. | | | | |
| UNIT I | INTR | ODUCTION | | | | 9 |
| Classification | ofo | ptimization problems, concepts of design vector, Des | sign | со | nst | raints, |
| constrains su | ırface, | objective function surface and multi-level optimization, p | bara | me | tric | linear |
| programming | g | | | | | |
| | | | | | | |
| UNIT II | LINE | AR PROGRAMMING | | | | 9 |
| Linear progra | ammin | g methods for optimum design: Review of Linear programn | ning | ; me | etho | ods for |
| optimum de | sign - | - Post optimality analysis – Application of LPP models | s in | de | esig | n and |
| manufacturir | ng. | | | | | |
| | | | | | | |
| UNIT III | NON | -LINEAR OPTIMIZATION | | | | 9 |
| Unconstraine | ed one | e variable and multi variable optimization, KKT Conditio | ons, | Со | nst | rained |
| optimization | , Qua | dratic programming, Convex programming, Separable | e p | rog | ran | nming, |
| Geometric p | rogram | nming, Non-Convex programming | | | | |
| | | | | | | |

| | V | OPTIMIZATION A | LGORITHMS | | | | 9 |
|--------|-----------|----------------------|------------------|---------------|---------------------------------------|-----------|-----------------|
| Optim | ization | algorithms for sol | lving unconst | trained optir | nization probler | ns – G | radient based |
| netho | od: Cau | hy's steepest des | cent method, | , Newton's r | nethod, Conjuga | ate grad | lient method. |
| Optim | ization | algorithms for so | lving constra | ined optimiz | zation problems | - dire | ct methods – |
| penalt | ty func | tion methods – | steepest de | escent meth | nod – Enginee | ring ap | plications of |
| constr | rained a | nd unconstrained | algorithms. | | | | |
| | | | | | | | |
| י דואע | V | MODERN METHO | DDS OF OPTIM | VIZATION | | | 9 |
| Mode | rn meth | ods of Optimizatio | on: Genetic Al | lgorithms – S | Simulated Annea | aling – A | Ant colony |
| optim | ization - | - Tabu search — Ne | eural-Networl | k based Opti | mization – Fuzzy | y optim | ization |
| echni | iques – J | Applications. | | | | | |
| | | | | | T | | |
| | | | | | TOTAL: | 45 | PERIODS |
| OUTC | OMES: | | | | | | |
|)n su | ccessful | completion of this | s course, the | student will | be able to | | |
| • | The st | udents will be able | e to classify or | ptimization r | problems. | | |
| • | | stand the Linear p | , , | • • | | | |
| • | | stand the Optimiz | | | •• | ications | |
| • | | the unified and e | 0 | | 0 0 11 | | |
| • | | | | | as well as the | general | principles of |
| | | s soft computing t | - | | | | |
| • | | p Soft skills to sol | • | • | | | |
| ٠ | Implei | nent nontradition | nal optimizati | ion techniqu | es like swam, a | ant colo | ony and fuzzy |
| | systen | 15. | | | | | |
| | | | | | | | |
| EXTB | BOOKS: | | | | | | |
| 1. | Engine | ering Optimizatio | n Theory and | Practice, S.S | S.Rao, New Age | Interna | tional (P) Ltd, |
| | Publis | ners | | | | | |
| 2. | Deb K. | - 'Optimization for | or Engineering | g Design Alg | orithms and Exa | mples' | – PHI – 2000 |
| | | | | | | | |
| ₹EFER | ENCES: | | | | | | |
| 1. | Christ | os H. Papadimitrio | u, Kenneth St | teiglitz, Com | binatorial Optim | ization | , PHI 2006 |
| | | k S.Hillier and G.J. | • | • | • | | |
| | | . 1995. | , | | • | | |
| 3. | | | ization for Fn | gineering De | | | |
| | • | , , , | LACION IOI LIN | | sign" PHI 2003 | | |
| 4. | | 1 an - Finnps - 301 | hara "Onorat | 0 0 | esign", PHI,2003 | | tica" John |
| F | whey | India 2006 | lberg, "Operat | 0 0 | esign", PHI,2003 ch – Principles a | | ctice", John |
| 5. | A reason | India, 2006. | 0, 1 | itions Resear | ch – Principles a | nd Prac | · |
| - | | J. – 'Introduction t | 0, 1 | itions Resear | ch – Principles a | nd Prac | · |
| - | - 2004 | J. – 'Introduction t | to Optimizatio | on Design' – | ch – Principles a Elsevier Academ | nd Prac | s, New Delhi |

- 6. Saravanan R. 'Manufacturing Optimization through Intelligent Techniques' Taylor & Francis (CRC Press) 2006
- 7. Hardley G. -'Linear Programming' Narosa Book Distributors Private Ltd. 2002

| ME1714 | | ADDITIVE MANUFACTURING | L | ТР | С |
|---|---------------------------------|--|---------------------------------------|--------------------------|--------------------|
| | T | | 3 | 0 0 | 3 |
| OBJECTIVE | | | | | |
| env • To f | vironn famili | t knowledge on the principle, methods, possibilities and limit nental effects of various additive manufacturing technologies arize the characteristics of the different materials that are em dditive manufacturing technologies | | | vell as |
| UNIT I | INT | RODUCTION | | | 6 |
| Process Ch | – Ne nain- | ed - Development of Additive Manufacturing Technology Classification – Rapid Prototyping- Rapid Tooling – Rapid I nefits – Small Case studies | | • | |
| UNIT II | | JID AND SOLID BASED RAPID PROTOTYPING SYSTEMS | | | 10 |
| application Stereo lith application | ns, Lar hogra ns, Se | RP systems, Fusion Deposition Modeling – Principle– proc ninated Object Manufacturing– Principle– process parameter phy systems– Principle– process parameters, process–p lective Laser Sintering (SLS) - Direct Metal Sintering (DMLS) n- Principle– process parameters–applications-Solid ground c | rs — a proce) Sys ⁻ | applic ess d tem - | ations, etails– |
| UNIT III | DAT | A PREPARATION FOR RAPID PROTOTYPING TECHNOLOGIES | | | 10 |
| Wire frame support ge | e, sur nerat | D model preparation –Data requirements-geometric mode face and solid modelling-data formats- data interfacing, Part ion, support structure design, – Model Slicing and contour da ive slicing, –Tool path Generation. | Orie | ntatio | on and |
| UNIT IV | THR | EE-DIMENSIONAL PRINTING | | | 10 |
| capabilities strength ar Shape Dep | s, ma nd we positi Mar | nal Printing - Principle, basic process, physics of 3DP, types of terial system, solid based, liquid based and powder base akness, Applications and case studies. on Manufacturing (SDM): Introduction, basic process, shape id applications, Selective laser Melting, Electron Beam | ed 30 e dec | OP sy | stems, osition, |
| UNIT V | RAD | ID TOOLING | | | 9 |
| Classificatio | on: So | oft tooling, production tooling, Bridge tooling, direct and indir cations. Case studies – automotive, aerospace and electronic | | | ication |
| | | TOTAL: | 45 | PER | IODS |
| • exp | ful co lain t | mpletion of this course, the student will be able to he importance of Rapid Prototyping Technology iate liquid based and solid based Rapid Prototyping | | · | |

- design RPT solutions based on tooling
- understand the potential of various additive Manufacturing technologies to support design and manufacturing in industrial scenario

TEXTBOOKS:

- 1. Chua C.K., Leong K.F., and Lim C.S., "Rapid prototyping: Principles and applications", Third Edition, World Scientific Publishers, 2010
- 2. Ian Gibson, David W.Rosen, Brent Stucker "Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing" Springer, 2010

- 1. Liou L.W. and Liou F.W., "Rapid Prototyping and Engineering Applications: A tool box for prototype development", CRC Press, 2007.
- 2. Andreas Gebhardt, "Understanding Additive Manufacturing: Rapid Prototyping, Rapid Manufacturing" Hanser Gardner Publication 2011.
- 3. Liou L.W. and Liou F.W., "Rapid Prototyping and Engineering Applications: A tool box for prototype development", CRC Press, 2007.
- 4. Tom Page, "Design for Additive Manufacturing" LAP Lambert Academic Publishing, 2012.
- 5. Kamrani A.K. and Nasr E.A., "Rapid Prototyping: Theory and practice", Springer, 2006

| ME1715 | 715 HEAT TRANSFER IN NANOFLUIDS L T P | | | | | | | | |
|----------------------|--|---------------------|-------|-------|------|---------|--|--|--|
| | | | 3 | 0 | 0 | 3 | | | |
| OBJECTIVE | : | | | | | | | | |
| con anc • To l | understand the mechanisms of heat tran litions extended surfaces. earn the thermal analysis and sizing of heat ex eepts of mass transfer. (Use of standard HM ⁻ | changers and to unc | lerst | · | | | | | |
| UNIT I | NANO MATERIALS AND SYNTHESIS | | | | | 9 | | | |
| Basic classi | ication of Nano materials, Methods of prep | aration of nanomate | erial | 's, t | otto | om up | | | |
| and top-do | wn approaches, Nanoparticle synthesis techr | iques. | | | | | | | |
| | | | | | | | | | |
| UNIT II | CHARACTERIZATION TOOLS | | | | | 9 | | | |
| Characteriz | ation techniques- X-ray diffraction, Scannin | g Electron Microsco | pe, | Tra | nsn | nission | | | |
| Electron M | croscope, Optical Methods Fluorescence Mic | roscopy, Atomic For | ce N | /licr | osco | эру. | | | |
| | | | | | | | | | |
| UNIT III | NANOFLUIDS PREPARATION AND PROPERT | IES | | | | 9 | | | |
| | | | | | | | | | |

Preparation of Nanofluids, Ultra sonication, effect of surfactant, Thermo-Physical properties of Nano fluids, measurement of Specific heat, density, viscosity, thermal conductivity and pH value.

UNIT IV HEAT TRANSFER ENHANCEMENT

Convective heat transfer enhancement of Nanofluids - Mechanism of heat transfer- Brownian motion, Interfacial layer - Particle cluster.

UNIT V NANOFLUIDS FOR HEAT TRANSFER APPLICATIONS

Applications of Nanofluids for heat transfer enhancement in various heat exchangers, application to electronic cooling, Environmental and safety aspects.

TOTAL: 45 PERIODS

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OUTCOMES:

At the end of the course students will be able to

- Get a basic knowledge of Nano materials & preparation methods
- Gain knowledge about Characterization techniques of nanofluids
- Gain knowledge about heat transfer application of nanofluids
- Identify, formulate, and solve fluid dynamic and thermal engineering problems involving nanofluids.
- Have the capability to carry out a Nanofluid based research project and heat transfer application.
- Apply the knowledge of nanotechnology in fluids and thermal engineering.

TEXTBOOKS:

- 1. T.Pradeep, Nano: The Essentials, Tata Mc Graw- Hill Publishing Company Limited, New Delhi.
- 2. Ozisik, M.N., Heat Transfer A Basic Approach, McGraw-Hill, 1987

- 1. T.Pradeep, Nano: The Essentials, Tata Mc Graw- Hill Publishing Company Limited, New Delhi.
- 2. Sarit K Das ,Stephen U S Choi and Wenhua Yu, Nanofluids: Science and Technology, Wiley-Interscience (2007).
- 3. Guozhong Cao Nanostructures & Nanomaterials, Imperial College press, World Scientific Publishing Co. Pte. Ltd.(2003).
- 4. Greg F.Naterer,"Advanced Heat Transfer",CRC Press,2021.
- 5. Sarit K. Das, S. U. S. Choi, W. Yu, and T. Pradeep, Nanofluids: Science and Technology, John Wiley & Sons, 2008.

| ME1716 | FLEXIBLE MANUFACTURING SYSTEMS | L | Т | Ρ | С |
|-----------|--|---|---|---|---|
| | | 3 | 0 | 0 | 3 |
| OBJECTIVE | : | | | | |
| • Toi | troduce the concepts of Flexible Manufacturing systems | | | | |

• To familiarize the principles of group technology and justify flexible manufacturing systems

| UNIT I | PLANNING AND SCHEDULING OF FLEXIBLE MANUFACTURING SYSTEMS | 9 |
|--------------|--|----------|
| Introductio | on to Flexible Manufacturing System (FMS) - Development of Manufacturing Sy | stems |
| - Benefits - | Major Elements of FMS - Types of Flexibility - FMS Application and Flexibility - | Single |
| product, S | ingle batch, n-product, n-batch Scheduling Problem-Knowledge Based Sche | duling |
| System. | | |
| | | |
| UNIT II | COMPUTER CONTROL AND SOFTWARE FOR FLEXIBLE MANUFACTURING SYSTEMS | 9 |
| Introductio | on - Composition of FMS - Hierarchy of Computer Control - Computer Cont | trol of |
| Work Cent | er and Assembly Lines - FMS Supervisory Computer Control. Computer Softwa | are for |
| FMS - Intro | oduction, System Issues, Types of Software Specification and Selection - Trenc | ls. |
| | | |
| UNIT III | FLEXIBLE MANUFACTURING SYSTEM SIMULATION AND DATA BASE | 9 |
| Introductio | on-Application of Simulation -Simulation Process-Model of FMS - Simu | Ilation |
| | Limitation - Manufacturing Data Systems - Data Flow - FMS Database Systems | |
| | pr FMS Database. | |
| - | | |
| UNIT IV | GROUP TECHNOLOGY AND JUSTIFICATION OF FLEXIBLE MANUFACTURING SYSTEMS | 9 |
| Introductio | on - Matrix Formulation - Mathematical Programming Formulation - | Graph |
| | on - Knowledge Based System for Group Technology - Economic Justification o | • |
| | on of Possibility Distributions in FMS Systems -Justification. | |
| | , , , | |
| UNIT V | IMPLEMENTATION OF FMS AND FACTORIES OF THE FUTURE | 9 |
| FMS appli | cation in Machining, Sheet Metal Fabrication, Prismatic Component Produc | tion - |
| Aerospace | Application - FMS Development towards Factories of the Future - Ar | tificial |
| Intelligenc | e and Expert Systems in FMS - Design Philosophy and Characteristics for Futur | re. |
| - | | |
| | TOTAL: 45 PERI | ODS |
| OUTCOME | S: | |
| On success | sful completion of this course, the students will be able to | |
| | familiarized with concepts of Flexible Manufacturing Systems | |
| | ceive Computer Control and Software for Flexible Manufacturing Systems | |
| | acquainted with Flexible Manufacturing System Simulation and Database | |
| | aluate principles of Group Technology and justify Flexible Manufacturing Syste | ms |
| | scribe various flexible manufacturing systems and their applications. | |
| | pare themselves for the Factory of Future. | |
| ÷ rit | | |
| TEXTBOO | /S· | |
| | N.K., "Handbook of flexible manufacturing systems", Academic Press Inc., U | Inited |
| | · · · · | Jinted |
| | tes of America, 2012, ISBN-13: 978-03-231-3935-9. | 000±″ |
| | ouf A. and Daya B.M., "Flexible manufacturing systems: recent developr | nent, |
| EIS | evier Science, Netherlands, 2005, ISBN-13 978-04-448-9798-5. | |

| RFI | FRF | NCES: | |
|-----|-----|-------|--|
| | | NCLJ. | |

- 1. GrooverM.P., "Automation, production systems and computer integrated manufacturing", Prentice Hall of India Pvt., New Delhi, 2016, ISBN-13: 978-93-325-7249-2.
- 2. Kalpakjian S., "Manufacturing Engineering and Technology", Addison-Wesley Publishing Co., United States of America, 2013, ISBN-13: 978-01-331-2874-1.
- 3. Ohno T., "Toyota production system: Beyond large-scale production", Productivity Press (India) Pvt. Ltd., 1992, ISBN-13: 978-09-152-9914-0.
- 4. Radhakrishnan P. and Subramanyan S., "CAD/CAM/CIM", Wiley Eastern Ltd., New Age International Ltd., India, 2009, ISBN-13: 978-81-224-2236-8.
- 5. Lonnie Allan Wilson "How to implement Lean Manufacturing" McGraw Hill; 2nd edition,2015.

| ME1717 | | LOGISTICS AND SUPPLY CHAIN MANAGEMENT | L | Т | Ρ | С |
|-------------|--------|---|------|------|-------|---------|
| | | | 3 | 0 | 0 | 3 |
| OBJECTIVE | S: | | | | | |
| • To | Expla | in about Supply Chain Network Design | | | | |
| • To | llust | rate about the issues related to Logistics in Supply Chain. | | | | |
| | 1 | | | | | |
| UNIT I | INT | RODUCTION | | | | 9 |
| Role of Log | gistic | s and Supply chain Management: Scope and Importance - Evo | lut | ion | of S | Supply |
| Chain – Exa | ampl | es of supply Chains - Decision Phases in Supply Chain - Compet | itiv | e a | nd S | Supply |
| chain Strat | egies | - Drivers of Supply Chain Performance and Obstacles. | | | | |
| | | | | | | |
| UNIT II | SUF | PPLY CHAIN NETWORK DESIGN | | | | 9 |
| Role of Dis | tribu | tion in Supply Chain – Factors influencing Distribution network | de | sigr | ι — [| Design |
| options for | Dist | ribution Network- Distribution Network in Practice - Role of ne | etw | ork | De | sign in |
| Supply Cha | in – I | Framework for network Decisions. | | | | |
| | 1 | | | | | |
| UNIT III | LOC | GISTICS IN SUPPLY CHAIN | | | | 9 |
| Role of tra | nspo | rtation in supply chain – Factors affecting transportations de | ecis | ion | - [| Design |
| option for | tran | sportation network – Tailored transportation – Routing an | d s | sche | dul | ing in |
| transporta | tion - | 3PL- 4PL- Global Logistics - Reverse Logistics; Reasons, Activit | ies | and | iss | ues. |
| | 1 | | | | | |
| UNIT IV | SOL | JRCING AND COORDINATION IN SUPPLY CHAIN | | | | 9 |
| | | ng in supply chain - Supplier selection - Contracts - Design | | | | |
| | | ng and analysis - Supply chain co-ordination - Bull whip effect – | | | | |
| | | supply chain and obstacles – Building strategic partnerships a | nd t | rus | t w | ithin a |
| supply cha | in. | | | | | |
| | | ND EMERGING CONCEPTS IN SUPPLY CHAIN | | | | 9 |
| UNIT V | | | | | | |

The role IT in supply chain-The supply chain IT framework - Customer Relationship Management – Internal supply chain management – supplier relationship management – future of IT in supply chain – E-Business in supply chain- Introduction to Warehouse Management, Risks in Supply Chain, Lean supply Chains, Sustainable supply Chains.

OUTCOMES:

TOTAL: 45 PERIODS

On successful completion of this course, the student will be able to

- Understand the scope of Supply Chain Management and the Drivers of SC performance
- Design suitable SC network for a given situation.
- Solve the issues related to Logistics in SCM.
- Understand Sourcing, Coordination and current issues in SCM.
- Appraise about the applications of IT in SCM and apply SCM concepts in selected enterprise.
- Develop logistics solutions to cater the industry needs.

TEXT BOOK:

- 1. Sunil Chopra, Peter Meindl and D.V. Kalra, "Supply Chain Management: Strategy, Planning, and Operation", Pearson Education, 2016.
- 2. Gianpaolo Ghiani , Gilbert Laporte and Roberto Musmanno , "Introduction to logistics systems management", Wiley 2013.

- 1. David J.Bloomberg, Stephen Lemay and Joe B.Hanna, Logistics, PHI 2010
- 2. G. Srinivasan (2010) Quantitative Models in Operations and Supply Chain Management, PHI, Learning (P) Ltd, New Delhi.
- 3. Jeremy F.Shapiro , Modeling the supply chain, Thomson Duxbury, 2002.
- 4. Sople Vinod V, Logistics Management, Pearson Education, 2010.
- 5. James B.Ayers, "Handbook of Supply chain management", St.Lucle press, 2000.

| ME1718 | | INDUSTRIAL ROBOTICS | L | Т | Ρ | С | | | |
|--|-----|---------------------|---|---|---|---|--|--|--|
| | | | 3 | 0 | 0 | 3 | | | |
| OBJECTIVE | S: | | | | | | | | |
| To understand the functions of the basic components of a Robot, use of various types of Sensors and image processing fundamentals To impart knowledge in Robot Kinematics and Programming, safety issues and economics. | | | | | | | | | |
| UNIT – I | INT | RODUCTION | | | | 9 | | | |
| Robot - Definition - Robot Anatomy - Co ordinate Systems, Work Envelope Types and Classification- Specifications-Pitch, Yaw, Roll, Joint Notations, Speed of Motion, Pay Load- Robot Parts and their Functions-Need for Robots-Different Applications. | | | | | | | | | |
| UNIT – II ROBOT DRIVE SYSTEMS AND END EFFECTORS 9 | | | | | | | | | |

Pneumatic Drives-Hydraulic Drives-Mechanical Drives-Electrical Drives-D.C. Servo Motors, Stepper Motors, A.C. Servo Motors-Salient Features, Applications and Comparison of all these Drives, End Effectors-Grippers-Mechanical Grippers, Pneumatic and Hydraulic- Grippers, Magnetic Grippers, Vacuum Grippers; Selection and Design Considerations.

UNIT-III SENSORS AND MACHINE VISION

9

Principles and Applications of the following types of sensors- Position sensors - Piezo Electric Sensor, Optical Encoders, , Range Sensors Triangulations Principles, Structured, Lighting Approach, Time of Flight, Rangefinders, Laser Range Meters, Touch Sensors , binary Sensors. Analog Sensors, Wrist Sensors, Compliance Sensors, Slip Sensors, Camera, Frame Grabber, Sensing and Digitizing Image Data-Signal Conversion, Image Storage, Lighting Techniques, Image Processing and Analysis-Data Reduction, Segmentation, Feature Extraction, Object Recognition,

UNIT – IV ROBOT KINEMATICS AND ROBOT PROGRAMMING

9

9

PERIODS

TOTAL:

45

Forward Kinematics, Inverse Kinematics and Difference; Forward Kinematics and Reverse Kinematics of manipulators with Two, Three Degrees of Freedom (in 2 Dimension), Four Degrees of freedom (in 3 Dimension) Manipulator Dynamics, Manipulator Mechanism Design-Lead through Programming, Robot programming Languages-VAL Programming-Motion Commands, Sensor Commands, End Effector commands and simple Programs

UNIT – V IMPLEMENTATION AND ROBOT ECONOMICS

Robot work cell- Implementation of Robots in Industries-Various Steps; Safety Considerations for Robot Operations - Economic Analysis of Robots..

OUTCOMES:

On successful completion of this course, the student will be able to

- Explain the concepts of industrial robots, classification, specifications and coordinate systems. Also summarize the need and application of robots in different sectors.
- Illustrate the different types of robot drive systems as well as robot end effectors.
- Apply the different sensors and image processing techniques in robotics to improve its ability.
- Develop robotic programs for different tasks and familiarize with the kinematics motions of robot
- Examine the implementation of robots in various industrial sectors and interpolate the economic analysis of robots.
- Explain the safety considerations in a given robotic application.

TEXTBOOKS:

1. Klafter R.D., Chmielewski T.A and Negin M., "Robotic Engineering - An Integrated Approach", Prentice Hall, 2003.

2. Groover M.P., "Industrial Robotics -Technology Programming and Applications", McGraw Hill, 2001.

REFERENCES:

1. Craig J.J., "Introduction to Robotics Mechanics and Control", Pearson Education, 2008.

2. Deb S.R., "Robotics Technology and Flexible Automation" Tata McGraw Hill Book Co., 1994.
 3. Koren Y., "Robotics for Engineers", McGraw Hill Book Co., 1992.

4. Fu.K.S.,Gonzalz R.C. and Lee C.S.G., "Robotics Control, Sensing, Vision and Intelligence", McGraw Hill Book Co., 1987.

5. Janakiraman P.A., "Robotics and Image Processing", Tata McGraw Hill, 1995.

6. Rajput R.K., "Robotics and Industrial Automation", S.Chand and Company, 2008. 7.

| ME1719 | INDUSTRIAL MANAGEMENT AND SAFETY ENGINEERING | L | Т | Ρ | С |
|-----------|--|---|---|---|---|
| | | 3 | 0 | 0 | 3 |
| OBJECTIVE | 5: | | | | |

• Understand the philosophies of management gurus, learning various Industrial Engineering Practices like Operations Management techniques.

• Identify unsafe conditions and solve problem of accidents for improved safety.

| UNIT I | INTRODUCTION TO MANAGEMENT |
|--------|----------------------------|
| | |

Entrepreneurship and organization – Nature and Importance of Management, Functions of Management, Taylor's Scientific Management Theory, Fayol's Principles of Management, Maslow's Theory of Human Needs, Douglas McGregor's Theory X and Theory Y, Herzberg's Two-Factor Theory of Motivation, Systems Approach to Management, Leadership Styles, Social responsibilities of Management.

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UNIT II DESIGNING ORGANIZATIONAL STRUCTURES

Departmentalization and Decentralization, Types of Organization structures – Line organization, Line and staff organization, functional organization, Committee organization, matrix organization, Virtual Organization, Cellular Organization, team structure, boundary less organization, inverted pyramid structure, lean and flat organization structure and their merits, demerits and suitability.

UNIT III OPERATIONS MANAGEMENT

Objectives- product design process- Process Selection-Types of production system (Job, batch and Mass Production), Plant location-factors- Urban-Rural sites comparison- Types of Plant Layouts- Design of product layout- Line balancing (RPW method) Value Analysis-Definitiontypes of values- Objectives- Phases of value analysis- Fast diagram.

UNIT IV INTRODUCTION TO SAFETY AND HAZARDS

Evolution of modern safety concepts – Fire prevention – Mechanical hazards – Boilers, Pressure vessels, Electrical Exposure. Chemical exposure – Toxic materials – Radiation Ionizing and Non-ionizing Radiation - Industrial Hygiene – Industrial Toxicology.

| UNIT V HAZARD ANALISIS 9 | UNIT V F | HAZARD ANALYSIS | 9 |
|--------------------------|----------|-----------------|---|
|--------------------------|----------|-----------------|---|

System Safety Analysis – Techniques – Fault Tree Analysis (FTA), Failure Modes and Effects Analysis (FMEA), HAZOP analysis and Risk Assessment.

TOTAL: 45 PERIODS

OUTCOMES:

On successful completion of this course, the student will be able to

- Apply principles of management
- Design the organization structure
- Apply techniques for plant location, design plant layout and value analysis
- Identify and prevent chemical, environmental mechanical, fire hazard.
- Able to perform hazard analysis.
- Understand the safety requirements in working environment

TEXTBOOKS:

- 1. O.P. Khanna," Industrial Engineering and Management", Dhanpat Rai Publications, 2018
- 2. John V. Grimaldi, "Safety Management", AITB S Publishers, 2003.

- 1. Paneer Selvam, "Production & Operation Management", PHI,2012
- 2. NVS Raju, "Industrial Engineering Management "Cengage Learning, 2013
- 3. David L. Goetsch, "Occupational Safety and Health for Technologists", Engineers and Managers, Pearson Education Ltd. 5th Edition, 2005.
- 4. Deshmukh L M, "Industrial Safety Management", Tata McGraw-Hill Publishing Company Ltd., 2005
- 5. Safety Manual, "EDEL Engineering Consultancy", 2000

| OME703 | ENERGY CONVERSION TECHNIQUES | QUES L | | | |
|---------------|---|----------|--------|-------|------|
| | | 3 | 0 | 0 | 3 |
| OBJECTIV | ES: | • | | | |
| To analyze th | e working principle, pros and cons of | | | | |
| • Conv | entional energy conversion techniques and direct energy conversi | on s | yste | ms. | |
| Need | and necessity of energy storage systems and their desirable chara | acter | istic | s & 1 | Fuel |
| cells. | | | | | |
| | | | | | |
| UNIT I | CONVENTIONAL ENERGY CONVERSION CYCLES | | | | 8 |
| Reversible an | d irreversible cycles – Thermodynamics analysis of Carnot – Stir | ling | $-E_1$ | ricss | on – |
| Otto – Diese | – Dual – Lenoir – Atkinson – Brayton - Rankine. | | | | |
| | | | | | |
| UNIT II | DIRECT CONVERSION OF THERMAL TO ELECTRICA | L | | | 9 |
| | ENERGY | | | | |
| Thermoelect | ic Converters – Thermionic converters – MHD – Ferro electric co | onve | rter | – Ne | rnst |
| effect genera | ior | | | | |
| | | | | | |
| UNIT III | CHEMICAL & ELECTROMAGNETIC ENERGY TO | | | | 9 |
| | ELECTRICAL ENERGY | | | | |

Batteries – types – working – performance governing parameters – hydrogen energy – solar photovoltaic cells

UNIT IV ENERGY STORAGE SYSTEMS

Energy Storage Technologies - Mechanical energy, Electrical energy, Chemical energy, Thermal energy

9

11

45 **PERIODS**

UNIT V FUEL CELLS

Basics – types – working - comparative analysis – thermodynamics and kinetics of fuel cell process – performance of fuel cell – applications - advantages and drawbacks

TOTAL:

OUTCOMES:

At the end of the course the students would be able to

- Understand the concept of conventional energy conversion cycles.
- Understand the concept of direct conversion of thermal to electrical energy.
- Understand the concept of chemical & electromagnetic energy to electrical energy.
- Understand the concept of energy storage systems.
- Understand the concept of fuel cells.
- Understand the concept of energy conversion techniques.

TEXTBOOKS:

- 3. D. Yogi Goswami, Frank Kreith, "Energy Conversion" Published by CRC Press, 2017
- 4. Ibrahim H. Al-Bahadly, "Energy Conversion Current Technologies and Future Trends", Massey University, New Zealand, 2019.

- 6. Archie.W.Culp, Principles of Energy Conversion, McGraw-Hill Inc., 1991, Singapore
- 7. Kordesch. K, and Simader.G, Fuel Cell and Their Applications, Wiley-Vch, Germany 1996
- 8. Kettari, M.A.Direct Energy Conversion, Addison-Wesley Pub. Co 1997
- 9. Hart A.B and Womack, G.J.Fuel Cells: Theory and Application, Prentice Hall Newyork Ltd., London 1989

| OME704 | ENEF | ENERGY EFFICIENT BUILDINGS DESIGN L T P | | | | | | | | Р | С | |
|--|----------------|---|--------|------|------|-----|-----|--|--|---|---|---|
| | | | | | | | | | | 3 | | |
| OBJECTIVES: | | | | | | | | | | | | |
| • To be familiar with basic terminologies related to buildings and air conditioning | | | | | | | | | | | | |
| techni | lues. | | | | | | | | | | | |
| • To know the methods to evaluate the performance of buildings and Renewable energy | | | | | | | | | | | | |
| system | s in building | 8. | | | | | | | | | | |
| | | | | | | | | | | | | |
| UNIT I | INTRODU | CTION | | | | | | | | | | 9 |
| Climate and Building, Historical perspective, Aspects of green building design – Sustainable | | | | | | | | | | | | |
| Site, Water, Energy, Materials and IAQ, ECBC Standards | | | | | | | | | | | | |
| | | | | | | | | | | | | |
| UNIT II | LAND SCA | PE AND B | UILDI | NG E | ENVE | LOI | PES | | | | | 9 |
| UNIT II | LAND SCA | PE AND B | BUILDI | NG E | ENVE | LOI | PES | | | | | 9 |

Energy efficient Landscape design - Microclimate, Shading, Arbors, Windbreaks, Xeriscaping, Building envelope - Thermal comfort, Psychrometry, Comfort indices, Thermal Properties of Building Materials - Thermal Resistance, Thermal Time Constant (TTC), Diurnal Heat Capacity(DHC), Thermal Lag, Decrement Factor, Effect of Solar Radiation -Sol-air Temperature, Processes of heat exchange of building with environment, Insulation.

PASSIVE HEATING AND COOLING UNIT III

HVAC introduction, Passive Heating - Solar radiation basics, Sun Path Diagram, Direct Heating, Indirect Heating and Isolated heating, Concept of Day lighting, Passive Cooling-Natural Ventilation(Stack and Wind), Evaporative Cooling and Radiative Cooling.

UNIT IV THERMAL PERFORMANCE OF BUILDINGS

Heat transfer due to fenestration / infiltration, Calculation of Overall Thermal Transmittance, Estimation of building loads: Steady state method, network method, numerical method, correlations, Thermal Storage integration in buildings

UNIT V **RENEWABLE ENERGY IN BUILDINGS**

Introduction of renewable sources in buildings, BIPV, Solar water heating, small wind turbines, stand- alone PV systems, Hybrid system–Economics.

OUTCOMES:

At the end of the course the students would be able to

- Design climate responsive building.
- Discover various physical properties influencing passive building design. •
- Apply the passive (air) conditioning techniques in energy efficient building.
- Interpret the energy performance of buildings. •
- Appraise the adaptation of renewable energy systems in buildings.
- Design Energy efficient buildings.

TEXTBOOKS:

- 5. Paul Tymkow, Savvas Tassou, Maria Kolokotroni, Hussam Jouhara, "Building Services Design for Energy Efficient Buildings" Published by Routledge, 2020
- 6. Umberto Desideri, Francesco Asdrubali, "Handbook of Energy Efficiency in Buildings", A Life Cycle Approach, 1st Edition - November 12, 2018.

REFERENCES:

- 10. ASHRAEHandbook-2009-Fundamentals.
- 11. Baruch Givoni: Climate considerations in building and Urban Design, John Wiley & Sons, 1998
- 12. Baruch Givoni: Passive Low Energy Cooling of Buildings by, John Wiley & Sons, 15-Jul-1994
- 13. JA Duffie and WA Beckman: Solar Engineering of Thermal Processes, Third Edition, John Wiley& Sons, 2006.
- 14. Jan F. Kreider, Peter S.Curtiss, Ari Rabl, Heating and cooling of buildings: Design for Efficiency, Revised Second Edition, CRC Press, 28-Dec-2009.

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PERIODS

TOTAL: